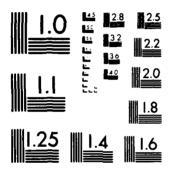
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## A Numerical Model to Simulate Sediment Transport in the Vicinity of Coastal Structures

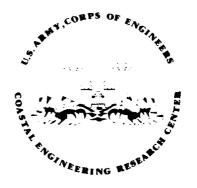
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by

Marc Perlin and Robert G. Dean

MISCELLANEOUS REPORT NO. 83-10

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RESEARCH CENTER

Kingman Building Fort Belvoir, Va. 22060

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#### **PREFACE**

The purpose of this report is to provide coastal engineers and researchers with a numerical model which predicts sediment transport and the resulting bathymetry in the vicinity of coastal structures. The work was carried out under the U.S. Army Coastal Engineering Research Center's (CERC) Numerical Modeling of Shoreline Response to Coastal Structures work unit, Shore Protection and Restoration Program, Coastal Engineering Area of Civil Works Research and Development.

This report was written by Marc Perlin and Robert G. Dean, Coastal and Offshore Engineering and Research, Inc., under Contract No. DACW72-80-C-0030. The CERC contract monitor was Dr. F. Camfield, Chief, Coastal Design Branch, under the general supervision of Mr. N. Parker, Chief, Engineering Development Division.

Technical Director of CERC was Dr. Robert W. Whalin, P.E.

Comments on this publication are invited.

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Colonel, Corps of Engineers Commander and Director

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CONVERSION FACTORS, U.S. CUSTOMARY TO METRIC (SI) UNITS OF MEASUREMENT U.S. customary units of measurement used in this report can be converted to metric (SI) units as follows:

Multiply	by	To obtain				
inches	25.4	millimeters				
	2.54	centimeters				
square inches	6.452	square centimeters				
cubic inches	16.39	cubic centimeters				
feet	30.48	centimeters				
	0.3048	meters				
square feet	0.0929	square meters				
cubic feet	0.0283	cubic meters				
yards	0.9144	meters				
square yards	0.836	square meters				
cubic yards	0.7646	cubic meters				
miles	1.6093	kilometers				
square miles	259.0	hectares				
knots	1.852	kilometers per hour				
acres	0.4047	hectares				
foot-pounds	1.3558	newton meters				
millibars	$1.0197 \times 10^{-3}$	kilograms per square centimeter				
ounces	28.35	grams				
pounds	453.6	grams				
•	0.4536	kilograms				
ton, long	1.0160	metric tons				
ton, short	0.9072	metric tons				
degrees (angle)	0.01745	radians				
Fahrenheit degrees	5/9	Celsius degrees or Kelvins <sup>1</sup>				

<sup>&</sup>lt;sup>1</sup>To obtain Celsius (C) temperature readings from Fahrenheit (F) readings, use formula: C = (5/9) (F -32).

To obtain Kelvin (K) readings, use formula: K = (5/9) (F -32) + 273.15.

# A NUMERICAL MODEL TO SIMULATE SEDIMENT TRANSPORT IN THE VICINITY OF COASTAL STRUCTURES by Marc Perlin and Robert G. Dean

#### I. INTRODUCTION

#### 1. General.

The need for reliable predictions of shoreline response to man-made or natural modifications is increasing due to environmental concerns and the rising cost of remedial measures. The capability of numerical modeling in addressing problems of shoreline response has advanced with improvements in wave climatology, programs to better understand sediment transport relationships, and improvements in numerical modeling. In-situ and remote sensing technology for the measurement of directional wave characteristics has been developed and applied, primarily within the last two decades. In addition to providing the necessary climatology, the resulting measurements have provided the basis for evaluation and refinement of directional wave prediction procedures. Studies such as the Channel Islands Harbor Longshore Sand Transport Study (Bruno, et al., 1981) and the Nearshore Sediment Transport Study (NSTS) (Gable, 1979) have yielded a better understanding of surf zone dynamics and the resulting sediment transport. The increased capacities of large computers and reduced computing costs combined with improved numerical modeling algorithms have resulted in an extremely promising potential for the numerical modeling of shoreline problems.

Although it is doubtful that numerical modeling will ever replace completely the use of movable-bed physical models, the former type offers many advantages. The modeling of shoreline response is somewhat analogous to the problem of simulating storm surges in the coastal zone in which the scale effects and measurement difficulties essentially preclude physical modeling. For shorelines, the scale effects inherent in modeling sediment are well recognized and the costs of representing a substantial length of shoreline may be prohibitive. The laboratory representation of a realistic wave climate is at the forefront of technology.

The investigation of shoreline response can best proceed by several approaches, with each approach selected for the particular strengths which it offers. Field programs are costly, usually because of the considerable equipment and the extensive time required, but these programs are essential for quantifying the values of constants or parameters, the forms of which may be available from laboratory measurements or theoretical considerations. Laboratory studies occupy a special niche by allowing the wave conditions and independent variables to be controlled readily, experiments to be repeated, and selected measurements to be conducted. Although, as noted before, scale effects are present in laboratory measurements of sediment transport, the physics governing the process should be the same. However, the relative magnitudes of suspended versus bedload transport in the laboratory and field may differ. Laboratory studies can also provide an excellent base for evaluating certain aspects of a numerical model, including wave refraction and diffraction and the resulting shoreline patterns due to, for example, the placement of a littoral barrier. Numerical modeling offers the capability to

incorporate all the hydrodynamic wave-surf zone and sediment transport knowledge that is available from laboratory and field studies. Numerical modeling has the potential of providing accurate predictions of shoreline response to various structural and nourishment alternatives. Additionally, the possibility exists of employing numerical models and available field measurements to learn more about sediment transport mechanisms. In this latter mode, various candidate mechanisms or coefficients would be evaluated by determining the best match between measured and predicted shorelines and the bathymetry. Generally, this mode would require high-quality measurements of the forcing function (waves and nonwave-related currents) and the associated response (sediments) as well as the knowledge of appropriate conditions at the boundaries of the model.

The present report documents the development and application of an n-line numerical model to investigate bathymetric response to time-varying wave conditions and shoreline modification. The model includes both longshore and onshore-offshore sediment transport. Based on laboratory results, a new distribution of longshore sediment transport across the surf zone is used. The wave climate is specified on the model boundaries which do not need to extend to deep water. Efficient algorithms are employed for representing wave refraction and diffraction. The equation of sediment continuity and transport are solved by a completely implicit algorithm which allows a large time-step. Specified sediment transport values or specified contour positions can be accommodated at the model boundaries. The model is suitable for investigating the shoreline response to a variety of modifications such as one or more groins, terminal structures, structures with variable permeability, and beach nourishment with or without terminal structures.

#### 2. Study Objectives.

The objectives of the present study include (a) the documentation of state-of-the-art models, (b) the development and documentation of an improved model which includes the capability to represent n-contour lines and (c) the application of the model to several relevant coastal engineering problems.

#### II. BACKGROUND

This discussion describes significant contributions which either address numerical modeling of shorelines directly or provide improved capability for modeling.

#### 1. Wave Refraction (Noda, 1972).

Noda developed an algorithm for solving the following steady state equation for wave refraction

$$\vec{\nabla} \times \vec{k} = 0 \tag{1}$$

in which  $\vec{\forall}$ , the horizontal vector differential operator, and  $\vec{k}$ , the wave number, are defined in terms of their components as

$$\vec{\nabla} = \vec{\mathbf{1}} \frac{\partial}{\partial \mathbf{x}} + \vec{\mathbf{j}} \frac{\partial}{\partial \mathbf{y}} \tag{2}$$

$$\vec{k} = \vec{i} k_X + \vec{j} k_y \tag{3}$$

where  $\vec{i}$  and  $\vec{j}$  are the unit vectors in the x and y directions respectively. Equation (1) can be expressed as

$$\frac{a(ksine)}{ax} = \frac{a(kcose)}{ay} \tag{4}$$

in which  $\theta$  is the direction of the vector wave number relative to the x-axis and k denotes  $|\vec{k}|$  . Noda expanded Equation (4) to the following form

k cose 
$$\frac{\partial \Theta}{\partial x}$$
 + sine  $\frac{\partial k}{\partial x}$  = -k sine  $\frac{\partial \Theta}{\partial y}$  + cose  $\frac{\partial k}{\partial y}$  (5)

Since  $\frac{\partial k}{\partial x}$  and  $\frac{\partial k}{\partial y}$  are known from the angular frequency  $\sigma$ , the water depth h, and the dispersion equation

$$\sigma^2 = g k \tanh kh$$
 (6)

Equation (5) can be solved numerically, although there are problems of directional stability. The primary advantage of Equation (5) is that it allows the wave direction e to be determined on a specified grid, compared to unspecified locations that would be obtained by, for example, wave ray tracing.

#### 2. Crenulate Bays (LeBlond, 1972).

LeBlond attempted to model the evaluation of an initially straight shoreline between two headlands into a crenulate bay. The model constitutes a one-line (shoreline) representation. The transport equation employed related the total sediment transport to total water transport in the surf zone as predicted by the formulation provided by Longuet-Higgins (1970). The initial shoreline patterns resemble crenulate bays in nature; however, the predictions were found to be unstable for reasonably long periods of computational time and did not approach a realistic planform.

#### 3. Crenulate Bays (Rea and Komar, 1975).

Rea and Komar employed a rather ingenious system of orthogonal grid cells to provide a cell which locally is displaced perpendicular to the general shoreline orientation. A one-line representation was employed. A simple and approximate representation of wave diffraction was employed. Although the model yielded reasonable results for the examples presented, the unique coordinate system would not be suitable for a general model as the coordinate system must be "tailored" to some degree to conform to the expected shoreline configurations.

#### 4. General One-line Shoreline Model (Price, Tomlinson, and Willis, 19/2).

Price, Tomlinson, and Willis' formulation consists of the sediment continuity equation and the total sediment transport equation

$$Q_{s} = \frac{0.70 E_{b} (nC)_{b} sin\alpha_{b} cos\alpha_{b}}{\gamma_{\omega} (1 - p) (S_{s} - 1)}$$
(7)

in which E represents the wave energy density, (nC) the group velocity,  $\alpha$  the angle between the breaking wave front and the shoreline,  $\gamma_\omega$  the specific weight of water, p the in-place sediment porosity, and  $S_S$  the specific gravity of the sediment relative to the water in which it is immersed. The subscript "b" represents values at breaking.

Two formulations were presented by Price, Tomlimson, and Willis (1972). In the first, Equation (7) was substituted into the continuity equation and the results cast into a finite-difference form. In the second, the two equations were employed separately. The latter formulation was selected due to its simplicity and used for the results presented.

Computations were carried out for the case of beach response due to the placement of a long impermeable barrier. The total sediment transport equation by Komar (1969) was used and the planform was calculated at successive times. Refraction was apparently not accounted for in the numerical model. To verify the computations, a physical model study was carried out for the same conditions using crushed coal as the modeling material. The comparison was interpreted as good for up to 3 hours; however, for greater times, substantial differences occurred and these were interpreted as being due to wave refraction not being represented. The crushed coal was supplied to the model at the updrift end at a rate based on the Komar equation, and the results were interpreted as substantiating this relationship. However, the updrift end of the model beach receded substantially both in the numerical and physical models. In the physical model, this can only be interpreted as due to the Komar equation predicitions being less than the actual transport rate, possibly due to the low specific gravity (1.35) of the crushed coal. The predicted recession of the updrift beach is puzzling, although it could be due to a problem in properly representing the updrift boundary condition.

Other one-line models for shoreline changes in the vicinity of coastal structures were developed by LeMehaute and Soldate (1977) and Perlin (1978). Perlin also developed a two-line model formulation, with one-line representing the shoreline and the second the offshore. Dragos (1981) developed an n-line nodel for bathymetric changes due to the presence of a littoral barrier.

#### III. THE NUMERICAL MODEL

#### 1. Description.

There are several methods of modeling bathymetric changes due to the presence of a littoral barrier. An attempt can be made to either model the complete hydrodynamics and the resulting sediment transport or model using a combination of analytical and empirical sediment transport equations. The second method was chosen due to past relative success.

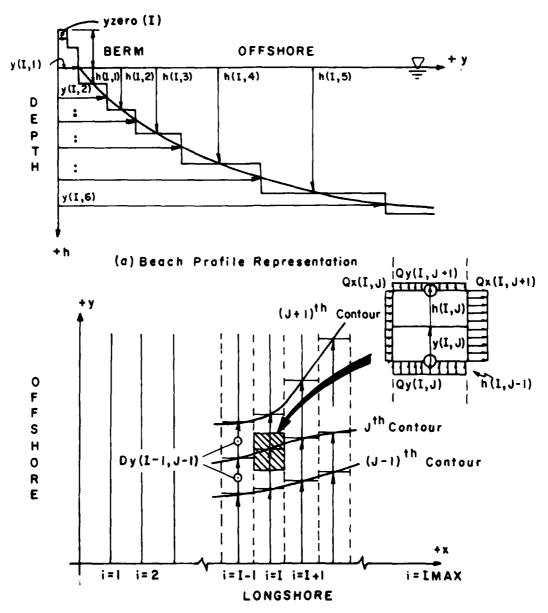
At least two methods of employing sediment transport equations exist: a fixed longshore and cross-shore grid system where the depth is allowed to vary or a fixed longshore and depth system where the cross-shore distance is allowed to change. Although it may seem somewhat awkward, the latter system was chosen for the model. This method allows the modeler to think of bathymetric changes due to a littoral barrier in terms of the effect on the contours; i.e., the contour realinement due to the structure's presence is observed. One limitation of this approach, at least as it was applied here, is that each depth contour must be single-valued; it is not possible to represent bars.

The next step in formulating the model was choosing the specific representation of the bathymetry. The model is an n-line representation of the surf zone in which the longshore direction x is divided into equal segments each  $\Delta x$  in length. The bathymetry is represented by n-contour lines, each a specified depth, which change in offshore location according to the equation of continuity. There are two components of sediment transport at each of the contour lines, a longshore component,  $Q_{\rm X}$ , and an offshore component,  $Q_{\rm Y}$ . Figure 1 is a definition sketch showing the beach profile representation in a series of steps and the planform profile representation and notations used.

Implementation of the sediment transport equations requires knowledge of the wave field and the equilibrium offshore profile. A discussion of the refraction and diffraction schemes follows. The equilibrium profile is introduced when it is convenient. As an introduction to the logic used in the numerical model, a flow chart is presented in Figure 2.

#### 2. Refraction.

A refraction scheme compatible with variable  $\Delta y$ 's was required because of the variable distance to fixed depth contours (as opposed to the more usual fixed grid system where a grid center has a longshore and offshore coordinate with a variable depth). One of the benefits of the n-line model is the ease with which the response of the contours to a particular wave and structure condition can be visualized. A fixed grid system and an interpolation scheme could have been used to obtain the wave field; however, this would have reduced accuracy and increased computation time. The scheme developed also saves computation time because it does not use differential products terms.



(b) Beach Planform Representation

Figure 1. Definition sketch.

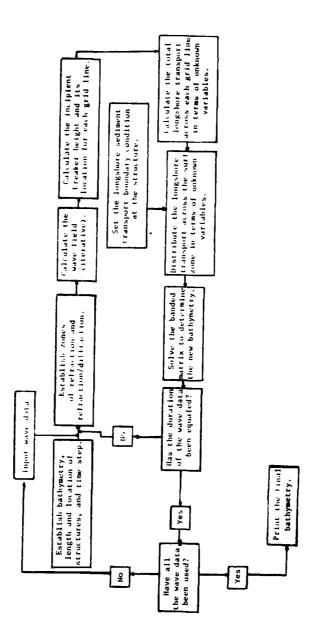


Figure 2. Flow chart.

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$$\frac{d\sigma}{dt} + \hat{\tau}_{H} \times \vec{k} = 0 \tag{8}$$

where  $\nabla_H$  is the horizontal differential operator equal to  $i(\partial/\partial x) + j(\partial/\partial y)$  in which i and j are the unit vectors in the x and y directions, respectively, and x is the longshore direction, with positive to the right when facing the water, y the offshore direction, with positive seaward, and z the vertical coordinate, with positive defined as upwards. For the steady-state case, equation (8) yields

$$\frac{\partial}{\partial x} (k_y) - \frac{\partial}{\partial y} (k_x) = 0$$
 (9)

where  $k_X$  and  $k_y$  are the wave number projections in the respective directions. Defining  $\$ as the angle k makes with the y-axis positive in the counter-clockwise direction, the equation can be written in final form as

$$\frac{\partial}{\partial x} (k \cos \theta) = \frac{\partial}{\partial y} (k \sin \theta)$$
 (10)

where  $\theta=\alpha+\pi$  (in radians). Noda (1972) and others have developed numerical solutions to expanded forms of equation (10). In the present study, equation (10) was initially central-differenced in the x-direction and forward-differenced in the y-direction with Snell's law used to specify the boundary conditions on the offshore boundary and one of the sides (i.e., the side of the wave angle approach). However, a numerical problem arose. The argument of the arcsine exceeded  $\pm$  1.0 for large  $\Delta y/\Delta x$ . To overcome this problem, a dissipative interface was used on the forward-difference term (after Abbott, 1979). The final finite-differenced form of equation (10) is

$$e_{i,j}^{n+1} = \sin^{-1} \left\{ \frac{1}{k_{i,j}} \left[ \tau(k \sin e)_{i-1,j+1} + (1-2\tau)(k \sin e)_{i,j+1} \right] \right\}$$
 (11)

+ 
$$\tau(k \sin \theta)_{i+1,j+1} - \frac{\Delta y}{2\Delta x} \left( (k \cos \theta)_{i-1,j} - (k \cos \theta)_{i-1,j} \right)$$

where  $\tau$  has been taken as 0.25. The past  $\odot_{i,j}^n$  and the present  $\odot_{i,j}^n$  wave angles are numerically averaged to give the  $\odot_{i,j}$ . Newton's method is used to compute the wave number via the linear wave theory dispersion relation. In addition, numerical smoothing is used at the conclusion of the wave field calculation. This approximates in an ad hoc manner diffractive effects (lateral transfer of wave energy along the wave) which exist in nature but have been omitted due to use of the equation for refraction (equation 8). The smoothing routine is

$$e_{i,j} = \frac{1}{4} e_{i-1,j} + \frac{1}{2} e_{i,j} + \frac{1}{4} e_{i+1,j}$$
 (12)

The second governing equation used in the refraction scheme is conservation of energy. Neglecting dissipation of energy due to friction, percolation, and turbulence, this equation can be expressed as

$$\vec{\nabla} \cdot (\mathbf{E} \ \vec{\mathbf{C}}_{\mathbf{G}}) = \mathbf{0} \tag{13}$$

where E is the average energy per unit surface area and  $\overrightarrow{C}_G$  the group velocity of the wave train. Performing the operation indicated and replacing  $\overrightarrow{C}_G$  by its components ( $C_G$ sin  $\Theta$ ) and ( $C_G$ cos  $\Theta$ ) results in the following:

$$\frac{\partial}{\partial x}$$
 (E C<sub>G</sub> sin e) +  $\frac{\partial}{\partial y}$  (E C cos e) = 0 (14)

Assuming linear theory,

$$E = \frac{\rho gH^2}{8} \tag{15a}$$

where  $\rho$  is the mass density of water, g the gravitational constant, and H the wave height. Dividing the equation by  $\frac{\rho}{g}$ , finite-differencing and weighting the forward-differenced term as before, and solving for the wave height, results in the following:

$$H_{i,j}^{n+1} = \left\{ \frac{1}{(C_{G}cose)_{i,j}} \left[ (\tau)(H^{2}C_{G}cose)_{i-1,j+1} + (1-2\tau)(H^{2}C_{G}cose)_{i,j+1} + (\tau)(H^{2}C_{G}cose)_{i+1,j+1} + \frac{\Delta y}{2\Delta x} \left[ (H^{2}C_{G}sine)_{i+1,j} - (H^{2}C_{G}sine)_{i-1,j} \right] \right\}^{(15b)}$$

This equation is also solved by iterative techniques and the  $H_{i,j}^{n+1}$  and  $H_{i,j}^{n}$  are averaged at the conclusion of each iteration.

 $\mathbf{C}_{\mathbf{G}}$  is determined by the linear wave theory relationship

$$C_{G} = \frac{C}{2} \left( 1 + \frac{2kh}{\sinh 2kh} \right) \tag{16}$$

where h is the water depth, k the wave number, and C the wave celerity. Wave height boundary conditions are input along the same boundaries as the wave angles using linear theory shoaling and refraction coefficients. The  $\theta$ 's have been previously determined. In both equations (11) and (15) for a variable grid system, the points (i+1,j) and (i-1,j) need to be determined (i.e., because the y coordinates are not fixed, adjacent values with the same subscripts can be farther or closer to shore, therefore interpolation must be used). The actual values are found by searching the (i+1) and (i-1) cross-shore lines, finding the adjacent values in the positive and negative y-direction, and interpolating to determine the value.

#### 3. Diffraction.

The diffraction solution (in the lee of the structure) used in the model is based on the method of Penny and Price (1952). Assumptions used in this method include a semi-infinite breakwater, which is infinitesimally thin, linear wave theory and constant depth. A definition sketch for wave diffraction is shown in Figure 3. The quantity THETAO represents the angle of wave incidence relative to the jetty axis, ANGLE represents the angle from the jetty at the point where the diffraction coefficient is to be computed, and RAD is the radial distance. The radial distance is then cast into a dimensionless parameter, RHOND (=  $2\pi$  RAD/L), where L is the wavelength. This is equivalent to multiplying the radial distance by the wave number k.

The diffraction coefficient AMP is expressed as the modulus of the diffracted wave  $\frac{1}{2}$ 

$$AMP = (Sum 1)^2 + (Sum 2)^2$$
 (17)

where

Sum 1 = [cos (RHOND (cos (ANGLE-THETAO))) . 
$$(\frac{1}{2} (1.0 + C_F + S))] +$$
[sin (RHOND (cos (ANGLE-THETAO))) .  $(-\frac{1}{2} (S - C_F))] +$ 
[cos (RHOND (cos (ANGLE+THETAO))) .  $(\frac{1}{2} (1.0 + C_F + S))] +$ 
[sin (RHOND (cos (ANGLE+THETAO))) .  $(\frac{1}{2} - (S - C_F))]$  (18)

Sum 2 = [cos (RHOND (cos (ANGLE-THETAO))) . 
$$(-\frac{1}{2}(S - C_F))] +$$
[sin (RHOND (cos (ANGLE-THETAO))) .  $(\frac{1}{2}(1.0 + C_F + S))] +$ 
[cos (RHOND (cos (ANGLE+THETAO))) .  $(-\frac{1}{2}(S - C_F))] +$ 
[sin (RHOND (cos (ANGLE+THETAO))) .  $(\frac{1}{2}(1.0 + C_F + S))]$  (19)

In Equations (18) and (19),  $C_F$  and S represent Fresnel integrals and are computed in the model by means of an approximation after Abramowitz and Stegun (1965).

Having obtained AMP, the wave height at the location in question is simply the product of the specified partially refracted incident wave height and AMP. The angle of the wave crest is computed assuming a circular wave front along any radial; this angle is then refracted using Snell's law.

Throughout the refraction and diffraction schemes, the local wave heights are limited by the value,  $0.78 \times \text{depth}$ .

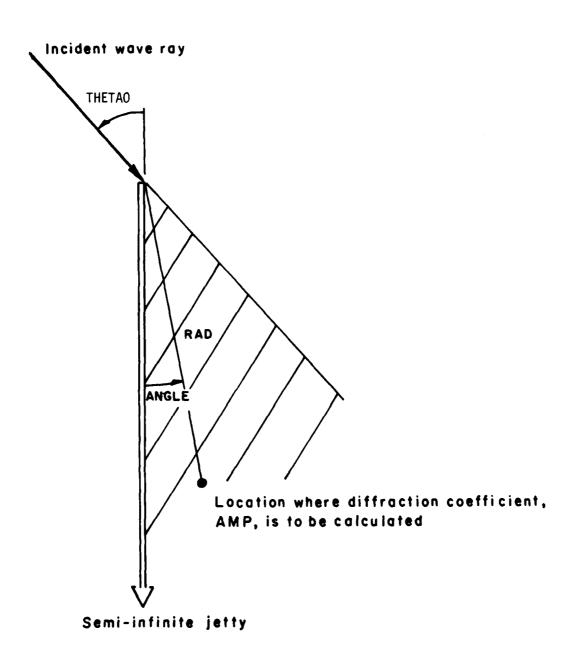


Figure 3. Definition sketch for wave diffraction.

#### 4. Sand Transport Model.

a. Governing Equations. Three basic equations are used to simulate the sediment transport and bathymetry changes according to the wave field. The equation of continuity

$$\frac{\partial y}{\partial t} + \frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} = 0 \tag{20}$$

requires as input, knowledge of the longshore and cross-shore components of sediment transport. The total transport alongshore has been measured by several investigators and many equations exist; however, the distribution of the transport across the surf zone is not well known. Fulford (1982) based on laboratory data from Savage (1959), developed a distribution of longshore sediment transport across the surf zone for the case of straight and parallel contours. Fulford's use of Savages experiment was based on two assumptions: 1) the structure must be a total littoral barrier and 2) onshore-offshore sediment transport could be neglected. Test 5-57 was chosen because the two criteria were nearly met. Savage reported that the groin acted as a total littoral barrier for the first 35 hours of the test (i.e., no bypassing occurred prior to 35 hours). This does not mean that no onshore-offshore transport occurred because as the profile steepens on the updrift side, onshore-offshore transport does occur. However, it was assumed to be negligible. In addition, the initial profile had been molded to an equilibrium profile via 150 hours of waves. Thus, the two criteria required to develop an inferred longshore distribution of sediment transport were nearly satisfied. This distribution is shown as a dashline in Figure 4. The smaller "maximum" is believed to be an extraneous effect of a groin downdrift from the location in the experiment where the data were taken. Therefore, this feature was replaced by a monotonically decreasing, smooth curve as shown by the "altered" curve. To analytically represent this distribution, a function of the following form was chosen

$$q_{x}(y) = (B)(y)^{n-1} e^{-(y)^{n}}$$
 (21)

This type of equation is convenient because it is easily integrable, and by properly choosing the constant, B, the integral of the equation from zero to infinity can be required to equal a particular value. This too is highly desirable because, as was done in the model, the integral is set equal to one and then multiplying by the value of the well-known longshore transport equation, the value of the transport at any location across the surf zone can be determined. Further investigation suggested a value of n=3 to produce a curve similar to Fulford's curve. A more general form of the equation which allows more flexibility and curve fitting is

$$q_{x}(y) = B(y + a)^{2} e^{\left\{-\left[\frac{y + a}{cy_{b}}\right]\right\}^{3}}$$
 (22)

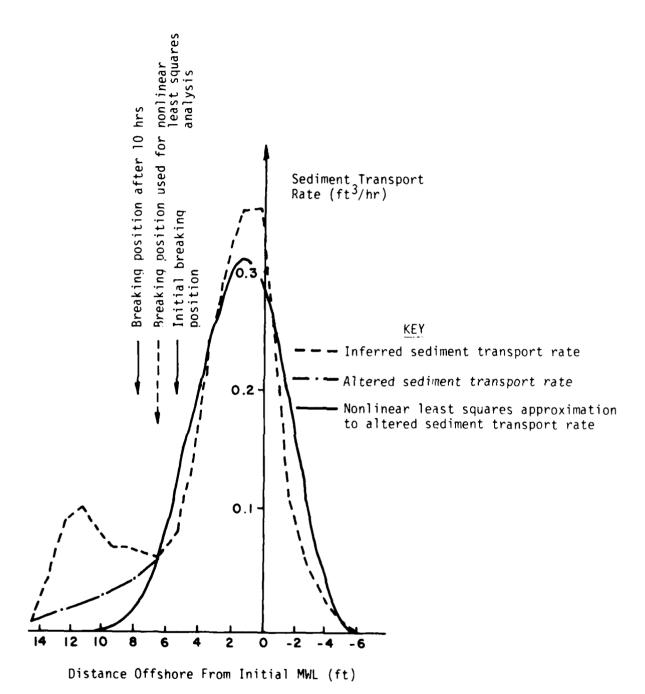


Figure 4. Distribution of sediment transport across the surf zone.

where  $y_b$  = distance to the point of breaking

- a = constant to allow sediment transport above mean water line (MWL)
   (swash transport or transport in region of wave setup) to be
   represented
- c = a constant establishing the width of the curve (to be determined)

$$B = \frac{3}{c^3 y_b^3}$$
 (causes  $\int_0^\infty q_x^2 (y) dy = 1.0$ )

Based on Fulford's (1982) results and considering a to be proportional to the breaking height divided by the beach slope, the constant of proportionality was determined to be unity; i.e.,  $a = h_b/(ah/ay)$ . Using equation (22) and a digitized version of the curve shown in Figure 4, a nonlinear least squares regression was carried out to determine the value of c. A Taylor's series expansion of the form

$$f^{k+1}(c,y) = f^{k}(c,y) + \frac{\partial f}{\partial c} \Delta c \qquad (23)$$

where k and k+1 represent the number of the iteration carried out. Least squares regression minimizes the square of the difference between observed and predicted values with respect to a change in the parameter being computed, or

$$\frac{\partial}{\partial(\Delta c)} \left\{ \sum_{n=1}^{N} \left[ f_{OBS} - \left( f^{k}(c, y) + \frac{\partial f}{\partial c} \Delta c \right) \right]^{2} \right\} = 0$$
 (24)

where fogs represents the observed values, which in this case is  $q_\chi(y)_{OBS}$ . Carrying out the differentiation indicated and manipulating terms,  $\Delta c$  can be solved in terms of known quantities.

An iterative procedure was then used by updating the values of  $f^k(c,y)$ ,  $\partial f/\partial c$ , and c until an acceptably small change in c results. For the data herein, the value of c was determined to be 1.25. The final form of sediment transport of a y location in the surf zone results for a shoreline with straight and parallel contours, as

$$q_{\chi}(y) = \frac{3}{(1.25)^3 (y_b)^3} (y + a)^2 e^{-[(y + a)/(1.25 y_b)]^3}$$
 (25)

This equation, which is also presented in Figure 4, predicts the relative transport at point y. To obtain the fraction of transport between two y coordinates, the integral of equation (25), from  $y_1$  to  $y_2$ , must be used.

$$Q_{XND} = Q_{X} \Big|_{y_{1}}^{y_{2}} = \int_{y_{1}}^{y_{2}} q_{X}(y)dy = e^{-[(y_{1} + a)/(1.25 y_{b})]^{3}} -e^{-[(y_{2} + a)/(1.25 y_{b})]^{3}}$$
(26)

 $Q_{\mathbf{x}}[\mathbf{ND}]$  is dimensionless; therefore, to compute a value in, say, cubic feet per second, it must be multipled by the total transport along a perpendicular to the shoreline obtained from the total longshore transport equation used in the model

$$Q = C' H_b^{5/2} \sin(2 \alpha_b)$$
 (27)

See Appendix A for a discussion of the constant C'. It is noted that the transformation of  $q_X(y)$  to  $q_X(h)$  can be effected by multiplying by the one-dimensional Jacobian  $(\Delta y/\Delta h)$ . This latter form  $(q_X(h))$  is more useful here because the present model simulates the changes in contour position  $(\Delta y)$  rather than changes by depth  $(\Delta h)$ .

In the numerical model,  $Q_X$  (I,J) (see Fig. 1) is determined using equation (26) except for the shoreline contour, J=1, and the farthest offshore contour simulated, J = JMAX. The shoreline contour longshore transport,  $Q_x$  (I,1), in order to include swash transport, uses equation (16); however, the first term is set equal to 1.0. The seawardmost contour transport,  $Q_X$  (I,JMAX), in order to include any longshore transport not yet accounted for, neglects the second term of equation (26) (i.e., it accounts for transport from y(I,JMAX) to infinity). The dimensionless numbers are then multiplied by Q determined from equation (27). This method is based on parallel contours which may not exist. In order to compensate for the nonparallel nature of the contours (note that refraction does account for it as far as the wave field is concerned), the term  $\sin (2\alpha_b)$  of equation (27) is replaced by sin  $(2\alpha_l)$  shoreward of the breakpoint, where  $\alpha_l$  represents the angle between the "local" wave angle and the "local" contour. It can be argued that for a spilling breaker, the remaining surf zone at any point "sees" a total transport similar to equation (27), where  $\alpha_{b}$  and  $H_{b}$  are the local values. The problem is that the constant of proportionality was determined for the entire surf zone and for nearly straight and parallel contours. This not being the case, the equation was altered on intuitive grounds to reflect the fact that the contours are no longer straight and parallel.

The second input required by the continuity equation to predict the bathymetric changes is the cross-shore sediment transport. The governing equation for onshore-offshore transport (after Bakker, 1968) is

$$Q_{y_{i,j}} = \Delta x C_{OFF_{i,j}} \left[ y_{i,j-1} - y_{i,j} + W_{EQ_{i,j}} \right]$$
 (28)

where  $C_{OFF}$  is an activity factor (inside the surf zone =  $10^{-5}$  feet per second for the prototype simulation herein,  $10^{-4}$  feet per second for the physical model simulation) (see App. A. for a discussion) and  $W_{EQ}(i,j)$  is the positive equilibrium profile distance between y(i,j) and y(i,j-1), determined from the equilibrium profile used in the numerical model  $h = Ay^{2/3}$  (Dean, 1977). See Appendix A for discussion of the value of A. The physical interpretation of equation (28) is that as this profile steepens (flattens), sediment is transported offshore (onshore).

- b. <u>Methods of Solution</u>. Three separate finite-difference techniques were used to solve the equations:
  - (1) Explicit longshore-continuity and explicit cross-shore continuity;
  - (2) Implicit longshore-continuity and explicit cross-shore continuity for half a time-step then vice versa; and
  - (3) Implicit longshore-cross-shore continuity.

An explicit formulation was first developed which used the refraction scheme, the distribution of longshore sediment transport across the surf zone, and the onshore-offshore sediment transport equation. Problems in addition to the usual ones which are encountered with explicit methods (e.g., computation time and cost) were immediately realized. In the explicit method, both transport computations are based on the former values of the contour locations and are completely uncoupled. Stability of an explicit scheme requires a small time-step. In addition, the noncoupled nature of the equations, in some cases, resulted in crossing of the contours due to the transport computed.

It is logical to assume that an implicit formulation of the longshore transport equation used as input to the continuity equation along with the explicit onshore-offshore transport component would help the numerical stability (on the other half time-step, the longshore component would be computed explicitly and the onshore-offshore transport equation would be solved implicitly with the continuity equation). Although this scheme would be superior to the explicit procedure, it still would be susceptible to crossing contours. It should be noted that the magnitude of the coefficient used in the onshore-offshore equation is very important to the extent that the simulation models natural phenomena. If the coefficient is very small or vanishes, sediment will not move offshore and contours will cross because of the variation in the distribution of longshore sediment transport across the surf zone. If the coefficient is too large, the onshore-offshore transport, may become large enough that on a particular time step, an offshore contour

would move too far shoreward, thereby crossing an inshore contour or vice versa. Once the contours cross, not only does the bathymetry become unrealistic, but mathematically, the equation which computes the longshore distribution across the surf zone changes signs at some locations and the entire model becomes physically unrealistic.

To circumvent these problems, an implicit scheme that simultaneously solves the three governing equations, was developed. Utilizing equation (26), and the one-dimensional Jacobian  $(\Delta y/\Delta h)$  to convert to  $Q_X(h)$ , the total longshore transport equation (27), the following equation is obtained,

$$Q_{x_{i,j}} = \left\{ \left[ exp \left( -\left( \frac{(h_{i,j-1})^{3/2} + H_{b_{i}}A^{3/2}}{1.25 h_{b_{i}}} \right)^{3} \right) - exp \left( -\left( \frac{(h_{i,j})^{3/2} + H_{b_{i}}A^{3/2}}{1.25 h_{b_{i}}} \right)^{3} \right) \right]$$

$$\times \left( C'H_{b_{i,j}}^{5/2} \right) \right\} \qquad x sin (2e - 2a_{c}) \qquad (29)$$

 $Q_X(i,j)$  represents the sediment transport between depths h(i,j) and h(i,j-1) (see Fig. 1). The term in brackets represents the normalized distribution of longshore transport between h(i,j) and h(i,j-1);  $\theta$  is the averaged wave angle at the location of  $Q_X(i,j)$  and  $\alpha_C$  is the local contour orientation angle. Defining everything except sin  $(2\theta-2\alpha_C)$  as  $\nu(i,j)$  and using a superscript to denote a time step, this equation can be written

$$Q_{x_{i,j}}^{n+1} = v_{i,j} \sin (2e - 2a_c^{n+1})$$
 (30)

The assumption has been made that the wave field (H and  $\Theta$ ) do not vary during the bathymetric changes over the time-step. Using the following trigonometric identities,

$$sin (2a - 2b) = sin 2a cos 2b - cos 2a sin 2b$$
 (31a)

$$\cos 2a = 2 \cos^2 a - 1$$
 (31b)

$$\sin 2a = 2 \sin a \cos a$$
 (31c)

and recognizing that the following expression is an approximation

$$\sin \left(\alpha_{c}^{n+1}\right)_{i,j} = \frac{\frac{1}{2} \left(y_{i,j}^{n+1} - y_{i-1,j}^{n+1} + y_{i,j}^{n} - y_{i-1,j}^{n}\right)}{\left(\left(\Delta x\right)^{2} + \left(y_{i,j} - y_{i-1,j}\right)^{2}\right)^{1/2}}$$
(32)

along with assuming that the change in the denominator is small for a reasonable time-step (the numerator has been averaged over the  $n^{th}$  and  $n+1^{th}$  time-steps), equation (30) results in

$$Q_{x_{i,j}}^{n+1} + (S3)_{i,j} y_{i,j}^{n+1} - (S3)_{i,j} y_{i-1,j}^{n+1} = (RHS1)_{i,j}^{n}$$
(33)

ere 
$$(S3)_{i,j} = (\frac{1}{2}) (v_{i,j}) \cos (2\theta) (2 \cos \alpha_c) \frac{1}{(\Delta x^2 + \Delta y^2)^{1/2}}$$
  
 $(RHS1)_{i,j}^n = (v_{i,j}) (2 \sin \theta \cos \theta) (\cos^2 \alpha_c - 1) - (S3)_{i,j} (y_{i,j}^n - y_{i-1,j}^n)$ 

Here it has also been assumed that  $\cos^2\alpha_C$  does not change over the time step. Equation (33) is the final form of the longshore sediment transport equation prior to its use in conjunction with the other equations.

Averaging y values on the  $n^{th}$  and  $(n+1)^{th}$  time-steps, equation (29) can be rewritten as

$$Q_{y_{i,j}} = Const6_{i,j} \left\{ \frac{1}{2} \left( y_{i,j-1}^{n+1} + y_{i,j-1}^{n} - y_{i,j}^{n+1} - y_{i,j}^{n} \right) + W_{EQ_{i,j}} \right\}$$
(34)

where Const6(i,j) = Coff(i,j).  $\Delta x$ . This is the final form on the onshore-offshore sediment transport equation.

The equation of continuity, finite-differenced for the  $n^{\mbox{th}}$  and  $(n+1)^{\mbox{th}}$  time-steps, can be written as

$$\frac{y_{i,j}^{n+1}-y_{i,j}^{n}}{\Delta t} = \frac{1}{2\Delta \times \Delta h} \left\{ Q_{x_{i,j}}^{n+1}+Q_{x_{i,j}}^{n}-Q_{x_{i+1,j}}^{n+1}-Q_{x_{i+1,j}}^{n}+Q_{y_{i,j}}^{n+1}+Q_{y_{i,j}}^{n}-Q_{y_{i,j}+1}^{n+1}-Q_{y_{i,j}+1}^{n} \right\}$$

Defining  $R_{i,j}$  as  $1/(2\Delta x \Delta h)$ , inserting equations (33) and (34) into equation (35), and transferring all known quantities for the  $n^{th}$  time-step to the right-hand side of the equation result in

$$y_{i,j}^{n+1} + (\Delta tR_{i,j})S3_{i,j}y_{i,j}^{n+1} - (\Delta tR_{i,j})S3_{i,j}y_{i-1,j}^{n+1} - (\Delta tR_{i,j})S3_{i+1,j}y_{i+1,j}^{n+1}$$

$$+ (\Delta tR_{i,j})S3_{i+1,j}y_{i,j}^{n+1} - (\Delta tR_{i,j}Const6_{i,j}) \left(\frac{1}{2} \left[ y_{i,j-1}^{n+1} - y_{i,j}^{n+1} \right] \right)$$

$$+ (\Delta tR_{i,j}Const6_{i,j+1}) \left(\frac{1}{2} \left[ y_{i,j}^{n+1} - y_{i,j+1}^{n+1} \right] \right) = (AWARE)_{i,j}$$
 (36)

Equation (36) can be rewritten as

$$(1 + U + V + Z1 + Z2) y_{i,j}^{n+1} - (U)y_{i-1,j}^{n+1} - (V)y_{i+1,j}^{n+1}$$

$$- (Z1)y_{i,j-1}^{n+1} - (Z2)y_{i,j+1}^{n+1} = (AWARE)_{i,j}$$
(37)

where

$$U = \Delta t R_{i,j} S_{i,j}^{3}$$

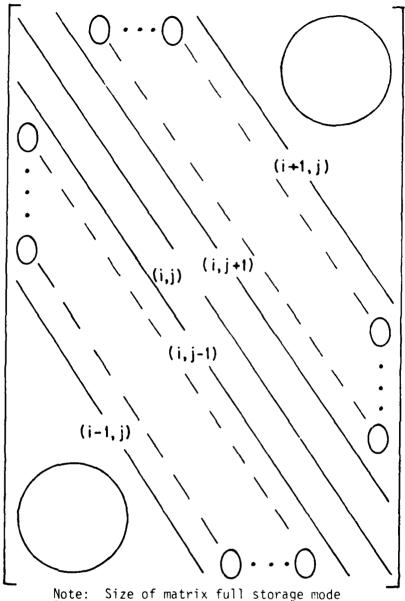
$$V = \Delta t R_{i,j} S_{i+1,j}^{3}$$

$$Z1 = (\frac{\Delta t}{2}) R_{i,j} Const_{i,j}^{6}$$

$$Z2 = (\frac{\Delta t}{2}) R_{i,j} Const_{i,j+1}^{6}$$

Equation (37) is a weighted, centered scheme in which  $y_i^{n+1}$  is computed using a weighting of itself and its four adjacent grid "neighbors". The weighting factors (U, V, Z1, and Z2) are functions of the wave climate, the slope between contours, and the variables included in the original formulation. An investigation of a small gridded system demonstrated that by writing simultaneous equations, one for each  $y_{i,j}$ , a banded matrix results. This matrix can be solved by LEQTIB, one of the available routines from the International Math and Statistics Library (IMSL). A schematic representation of the matrix A which results from the matrix equation [A][y] = [B] is presented in Figure 5. In this schematic, the large zeros represent triangular corner sections of all zeros and the 0...0 represents bands of zeros, the number of which is dependent on the number of contours simulated (the number of zero bands between either remote nonzero bands and the tridiagonal nonzero bands equals two less than the number of contours modeled (in both the upper and lower codiagonals of the matrix)). An inspection of the subscripts in equation (29) yields the reason the zero bands are required. The more j values (contours) used, the more y grids there are along any perpendicular to shore. This causes zeros to appear in the matrix between bands as the weighting factors await being used to operate on  $y^{n+1}(i-1,j)$ and  $y^{n+1}(i+1,j)$ . For this reason, the expense of simulating an increasing number of contours is exponential. The LEOTIB routine, utilizes banded storage and saves both storage and computation time; however, the routine has no special way of handling the interior zero bands. One refinement which would save computation time would be to develop an algorithm to solve and store the matrix by taking advantage of these inner zero bands; however, it is beyond the scope of this project.

Of course, the matrix requires boundary values on longshore extremities and on both onshore and offshore boundaries. The longshore boundary conditions are treated by modeling a sufficient stretch of shoreline so that effects of a structure's presence are minimal. The y values along these boundaries can therefore be fixed at their initial locations. In the onshore-offshore direction, boundaries are treated quite differently. The



Note: Size of matrix full storage mode [(IMAX-2)(JMAX) x (IMAX-2)(JMAX)]

Size of matrix banded storage mode [(IMAX-2)(JMAX) x (2JMAX + 1)]

Figure 5. Schematic representation of banded matrix if not stored in banded storage mode.

berm and beach face are assumed to move in conjunction with the shoreline position. The required sediment transport is then computed by the change in position of the shoreline. The two equations are

$$y_{i,0}^{n+1} = y_{i,0}^{n} + [y_{i,1}^{n+1} - y_{i,1}^{n}]$$
 (38a)

$$Q_{y_{i,1}}^{n+1} = -\left[\frac{Berm \Delta x}{\Delta t}\right] [y_{i,1}^{n+1} - y_{i,1}^{n}]$$
 (38b)

The offshore boundary is treated by keeping  $y^{n+1}(i,jmax)$  (the contour beyond the last simulated contour) fixed, until the angle of repose is exceeded. Then, the  $y^{n+1}(i,jmax+1)$  is reset (at the conclusion of the n+1 time-step) to a position such that the slope equals the angle of repose. Note that  $y^{n+1}(i,0)$  is represented in the program by YZERO<sub>i</sub>.

There are also no-flow boundary conditions required at each of the structures being modeled. These are imposed on the adjacent y-grid points which are located downdrift (i.e., in the shadow zone) of the structure and shoreward of the structures' seaward extremities. They are imposed by setting S3; j of equation (33) and DISTR; j (the term in square brackets in equation (29) equal to zero, thereby causing  $Q_X(i,j)$  to be zero (i.e., the no-sediment flow condition). This boundary condition is imposed automatically for every shore-perpendicular structure.

It was found that even with the implicit formulation, high frequency oscillations occurred in the y values immediately updrift and downdrift of the structure. The solution did not "blow up"; however, on larger time-steps "sloshing" (oscillating) did occur. Part of this problem was due to the boundary condition at the structure which had been such that either no sand was allowed along a contour line or the sand determined by the equations was allowed to be transported. Because of the very large angle which existed around the tip of the structure when a contour first exceeded the length of the structure, very large amounts of sediment transport were predicted. In the nature where analog sand transport rather than digitized transport occurs, this does not happen. Therefore, the boundary condition was altered to constantly allow sand transport around the end of the structure in proportion to that part of the contour representation which exceeded the structure (i.e., the transport was calculated for the location at tip of the structure as if the structure was not there and then a proportion of this value was allowed to bypass). Although the transport around the tip of the structure is based on the values from the past time-step, it more closely simulated the natural phenomenon.

Additionally, a dissipative interface is used on the y values as follows:

$$y_{i,j} = (\tau) y_{i-1,j} + (1 - 2\tau) y_{i,j} + (\tau) y_{i+1,j}$$
 (39)

where  $\tau$  was again taken as 0.25. It is noted that only high frequency oscillations in y are affected by the use of equation (39); the total sum of y values is not affected. Also, in all the dissipative interface

schemes used, if a boundary point is being computed, either a forward-difference or a backward-difference of equation (39) is used (after Abbott, 1979):

Backward: 
$$y_{i,j} = (\tau)y_{i-1,j} + (1 - \tau)y_{i,j}$$
 (40a)

Forward: 
$$y_{i,j} = (\tau)y_{i+1,j} + (1 - \tau)y_{i,j}$$
 (40b)

#### IV. SIMULATIONS AND VERIFICATION

Several simulations were run; two were attempts at verifying the numerical model, the others were run to gain insight. Because a complete data set does not exist, only the available data are compared. The first modeling effort was to simulate the physical model tests of Savage (1959). A second set of cases was run for shore-perpendicular structures. Next, an effort was made to model sediment transport in the vicinity of a hypothetical dredge disposal site in the 11- to 14-foot depths off Oregon Inlet. Finally, the Channel Islands Harbor Longshore Transport Study (Bruno, et al., 1981) was modeled. Bathymetric changes were closely monitored during this study; however, the wave climate (H, e, T) used was determined from the Littoral Environmental Observation (LEO) data and uncertainties exist as to the accuracy of the data.

#### 1. Simulation of Savage's Physical Model Tests.

The numerical model was used to simulate one of the physical model tests of Savage (1959). Test 5-57 was simulated numerically for a 10-hour period. In this physical model, the mean sediment size was 0.22 millimeters, the wave height averaged 0.25 feet, the wave period was 1.5 second, the wave angle was 30° (at a depth of 2.3 feet), and the groin was approximately 9.5 feet from still water to its seaward limit. Coff was held constant at  $10^{-4}$  feet per second throughout the profile for this simulation. The offshore profile is presented in Savage (1959). Figure 6 represents three of the eight contours simulated. Note that the initial 0.3- and 0.5-foot-depth contours, in the numerical representation are too far seaward by approximately 2 feet. This is due to the h =  $Ay^{2/3}$  equation as compared to the equilibrium physical model profile. Realizing this, it is the shape of the contour which must be used as an indication of the numerical model predictions. The general trend of the contours is similar, although the numerical model contours are displaced farther seaward as expected. The major differences are in the diffraction zone.

### 2. <u>Several Runs Using Shore Perpendicular Structures to Demonstrate Effects of Altering Some of the Pertinent Parameters.</u>

In the following simulations, the models were run until their near-equilibrium values were achieved. Coefficient Coff was not a function of depth (beyond the surf zone) but was held constant throughout the simulated area. Important variables are as shown in the figures. Only one wave condition ( $H_0$  = 3 feet, T = 7 seconds, and a deepwater wave angle  $\alpha_0$ 

Note: Discrepancy between initial Savage contours and initial model contours is due to use of the h =  ${\rm Ay}^{2/3}$  profile.

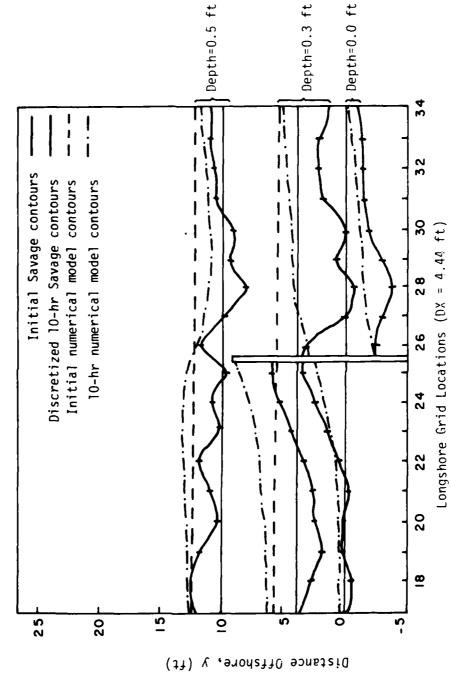


Figure 6. Simulation of the physical model of Savage (1959).

of 60°) was used as input for all four cases. Case 4.2a used an equilibrium shape factor A of 0.0899 and one groin. Case 4.2b was similar to 4.2a with the only modification being, that the A value was changed to 0.1486. In this way, a direct comparison was made based only on the shape of the equilibrium profile. Cases 4.2c and 4.2d used A-values of 0.0899 and 0.1486, respectively, but this time three shore-perpendicular, evenly spaced structures were simulated.

- a. Comparison of Cases 4.2a and 4.2b. The most obvious difference between Figures 7 and 8 is the volume of sand impounded updrift and eroded downdrift. This is due to blockage of more of the active transport zone in the second case (i.e., a shorter groin is required for an equivalent performance on a steeper beach). The next obvious difference is the size of the perturbation which exists in the offshore contours. Clearly, case 4.2b is more perturbed and this is expected because larger offshore transports occur due to the steepening on the updrift side. Conversely, this means less sediment is initially bypassed (and along with the downdrift requirement for larger volumes of sand) causes larger erosional features in case 4.2b. Another interesting feature is the downdrift fillet which occurs in the third, fourth, and fifth contours. The fillet is due to the shape of the sixth contour which occurs because of the inability of the wave to transport more sediment (due to the reduction in wave height and angle in the diffraction shadow zone). The remaining difference is also due to the volume of sediment being impounded; i.e., the distance and extent of change the presence of the groin causes upcoast and downcoast.
- b. Comparison of Cases 4.2c and 4.2d. The variations between cases 4.2c and 4.2d are very similar to the differences between cases 4.2a and 4.2b as would be expected with a groin field (here, three groins) as compared with a single groin (see Figs. 9 and 10). There is, however, one additional feature which can be attributed to the additional groins. Note that in the direction of littoral drift, the size of the fillet is decreasing. This is due to the updrift beach having an uninterrupted supply of sediment while the downdrift groin compartments are supplied sand at a rate determined by the bypassing. Part of this feature may also be due to the system not having attained complete equilibrium.

The effects of the fixed boundary conditions are evident on all cases run. In these example cases, the boundaries are clearly too close to the structure to provide a proper representation of the fillet contours.

3. <u>Simulations of Sediment Transport of Dredge Disposal in the Vicinity of Oregon Inlet.</u>

Hypothetical dredge disposal movement in the nearshore but beyond what is normally the surf zone at Oregon Inlet's adjacent beach to the south was modeled. In order to do these simulations, the program was altered such that for every  $n\frac{th}{t}$  iteration (time periods), the contours were shifted seaward to simulate the addition of dredged sediment disposal. The program presented in Appendix B does require slight modification to simulate this situation.

In general, the fifth and sixth contours were shifted seaward on a monthly basis to simulate the disposal of 121,000 cubic yards of sediment.

Note: J=7 and 8 contours not shown

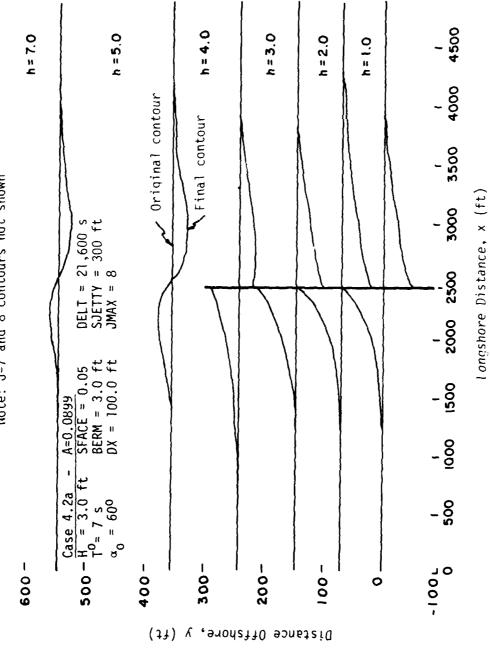


Figure 7. Equilibrium planform, case 4.2a.

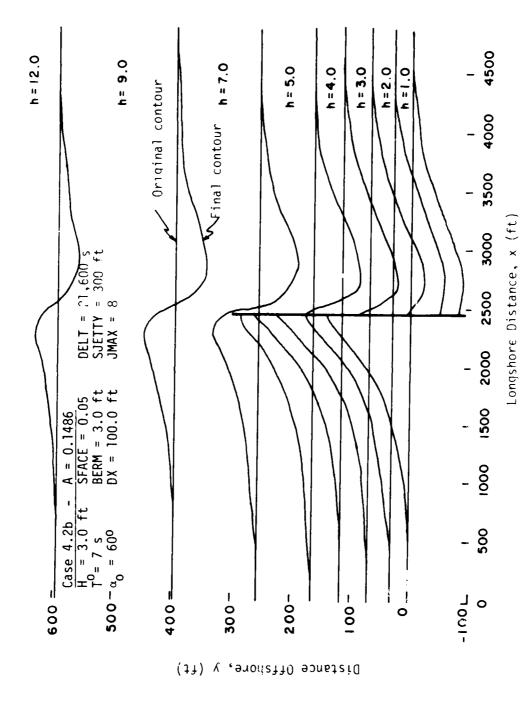
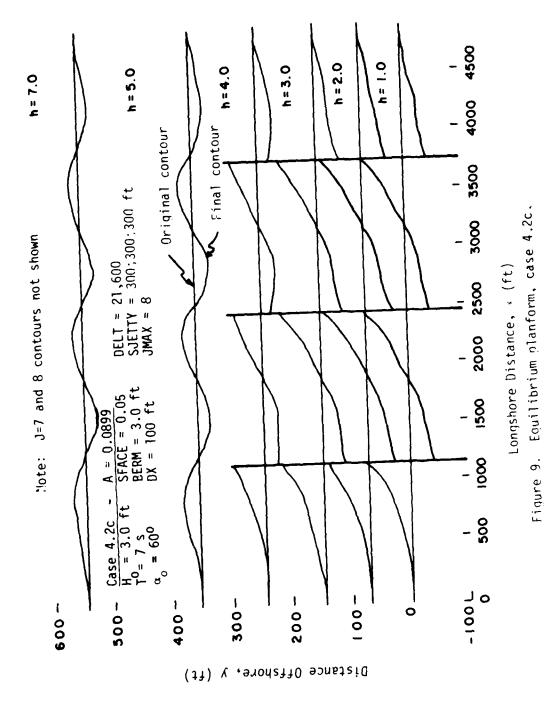


Figure 8. Equilibrium planform, case 4.2b.



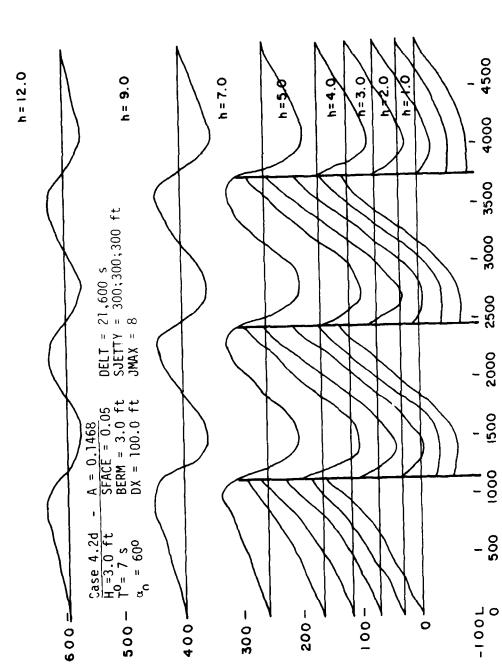


Figure 10. Equilibrium planform, case 4.2d.

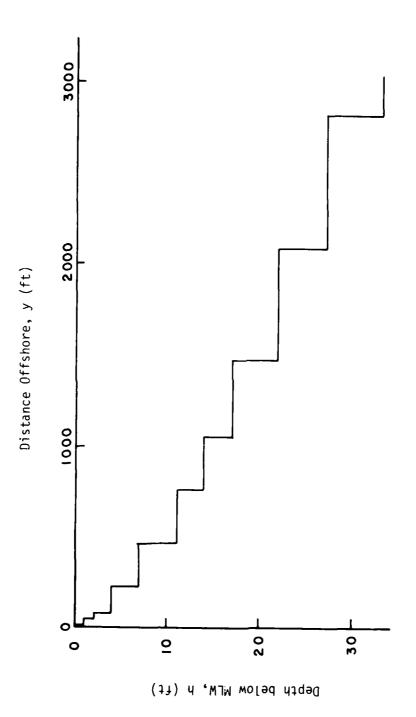
Longshore Distance, x (ft)

Distance Offshore, y (ft)

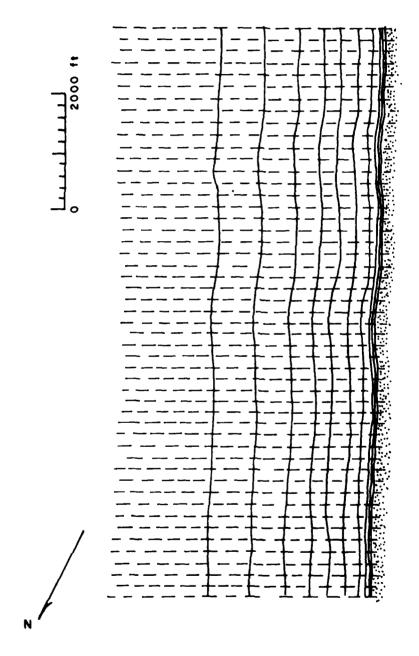
In all these simulations, the following variables were held constant: (a) a time-step of 3 hours, (b) a shoreline length of 10,000 feet, (c) a longshore space-step of 200 feet, (d) an A value of 0.15 foot $^{1/3}$  for the equilibrium profile (see Fig. 11), (e) a berm height of 5.3 feet with a beach face slope of 0.05, and (f) a duration of 1 year. The wave climate was provided by the U.S. Army Engineer Waterways Experiment Station Wave Information Study (WIS) 1975 data and was initiated at different times of the year as indicated in the specific cases below. All simulations, prior to any addition of sediment, used the bathymetry shown in Figure 12. The shoreline (relative to mean low water, MLW) was scaled from a bathymetry-topography survey provided by the U. S. Army Engineer District, Wilmington. The initial offshore bathymetry was computed according to the equilibrium profile and the O-foot contour; i.e., the profile was shifted seaward or landward, accordingly, (see App. C.) The boundary profiles were fixed throughout the simulations. The variation of COFF outside the surf zone was used because of the importance of the time rate of change in this simulation. Table 1 presents the percentage of sediment which moves out of the control volume (i.e., imaginary boundaries around the area where sediment was added) directly onshore and the percentage of sediment remaining in the control volume at the conclusion of the simulation for each of the cases. In addition, a seventh (case 3) and eighth (case 4) were modeled. In Case 3, the only difference was that sediment was placed at the 11- and 14-foot contours. Case 4, however, was quite different and will be described in detail later. It has a 20,000-foot shoreline, a longshore space-step of 400 feet, and sediment was added on a weekly basis. Also, the resolution in the profile was better.

### a. Specific Cases.

- (1) <u>Case 2.a.</u> In order to provide insight for the interpretation of the other modeling efforts, a simulation of the shoreline evolution using the January to December WIS time series, with no addition of sediment, was carried out. As expected, the contours almost attain an equilibrium planform shape (i.e., straight and parallel between the fixed end profiles; they do not, however, become aligned parallel to the base line because of the end conditions). Because of the scales involved, alongshore versus onshore-offshore, plotting the contours without distortion does not yield much information. Appendix C provides a listing of the final contours for all the cases modeled.
- (2) <u>Case 2.b.</u> The only difference between cases 2.a and 2.b is the suppression of the WIS wave angle which was set equal to zero (i.e., wave crest approach is shore-parallel at the offshore boundary of the model). This does not cause the longshore sediment transport to vanish completely. There are still local gradients in the contours which cause refraction and relative angles between wave crest and contour, thereby driving the longshore sediment transport (even if refraction was not considered, the local angle between the wave crest and contour would cause sediment transport). Note the larger onshore transport (Table 1) for this case compared with Case 2.a. This is due to the reduction in longshore transport caused by the wave angle of 0°. The model still tries to smooth the contour lines; however, more of the smoothing for the present case must be done by onshore-offshore transport.



Stepped version of equilibrium profile used in the Oregon Inlet modeling,  $h={\rm Ay}^2$   $^3$  (A = 0.15 feet  $^1$   $^3$  ). Figure 11.



Initial contours used in the numerical model for all the Oregon Inlet simulations. (The scale for case 4 was twice the scale shown.) Figure 12.

Table 1. Summary of results at Oregon Inlet.

Case No.	Description	Pct Onshore out of control volume	Pct Remaining in control volume
2.a	No sediment added, WIS waves Jan Dec.	Onshore Movement (992 yd <sup>3</sup> )	Increase (14,148 yd <sup>3</sup> )
2.b	No sediment added, WIS waves $(\alpha = 0^{\circ})$ , Jan Dec.	Onshore Movement (1624 yd <sup>3</sup> )	Increase (9,356 yd <sup>3</sup> )
2.c1	121,000 yd <sup>3</sup> added monthly, WIS waves Jan - Dec.	31.7 (460,264 yd <sup>3</sup> )	38.6 (559,984 yd <sup>3</sup> )
2.c2	121,000 yd <sup>3</sup> added monthly, WIS waves Apr Mar.	32.1 (466,160 yd <sup>3</sup> )	36.9 (535,392 yd <sup>3</sup> )
2.c3	121,000 yd <sup>3</sup> added monthly, WIS waves July - June.	28.6 (415,784 yd <sup>3</sup> )	47.0 (682,088 yd <sup>3</sup> )
2.c4	121,000 yd <sup>3</sup> added monthly, WIS waves Oct Sept.	27.2 (395,556 yd <sup>3</sup> )	46.8 (670,848 yd <sup>3</sup> )
3	121,000 yd <sup>3</sup> added monthly at the 11- and 14-foot contours WIS waves, Jan Dec.	8.9 * (32,164 yd <sup>3</sup> )	78.0 (283,016 yd <sup>3</sup> )
4	27,923 yd <sup>3</sup> added weekly on the 7- 8-, 9-, and 10-foot contours, WIS waves Jan Dec.	19.0 (275,796 yd <sup>3</sup> )	47.4 (687,525 yd <sup>3</sup> )

<sup>\*</sup> After 17 weeks, the addition of sand caused contours to cross. Prior sediment added was  $363,000~\text{yd}^3$ . Problem was rectified; however, case was not rerun.

(3) Case 2.cl. In this simulation, sediment is added to the system each month. It was simulated by advancing the 7- and 11-foot contours on a monthly basis to represent 121,000 cubic yards per month. Specifically, the sand volumes were "tapered" starting at the center of the nourished area over a distance of  $\pm$  2,700 feet from the center. Table 2 presents the monthly  $\Delta y$  values for the blocks between the 7- to 11-foot contours and the 11- to-14 foot contours. Figure 13 shows the planform  $\Delta y$  values added monthly. WIS waves were used with the sequence being the normal calendar year, January through December.

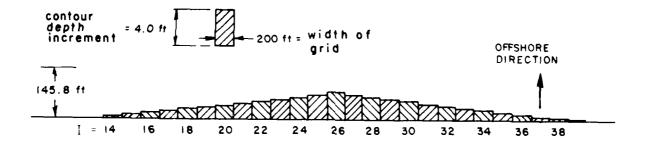


Figure 13. Monthly incremental values of  $\Delta y$  due to dredge disposal illustrated for the block between 7- and 11-foct contours.

The initial and final fifth and sixth contours have been plotted in Figures 14 and 15. The first figure has no distortion; the second is distorted 10 to 1. The simulation predicts that 31.7 percent of the dredge disposal will move shoreward out of the control volume. An additional 29.7 percent efflux occurs in the offshore and longshore directions, leaving only 38.6 percent of the total amount of sediment added remaining in the control volume. It is not clear what quantity of the sediment leaving in the longshore direction would reach shore. It is conceivable that most of this sediment would eventually reach the surf zone. The rate at which this material would move ashore would be expected to be slower than the rate at which the large mounds would move ashore because the deviation of the profile from equilibrium is much less.

(4) <u>Cases 2.c2, 2.c3, and 2.c4.</u> The next three simulations were the same as 2.c1 except the time series of wave events has been seasonally altered. Cases 2.c2, 2.c3 and 2.c4 use the 1975 wave climate from April through March, July through June, and October through September, respectively. The maximum variation is about 5 percent for the sediment volume moving onshore, and about 10 percent for the volume remaining. The variation in the

Table 2. Monthly values of  $\Delta y$  for the steps located between the 7- to 10-foot contours and the 11- to 14-foot contours.

Value of I	Monthly Δy value (ft) for steps between		
	7- and 11-foot contours	11- and 14-foot contours	
26	145.8	194.4	
25,27	135.4	180.5	
24,28	125.0	166.6	
23,29	114.6	152.7	
22,30	104.1	138.9	
21,31	93.7	125.0	
20,32	83.3	111.1	
19,33	72.9	97.2	
18,34	62.5	83.3	
17,35	52.1	69.4	
16,36	41.7	55.5	
15,37	31.2	41.7	
14,38	20.8	27.8	
13,39	10.4	13.9	
All Others	0	0	

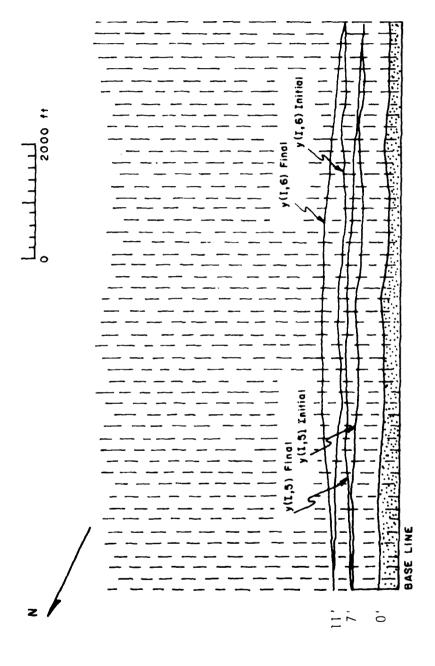


Figure 14. Initia, and final 7- and 11-foot contours (no distortion).

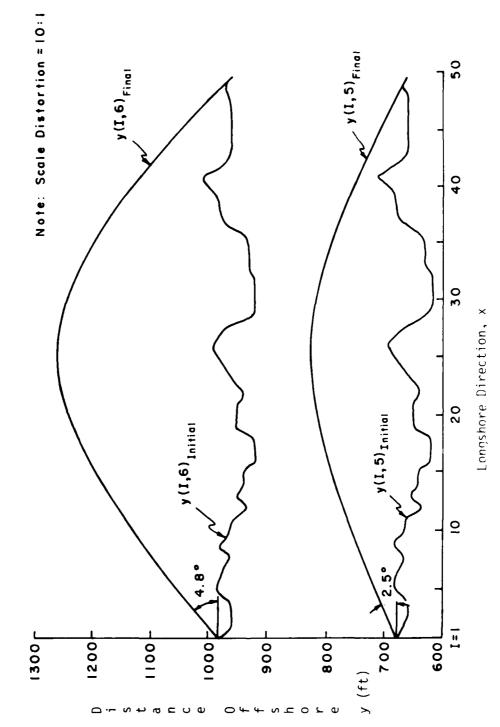


Figure 15. Initial and final contours for case 2.cl [y(1,5)] and y(1,6).

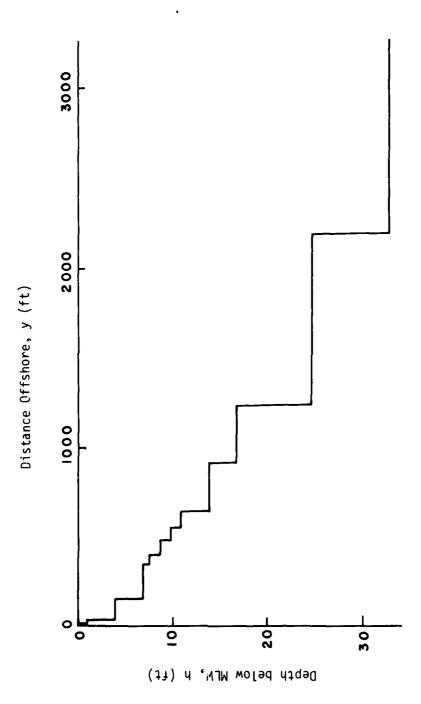
quantity moving onshore could be caused by waves that first tend to move more sediment longshore; then, the waves that transport more sediment onshore have a less out-of-equilibrium profile to cause movement upon. The variation in percentage remaining is due to the variation of the time series of the wave climate, with the last month in the simulation being especially important.

- (5) Case 3. Instead of extending the 7- and 11-foot contours monthly to simulate the disposal of dredged sediments, the 11- and 14-foot contours were extended (194.4 feet each at the center of the disposal area). This case was modeled because the larger available dredge could not dump in more shallow water. The reduction and increase in the percent of onshore volume and the percent volume remaining (8.9 percent and 78.0 percent, respectively) demonstrate the sensitivity of the depths investigated. Qualitatively, these depths are the depths to which offshore bars occur along the Atlantic U.S. coast.
- (6) Case 4. Further investigation of the disposal process demonstrated the need for an 11,000-foot shore-parallel disposal length with the sediment placed at the 11-foot contour building to about 7 feet. It was decided to model this physical situation also. The total shoreline length was changed to 20,000 feet, and the space step to 400 feet; the length of the disposal area in the longshore direction was increased to 10,800 feet. The resolution in the vicinity of the depths of the dump was improved by adding the additional contours and the profile is shown in Figure 16. As in the other seven cases, 1,452,000 cubic yards was added annually to the system; however, the addition was accomplished on a weekly basis (27,923 cubic yards per week). Sediment was still added by extending the contours seaward, but rather than placing one-fourth of the sediment at each of the four contours. the volumes were determined based on the trapezoidal cross section shown in Figure 17. This cross section more closely resembles the disposal mound formed by hopper dredging. The incremental values Figure 18 show, in planform, the extension of the contours to simulate the weekly sediment addition at the 8-foot contour.

A schematic illustration of the sediment transported from the nourished region is presented in Appendix C. Nineteen percent of the sediment added moved directly onshore out of the control volume.

b. Conclusions for the Movement of Disposed Sediment in the Vicinity of Oregon Injec. The computer simulations, tempered with engineering judgment, demonstrate that between 15 and 35 percent of the material added to the 7- and 11-foot contours, or to the 7- 8- 9-, and 10-foot contours would be transported into the nearshore transport system during the first year. If the disposal process was continued, the system would approach steady state in terms of the volume of deposited material residing offshore.

For the case of sediment addition at the 11- and 14-foot contours, the computer simulations, tempered with engineering judgment, show that between 5 and 25 percent of the material added would be transported into the nearshore transport system during the first year.



Stepped version of equilibrium profile used in the Oregon Inlet modeling,  $h=Ay^{2/3}$  (A=0.15 feet<sup>1/3</sup>), case 4. Note the resolution at 7, 8, 9, and 10 feet. Figure 16.

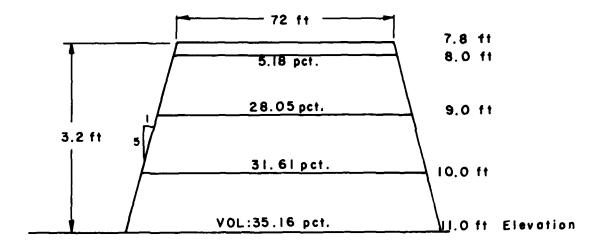


Figure 17. Shore-perpendicular cross section of disposal mound. The volumes represent the volume percentage of the trapezoidal section between contours and therefore, the quantity of sediment added to the 7-, 8-, 9-, and 10- foot contours.

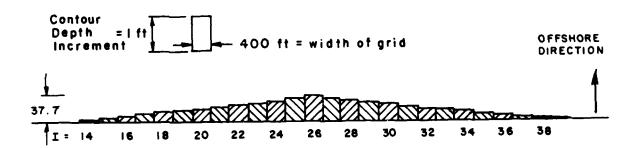


Figure 18. Incremental values of  $\Delta y$  due to dredge disposal, illustrated for the block between 8- and 9-foot contours (case 4).

# 4. <u>Simulation of the Longshore Sand Transport Study at Channel Islands Harbor, California.</u>

The CIH Longshore Sand Transport Study (Bruno, et al., 1981) was the only field study found suitable for verification purposes. Wave data collected included the LEO data and a two pressure-sensor gage array. Although the pressure gages were not in operation throughout the study, it was expected that the data they produced would be superior to that of the LEO data. However, these data were not available in a reduced form, so the LEO data were used. An adjustment of 11° was made to the breaker angle to orient the angle with respect to the base line, rather than to the local shoreline orientation angle. Observations had been taken twice daily at three locations; the middle location was used (observer No. 5714). Waves which approached the shoreline at angles too large to have originated in a depth of 10 meters, according to Snell's law, were set equal to 90° at that depth (crest of wave perpendicular to the baseline). The 10-meter depth was chosen because it is the approximate depth at the tip of the offshore breakwater (for this reason, it was also chosen as the depth of the step beyond the y(I, JMAX + 2) th contour). It was assumed that each of the two daily observations occurred for 12 hours and using a time-step of 6 hours, this meant two time-steps per wave. In cases where parts of the wave data (Hb, ah, or T) were missed by the observer or were equal to zero, the data were ignored (no computations were made), but the time was included. Because the time rate of change is important for this simulation, the variation of Coff outside the break point was used.

The period chosen to model was 20 April through 1 December 1976. The initial survey was taken after dredging of the sediment trap and for this reason was known to be out of equilibrium. The bathymetric surveys were conducted using several methods, the most advanced being a Lighter Amphibious Resupply Cargo vessel (LARC) proceeding along shore-perpendicular lines (approximately in the vicinity of each survey station) taking fathometer readings every 10 seconds, with positioning systems trilaterating the vessel's position concurrently. These data were recorded on tape. The beach-face data were taken using standard surveying methods. Because the data fluctuated randomly about the stations, depending on the speed of the craft, the (x, y) coordinate positions had to be altered to fixed changes in x and y. This was accomplished using an interpolation routine. The xvalues were made to coincide with the stations used in the surveys, and the y values were determined at 100-foot intervals beginning from the base line. Stations 100+00 and 118+00 were located at the north jetty and termination of the detached breakwater, respectively (these correspond to I values of 16.5 and 34.5 in the model). See Figure 19.

Monotonic profiles of the form  $h = A(y - ydel)^{2/3}$  were fit to the data along each station line. "ydel" represents the zero location of the fitted shoreline, the value of which was unknown. Because dredging had been done in the lee of the breakwater, there was no reason to expect the A value to correspond to the value upcoast where the influence of the structure and the dredging was negligible. For this reason, the profiles of Stations 122+00 through 134+00 were evaluated separately to determine an A value for the equilibrium profile to be used in the numerical model. For the detailed method used (LaGrange Multipliers and Newton-Raphson Method for nonlinear

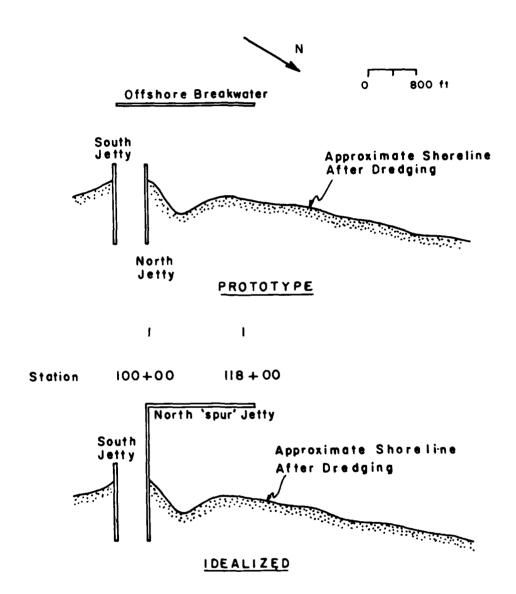


Figure 19. Idealized numerical model representation of offshore breakwater at Channel Islands Harbor, California.

equations) and the computer programs see Appendix D. The two values obtained for the surveys of 20 April and 1 December 1976 were averaged to obtain the value used in the model, A = 0.2606. Stations 101+00 through 121+00 were treated separately for the purpose of obtaining values with which to initialize those parts of the contours in the model and for comparison of the model predictions with the prototype values. Note that although the breakwater extends only to about Station 118+00, the influence of the structure and dredging extends beyond that location and so, although arbitrary, the 121+00 station was chosen as the dividing line. The initial and final values of the scaling parameter A for the profiles were 0.3233 and 0.3528, respectively. Because the initial shoreline is so irregular, a discontinuity between 121+00 and 122+00 is not evident.

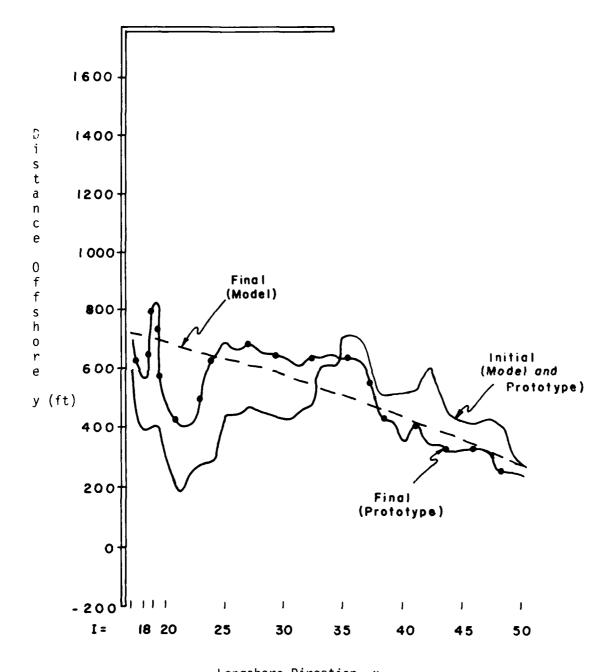
One further idealization was made. The jetty-breakwater system was idealized as shown in Figure 19. This was required to simplify the physical situation, and although waves, currents, and sediment do pass through the opening in the prototype, it is hoped that they are of secondary importance.

The results of the numerical modeling of Channel Islands Harbor are presented in Figures 20 and 21. The first figure presents the shoreline contour (depth = 0); the second figure presents the farthest offshore, modeled contour. In both cases, the initial shoreline represents the model and prototype (after fitting of the profiles). The initial shoreline contour is further offshore along the section of beach beyond the end of the breakwater, while in the lee of the breakwater, as would be expected after dredging, the shoreline is closer to the base line. The final prototype contour has undergone erosion along the reach beyond the tip of the structure, and accretion in the lee.

The model's shoreline contour has undergone similar changes, and on the average, represents the final prototype contour quite well. The JMAXth contour has been displaced quite similarly to the shoreline contour with shoreward movement (erosion) along the reach beyond the tip of the breakwater and seaward movement (accretion) within. It appears that the final model's shoreline has predicted too much erosion and not enough accretion. Several parameters could be incorrect, with the onshore-offshore sediment transport rate coefficient, COFF, perhaps the most likely. Overall, the model seemed to predict reasonable values or the contours.

#### V. SUMMARY AND RECOMMENDATIONS

Some of the parameters that the model does not include are important and should be mentioned. As stated previourly, the model does not include bar formation. This is precluded by an n-line system. There are no provisions for water level fluctuations or currents. Improvement to the model could also be facilitated with better longshore and cross-shore sediment transport relationships. A more reliable equation for distribution of sediment transport across the surf zone would also be helpful (or further testing and calibration of the equation proposed herein). Finally, combining refraction and diffraction using equations to predict their combined effect would improve the wave field. The program was constructed such that improvement



Longshore Direction, x
Figure 20. CIH simulation of shoreline contour, 20 April 1 December 1976 (from LEO data).

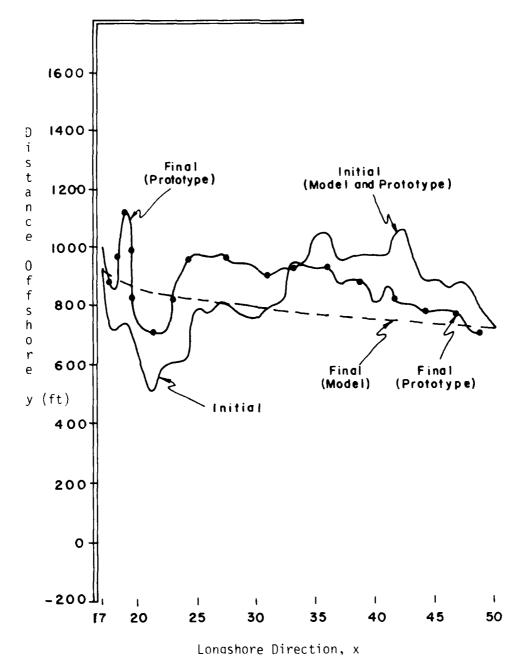


Figure 21. CIH simulation of (JMAX)<sup>th</sup> contour, 20 April - 1 December 1976 (from LEO data).

could be accomplished with minimum effort. Therefore, if a more suitable equation becomes available, the change of a subroutine should be sufficient for implementation of the equation.

Although the model is limited by the omission of the aforementioned parameters, it is reasonably correct. The ability to simulate various physical situations (shore-perpendicular structures, beach fills, breakwater and shore-perpendicular structures) has been demonstrated. In the CIH simulation where the data were first transformed to monotonically decreasing contours and LEO wave data were used, the model still predicts the prototype shoreline changes in a reasonable fashion.

Further research and model development should include exercising the model in a number of different situations. Several theoretical cases should be simulated, which if analyzed properly, would provide a tool for the coastal engineer. Combined refraction and diffraction should be included, if possible, along with any of the aforementioned parameters which have been omitted and for which relationships exist. Perhaps the most difficult problem to researchers working on modeling sediment transport in the vicinity of structures is the availability of field data. High-quality concurrent wave and bathymetric change data in the vicinity of coastal structures do not exist. One suggested field experiment is to monitor changes both updrift and downdrift of a jettied inlet which has a bypassing plant. Monitoring should begin immediately after bypassing, when the profiles are out of equilibrium. The recorded bathymetric and wave data would then provide data with which to calibrate, verify, and evaluate the existing models.

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#### APPENDIX A

## DISCUSSION OF CONSTANTS AND SOME OF THE VARIABLES REQUIRED BY THE MODEL

Establishing the grid-contour system requires several variables. IMAX represents the number of cross-shore grid lines desired and JMAX the number of contours simulated. DX represents the spacing between the IMAX grid lines and DY the spacing between the contours. DX is a value which must be chosen along with IMAX and JMAX such that sufficient detail is obtained where necessary (e.g., in the shadow zone, if diffraction effects are believed to be very important, DX must be assigned a sufficiently small value so that at least some points lie within the shadow zone for the larger wave angles). DY is not a constant, but a dimensional array which is computed by the model according to the contour location. Once the depths of contours to be modeled are chosen, the initialization of DY and the y values are computed with the following equation after Dean, 1977

$$h = A y^{2/3} \tag{A-1}$$

where h is the depth, y is the offshore distance and A is the scaling parameter Dean gives values for A for several diameter sediments; however, if long-term beach profiles are available for the site being modeled, the modeler may want to choose a slightly different A value to more closely match the site-specific beach profile. Figure A-1 presents values of A versus diameter (after Moore, 1982). The model is programmed to input the h(I,J) values (depths as shown in Figure 1, called DEEP (I,J) in the program) read in the value of A (called ADEAN in program) and it then computes the y values. Also shown in Figure 1 is the height of the berm (BERM) and this value, along with the beach-face slope (SFACE), is required as program input and can be obtained from beach profile site data. Because the model does not include water level fluctuations such as tides, all values are to be referenced to a chosen datum. Other geometrical constants depending on the site include SJETTY (the length of the jetty), MMAX (the number of structures to be input), and IJET (M), M = 1,2,...MMAX (the smaller I value adjacent to the  $M^{th}$  structure's location). If no structure is required, as in a beach fill, the value of SJETTY must be entered as 0.0, with MMAX and IJET (M) entered as 1 and (IMAX/2), respectively. As set up presently, the groin locations must be equally spaced.

One constant used throughout the program is the breaking wave criteria (CAPPA in the program) equal to 0.78. It is required in several different computations and always governs the maximum wave height allowed according to the depth.

Another group of variables assigned values within the program is the sediment and fluid properties. These include fluid mass density, sediment mass density, porosity, and the angle of repose (e.g., RHO = 1.99, RHOS = 5.14, POROS = 0.40, and REPOSE =  $32^{\circ}$ , respectively). The values can easily be changed to reflect site conditions.

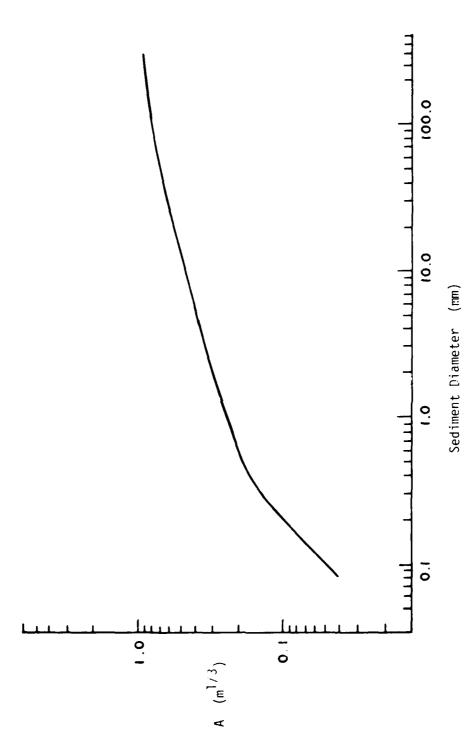


Figure A-1. A versus sediment diameter (after Moore, 1982).

Another very important set of constants is the constant chosen for the longshore and cross-shore components of sediment transport. Equation (27), the total longshore transport equation, contains the constant C' equal to

$$C' = \frac{\kappa_{\rho} (g)^{1/2}}{(\rho_{s} - \rho) (1 - p) (16) (\kappa)^{1/2}}$$
 (A-2)

where

K = 0.77 (Komar and Inman, 1970)

g is the acceleration of gravity (32.17 ft/sec<sup>2</sup>)

 $\rho_{\text{S}}$  and  $\rho$  are the mass densities of the sediment and the seawater (5.14 and 1.99 slugs per cubic feet, respectively

p is the porosity (0.40), and

 $\kappa$  is taken as 0.78.

Using these values to compute C' (TKSI in the program), a value of 0.325 is obtained. It is stressed that if any of these values are different for the site to be modeled, they should be changed and the program will compute another value for C'.

The parameter COFF is an "activity factor" which, based on earlier work primarily within the surf zone, was found to be

$$C_{OFF} = 10^{-5} \text{ ft/s}, \quad h < h_b$$

To generalize this concept for transport seaward of the surf zone, the wave energy dissipation per unit volume was utilized as a measure of mobilization of the bottom sediment. Inside the surf zone, the dominant wave energy dissipation is caused by wave breaking; outside the surf zone, the dominant mode of wave energy dissipation is due to bottom friction. These two components will be denoted by  $D_1$  and  $D_2$ , respectively.

(a) Energy Dissipation by Wave Breaking. The wave energy dissipation per unit volume by wave breaking,  $D_1$ , is

$$D_1 = \frac{1}{h} \frac{\partial}{\partial y} (E C_G) \tag{A-3}$$

which, employing the spilling breaker assumption (H =  $\kappa$ h) within the surf zone, can be shown to be

$$D_1 = \frac{5}{16} \rho g^{3/2} \kappa^2 h^{1/2} \frac{\partial h}{\partial y}$$
 (A-4)

or

$$D_1 = \frac{5}{24} \rho g^{3/2} \kappa^2 A^{3/2} \tag{A-5}$$

in which A is the scale parameter in the equilibrium beach profile

$$h(y) = Ay^{2/3}$$
 (A-6)

(b) Energy Dissipation by Bottom Friction. The wave energy dissipation per unit volume due to bottom friction,  $D_2$ , is

$$D_{2} = \frac{1}{h} \tau u_{b} = \frac{1}{h} \rho C_{f} \quad \overline{|u_{b}| u_{b}^{2}}$$
(A-7)

in which  $C_f$  is a bottom friction coefficient,  $u_b$  is the bottom water particle velocity and the overbar indicates a time average. For linear waves, equation (A-7) can be reduced to

$$D_2 = \frac{1}{6\pi} \stackrel{\circ}{h} C_f \frac{H^3 c^3}{\sinh^3 kh}$$
 (A-8)

The activity coefficient  $C_{OFF}$ , outside the surf zone, is expressed as

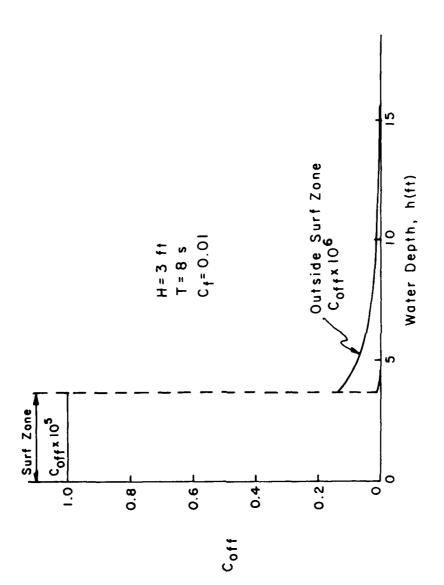
$$C_{OFF} = \frac{1}{\Gamma} \frac{D_2}{D_1} \times 10^{-5} \text{ ft/s}, \quad h > h_b$$
 (A-9)

$$c_{OFF} = \frac{4}{5\Gamma} \frac{c_{f^{\circ}}^{3}}{g^{3/2} \kappa^{2} A^{3/2} h} \left(\frac{H}{\sinh kh}\right)^{3} \times 10^{-5}$$
 (A-10)

in which  $\Gamma$  is a parameter relating the efficiency with which breaking wave energy (which occurs primarily near the water surface) mobilizes the sediment bottom (0 <  $\Gamma$   $\leq$  1). Herein,  $\Gamma$  is taken to be one.

Figure A-2 presents an example of the variation of the activity coefficient versus relative depth for a particular wave period and deep water wave height. It is seen that the activity coefficient reduces rapidly with increasing depth.

The value of COFF for the physical modeling of Savage's (1959) data was taken as  $10^{-4}$  feet per second. Perlin (1978) presents some rationale for choosing a value of COFF; however, very little testing has been done and none is based on actual field measurement.



Example of activity coefficient,  $C_{\Omega FF}$  versus water depth, h, for particular wave conditions. Figure A-2.

The second secon

Finally, wave data are read into the program and the simulation begins. (For information regarding "Read Formats" for the various constants and variables, see Appendix E). Wave data required are wave height, wave period, wave angle relative to the x-axis of the model at a depth, WDEPTH and the duration of the wave climate (HS, T, ALPWIS, and a combination of NTIMES x DELT, respectively, in the model). As is always the case with numerical models, the time step and space steps are very important to both stability and accuracy. Time steps on the order of 3 to 6 hours (10,800 to 21,600 seconds) or less are recommended. However, the complexity of the bathymetry, variation and time series of the wave data, constants used (especially COFF) along with several other factors, greatly influences the stability and accuracy of the results.

Table A-1 lists several of the important variables in the computer program.

Table A-1. List of important variables in the program

ABAND	The input banded matrix which stores the values from equation (37)	
ADEAN	The value of the scaling parameter in the equilibrium beach profile	
ALPHAS	The angle a contour makes with the x-direction base line (counter-clockwise is positive)	
ALPWIS	The angle (-90° to $\pm 90^\circ$ ) the wave crest makes with the x-direction (counter-clockwish is positive)	
AMP	The amplitude of the diffracted wave in the shadow zone	
ANGGEN	The wave angle at a depth, WDEPTH	
ANGLOC	The local contour orientation angle	
AWARE	See equations (36) and (37)	
BERM	The height of the berm above water level	
BMATRX	The matrix which, upon solution of the banded matrix problem yields the new y values	
С	The wave celerity	
CAPPA	The breaking wave index	
cc	Constant which establishes the width of the distribution of sediment transport across the surf zone	
CG	The group velocity throughout the wave field	
CGEN	The linear wave theory celerity at a depth, WDEPTH	

CGGEN	The linear wave theory group velocity at a depth, WDEPTH
CO	The deepwater, linear wave theory wave celerity
COFF	The onshore-offshore transport rate coefficient within the surf zone
CONST	The constant in the longshore sediment transport relationship (0.77)
CONST6	The space step, DX, multiplied by the activity coefficient
DEEP	The water depth at any grid location
DEEPB	The initial breaking depth along each profile (between adjacent profiles)
DEEPBI	The initial breaking depth along each profile (at each profile, rather than between them)
DELT	The time-step in seconds (DELT $x$ NTIMES = wave condition duration)
DIAM	The mean diameter of the sediment particles
DISTR	See equations (36) and (37)
DX	The alongshore space-step in the x-direction (distance between I values) $\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$
DY	The onshore-offshore space-step in the y-direction as defined by the stepped profile
EL0	The deepwater, linear wave theory wavelength
ELTIP	The wavelength at the tip of the structure
EPS	The change in the wave number which is acceptably small
G	The acceleration of gravity (32.17 feet/second $^2$ )
GAMMA	The specific weight of seawater
н	The wave height throughout the wave field
НВ	The maximum wave height which could exist throughout the wave field (where $H = 0.78 * h$ )
HBI	The initial breaking wave height along any profile at the y values rather than between them
нво	The initial breaking wave height along any profile, between adjacent profiles

HGEN Average wave height at a depth, WDEPTH The significant wave height input HS I The longshore grid location The leeward side of the initial breaker location J value **IBREAK** Represents the lesser I value adjacent to the structure (these IJET must be evenly spaced alongshore) IMAX The total number of grid points in the x-direction (alongshore) J The offshore contour location **JMAX** The value of the seawardmost contour simulated (JMAX + 2) the seawardmost contour at which the wave field is JUSE calculated J1 Landward contour of refraction zone J2 Seaward contour of refraction zone Landward J values of boundary of refraction zone **J1REF** Seaward J values of boundary of refraction zone J2REF MMAX The number of shore-perpendicular structures to be simulated (present maximum of 16) NITER The counterindex in the refraction routine The counterindex in the time simulation "DO" loop NTIME NTIMES The number of iterations of time-step, DELT, for which a particular wave is simulated NUNIV The total number of time-steps simulated at any time PΙ The value of  $\pi = 3.141592654$ **POROS** The porosity of the sediment QX The longshore sediment transport rate at a specific location QXTOT The total alongshore sediment transport rate due to the height and angle of the initial breaking wave OY The onshore-offshore sediment transport rate at a specific location

See equations (36) and (37)

R

REPOSE The angle of repose of the sediment

RHO The mass density of seawater

RHOND The dimensionless distance from the tip of structure where

diffraction is initiated

RHOS The mass density of sediment

RK The wave number

S3 See equations (36) and (37)

SFACE The slope of the shoreface

SJETTY The length of the shore-perpendicular structure (from the base

line)

SIGMA The wave radian frequency

T The wave period

TAU The dissipative interface parameter

THETA The wave angle throughout the wave field

THEATO The wave angle at the tip of the structure

TKSI The longshore sediment transport rate coefficient

TWOPI Twice the value of  $\pi$ 

U See equations (36) and (37)

UCRIT The critical velocity required to move the sediment according to

the Sheid's diagram

V See equations (36) and (37)

WDEPTH The depth of water in meters to which the input wave conditions

are to be transformed

WEQ The equilibrium profile distance between contours as defined by

the stepped profile

XCOOR The x-coordinate where the wave field is to be calculated.

Together with YCOOR, they determine whether the position is within

or beyond the diffraction shadow zone

XDISTN The location of the structure along the shoreline in feet

Y The distance offshore to the contours

YCOOR	The y-coordinate where the wave field is to be calculated. Together with XCOOR, they determine whether the position is within or beyond the diffraction shadow zone
YDISS	The value of y after the use of the dissipative interface
YOLD	The previous value of y
YZERO	The berm contour location
<b>Z</b> 1	See equation (37)
<b>Z2</b>	See equation (37)

APPENDIX B PROGRAM LISTING

```
100
        C* ****** PROGRAM IMPLICIT SEDTRAN
        C*THIS PROGRAM IS SET-UP TO HANDLE MULTIPLE GROINS(M<=10)

COMMON/A/ C(60,20),RK(60,20),Y(60,20),DEEP(60,20),ALPHAS(60,20)
 200
 300
 400
               COMMON/AA/YZERO(60)
               COMMON/BB/WEQ(60,20)
 500
               COMMON/B/ THETA(60,20),QXTOT(60), OLDANG(60,20), DY(60,20)
COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
 600
 700
 800
               COMMON/N USED/JUSE, T, CO. CGEN, CGGEN, ANGGEN, DX, BERM, THETAO (10). MMAX
 900
               COMMON/D/SIGMA, G, ELO, JMAX, IMAX, PI, TWOPI, PIO2, HGEN, IJET(10), SUFTIT
1000
               COMMON/F/ADEAN, REPOSE, DIAM
1100
               COMMON/AAA/DELT, NTIMES
               COMMON/COUNT/NUNIV
1200
               COMMON/EXPL/QYEXP(60,20), YIMP(60,20)
1300
               DIMENSION CHANGE(20), HC(10), TC(10)
1400
1500
               DIMENSION YORIG(60,20), YZEROO(60), SANGLE(20)
1600
               NUNIV=0
1700
               8= X AMU
1800
               JUSE = JMAX+2
1900
               IMAX=50
2000
               PI=3.141592654
2100
               TWOPI=PI*2.
               P102=P1/2.0
2200
               REPOSE = 32. *TWOPI / 360.
2300
2400
           WRITE(6,732)
732 FORMAT('*****
2500
2600
               WRITE(6,733)
2700
           733 FORMAT(2X, 'TO WHAT DEPTH ARE THE WAVES TO BE TRANSFORMED')
2800
        C*WDEPTH MUST BE A DEPTH BEYOND THE END OF THE STRUCT, PREFERABLY AT
        C**DEEP(JMAX) OR GREATER(OR ELSE SNELL'S LAW OR SHOAL COULD BLOWUP IN
2900
3000
        C***DEEPER WATER. IT'S IN METERS HERE!
3100
               READ(5,770)
                              WDEPTH
           770 FORMAT(10X,F10.3)
3200
               WDEPTH=WDEPTH*3.28084
3300
3400
               WRITE(6,762)
                               WDEPTH
3500
           762 FORMAT(2X. "THE DEPTH (IN FT) WAVES TRANSFORMED TO, WDEPTH= "
3600
              * F10.3)
               WRITE(6,732)
3700
3800
               WRITE(6,777)
3900
          777 FORMAT(2X, "ITS TIME FOR SJETTY, BERM, SFACE, AND DIAM"./)
        C*SJETTY MUST BE MUCH LESS THAN Y(I, JMAX)
4000
4100
               READ(5,776)
                              SJETTY, BERM, SFACE, DIAM
           776 FORMAT(2F10.3,F10.4,F10.3)
4200
4300
               WRITE(6,761)
                               SJETTY
4400
           761 FORMAT(2X, 'THE LENGTH OF THE STRUCTURE, SUETTY = ', F10 3)
4500
               WRITE(6,740)
                                BERM
4600
           740 FORMAT(2X, 'THE HEIGHT OF THE BERM, BERM: , F10.3)
4700
               WRITE(6,739)SFACE
          739 FORMAT(2X, THE SLOPE OF THE BEACH FACE, SFACE= 1,F10 4)
WRITE(6,738) DIAM
4800
4900
               WRITE(6,738)
           5000
5100
               WRITE(6,732)
           780 FORMAT(2X, 'SUPPLY MMAX( THE NO. OF GROINS) AND THEIR I-LOC',/)
5200
               UCRIT=16.3*SQRT(DIAM*O 00328)
5300
5400
        C*THE NO. OF MULTIPLE GROINS, MMAX MUST BE GIVEN THEIR X LOCATIONS
5500
               READ(5,779)
                               MMAX
5600
           779 FORMAT(13)
5700
               DO 760 M=1, MMAX
5800
        C*IJET REPS LESSER I-VALUE ADJACENT TO STRUCTURE
           760 READ(5,779)
                              IJET(M)
5900
6000
               WRITE(6,759) (M, IJET(M), M=1, MMAX)
6100
           759 FORMAT (2X, 'THE NUMBER', IS, 'GROIN IS LOCATED AT GRID .15)
6200
               WRITE(6,732)
6300
        C*CONVERT TO RADIANS
        C*FIRST MUST GIVE Y COORS POSITIONS AND DEPTHS
C*FIRST, MUST SET UP ALL OF THE DEEP-VALUES
WRITE(6,773)
6400
6500
6600
           773 FORMAT(2X, "NOW ENTER THE VALUE OF ADEAN")
6700
               READ(5,774)ADEAN
6800
6900
           774 FORMAT(F10.4)
7000
               WRITE(6,749)
                                ADCAN
7100
           749 FORMAT(2X, 'THE VALUE OF ADEAN= '.F10 4.' IN THE EQ. HEAY**2/3')
7200
               WRITE(6,732)
```

```
7300
               WRITE(6,772)
7400
           772 FORMAT(2X, "READ IN THE SPACE STEP, TIMESTEP", /)
7500
               READ(5,775)
                             DX.DELT
7600
           775 FORMAT(2(F10.3))
7700
               WRITE(6,737)
7800
           737 FORMAT(2X, 'THE VALUE OF THE LONGSHORE SPACE-STEP, DX= ',F10 3)
7900
               WRITE(6,736)
                              DELT
           736 FORMAT(2X, 'THE TIME-STEP IN SECONDS, DELT= ',F10.3)
8000
8 100
               DATA CHANGE/1.,2.,3.,5.,7.,11.,14.,17 ,25.,32.808,10*0 0/
               DO 220 J=1, JMAX+2
8200
               DO 220 I=1, IMAX
8300
8400
           220 DEEP(I,J)=CHANGE(J)
8500
               DATA(HC(I), I=1,8)/1.87,0.5,0.35,.25,.21,.20,.19,.19/
8600
               DATA(TC(I), I=1.8)/2..3..4..6 .8..10..12 .14 /
8700
               DO 200 J≈1, JMAX+2
8800
               DO 200 I=1, IMAX
8900
           200 Y(I,J+1)=(0.5*(DEEP(I,J+1)+DEEP(I,J))/ADEAN)**1.5+Y(I,1)
9000
               WRITE(6.732)
9100
         C*WE WILL ALWAYS REQUIRE Y(I,JMAX+2) TO COMPUTE DY AND YBAR
9200
9300
         C*WE WILL ALWAYS REQUIRE DEEP(I,JMAX+2) TO COMP SEDIMENT TRANSPORT
9400
9500
               WRITE(6,734)
9600
           734 FORMAT(2X, 'THE BOUNDARY Y-VALUES, I=1, IMAX ARE AS FOLLOWS', /)
9700
               WRITE(6,801)
                               (Y(1,U),U=1,UMAX+2)
9800
               WRITE(6,801)
                               (Y(IMAX,J),J=1,JMAX+2)
9900
               WRITE(6.732)
10000
               WRITE(6,735)
10100
           735 FORMAT(/,2x, 'THE DEPTHS BETWEEN CONTOURS ARE AS FOLLOWS: ,/)
10200
               WRITE(6,801)
                               (DEEP(1,J),J=1,JMAX+2)
10300
               WRITE(6,732)
10400
          801
               FORMAT(2X, 10(F8.2))
10500
               DO 2 I=1, IMAX
10600
               YZERO(I)=Y(I,1)-(BERM/SFACE)
10700
         C*WILL COMPUTE THE EQUIL WIDTH BETWEEN CONTOURS, HERE
10800
               DO 1 I=1, IMAX
10900
               WEQ(I, 1)=Y(I, 1)-YZERO(I)
               DO 1 J=1, JMAX
IF(J NE.1)
11000
11100
                            GO TO 32
11200
               YTEMP 1=0.0
11300
               GO TO 33
11400
               YTEMP1=((0.5*(DEEP(I,J-1)+DEEP(I,J)))/ADEAN)**1.5
11500
               YTEMP2=((0.5*(DEEP(I,J)+DEEP(I,J+1)))/ADEAN)**1.5
11600
               WEQ(I, J+1)=YTEMP2-YTEMP1
11700
               CONTINUE
11800
         C*LET'S STORE THE ORIG VALUES TO COMPUTE VOL CHANGES OVER CONTOURS, LATER
11900
               DO 796 I=1, IMAX+1
               YZEROO(I)=YZERO(I)
12000
12100
               DO 796 J=1, JMAX+2
12200
           796 YORIG(I,J)=Y(I,J)
12300
12400
         C*READ THE DISK FILE AND TRANSFORM PARAMETERS INTO MY UNITS
                 12500
12600
         C+ALL ADJUSTMENTS TO WAVE ANGLE, HEIGHT, CELERITY, GROUP VEL. WILL BE MADE
         C**HERE, AND THRUDUT THE REST OF THE PROG. THEY WILL BE AS IF OCCURRED
12700
12800
         C***AT WDEPTH
           798 READ(5,799,END=1000)
12900
                                      HS.T.ALPWIS
13000
           799 FORMAT(10X,3F6.1)
13100
               NTIMES=1
               NCHECK = NUNIV+NTIMES
13200
               HGEN=0.707107*HS
13300
               SIGMA = TWOPI/T
13400
               G=32 17
CO=G*T/TWOPI
13500
13600
13700
               ELO=CO+T
13800
               IF(T.LE.2.0)
                               GO TO 797
13900
               HCC=0.23
14000
               DO 444 I=2,7
14100
               T2=TC(I)
14200
               IF(T.GT.T2)
                              GO TO 444
               T1=TC(I-1)
14300
               DELTAT=T2-T1
14400
```

```
14500
                DT=(T-T1)/DELTAT
                DTT=(T2-T)/DELT
14600
                HCC=HC(I)*DT+HC(I-1)*DTT
14700
                GO TO 446
14800
           444 CONTINUE
14900
15000
           446 CONTINUE
15100
                IF (HGEN.LT.HCC)
                                  GO TO 797
15200
                ANGGEN=ALPWIS*TWOPI/360
15300
15400
                CALL WVNUM(WDEPTH, T, DUMKK)
         C*ANGGEN, HGEN, CGEN, CGGEN REPRESENT THE WAVE ANGLE, HEIGHT, CELERITY AND
15500
         C**GROUP VEL(RESPECT.) OF THE SPECIFIED WAVE INPUT AT A DEPTH. WDEPTH
15600
15700
                CALL WVNUM(11.0.T, DUMKKK)
                C11=TWOPI/(T*DUMKKK)
15800
15900
                CG11=0.5*C11*(1.+(2.*DUMKKK*11 O/SINH(2 *DUMKKK*11 O)))
16000
                CGEN=TWOPI/(T*DUMKK)
16100
                CGGEN=0 5*CGEN*(1 +(2 *DUMKK*WDEPTH/SINH(2.*DUMKK*WDEPTH)))
16200
                CALL TRANS
16300
           797 IF (NCHECK NE.NUNIV)
                                       NUNIV=NCHECK
16400
           709 GO TO 798
          1000 CONTINUE
16500
16600
                STOP
16700
                FND
16800
16900
                SUBROUTINE TRANS
17000
         C*THIS SUBROUTINE WILL COMPUTE SEDIMENT TRANSPORT
17100
                COMMON/A/ C(60.20), RK(60.20), Y(60.20), DEEP(60.20), ALPHAS(60.20)
17200
                COMMON/AA/YZERO(60)
17300
                COMMON/BB/WEQ(60.20)
                COMMON/B/ THETA(60,20),QXTDT(60), OLDANG(60,20), DY(60,20)
COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
17400
17500
                COMMON/N USED/JUSE, T, CO, CGEN, CGGEN, ANGGEN, DX, BERM, THETAO(10), MMAX
17600
17700
                COMMON/D/SIGMA.G.ELO.JMAX.IMAX.PI.TWOPI.PIO2.HGEN.IJET(10).SJETTY
17800
                COMMON/E/RHO, RHOS, POROS, CONST, TKSI
17900
                COMMON/F/ADEAN, REPOSE, DIAM
18000
                COMMON/G/IBREAK(60), HNONBR(20)
18100
                COMMON/P/HBQ(60), DEEPB(60)
18200
                COMMON/ZZZ/NTIME
                COMMON/AAA/DELT.NTIMES
18300
18400
                COMMON/COUNT/NUNIV
18500
                DIMENSION YOLD(60,20),R(60,20),S(60,20),HC(60,20),QY(60,20),YDISS(
18600
                  60.20)
18700
                DIMENSION RHS1(60,20), S3(60,20), THETAB(60,20), ANGLOC(60,20)
18800
                DIMENSION DISTR(60,20), AWARE(60,20
18900
19000
         C****** NOTE : SIZE OF ABAND AND XL HAVE TO BE CHANGED
19100
19200
                                     ACCORDING TO JMAX+1+JMAX AND JMAX+1, RESPECT
19300
                                     CHANGE REQ'D AT 7040 AND 18650
19400
19500
               * ).BMATRX(432),ABAND(432,19),QX(60,20),XL(432,10),CONST6(60.20)
19600
                COMMON/MP/ RKB(60), HBI(60), DEEPBI(60)
                COMMON/EXPL/QYEXP(60,20), YIMP(60,20)
19700
19800
                DIMENSION SANGLE (20)
19900
         C*LET'S ZERO-OUT ALL OF THE DIMENSIONED MATRICES
                DO 1000 U=1, JMAX+2
20000
20100
                SANGLE(J)=0.0
20200
                DO 1000 I=1, IMAX+2
20300
                YOLD(1,J)=0.0
20400
                R(I,J)=0.0
20500
                S(I,J)=0.0
                HC(1,J)=0.0
20600
                0.0=(U,1)YO
20700
20800
                YDISS(I,J)=0.0
20900
                RHS1(I,J)=0.0
21000
                53(I,U)=0.0
21100
                THETAB(I,J)=0.0
21200
                ANGLOC(I,J)=0.0
21300
                DISTR(I,J)=0.0
21400
                AWARE(I,J)=0.0
21500
                QX(I,J)=0.0
                CONSTG(I,J)=0 0
21600
```

```
21700
            1000 CONTINUE
21800
                 RHO≈1 99
                 RHOS=5 14
21900
22000
                 POROS=0 40
22100
                 CONST = 0 17
22200
                 CAPPA=0.78
22300
                 TAU=0 25
          TKS1=(CONST*RHO*SQRT(G))/((RHOS-RHO)*(1.0-POROS)*16.0*SQRT(CAPPA)
C* QX(I,U) IS THE TRANSPORT BETWEEN THE (I,U+1) AND (I,U) CONTOURS.
22400
22500
          C*THE 'DO 1 LOOP' SIMULATES TIME---TIME DELT*NTIMES.
22600
                 COFF = 0.00001
22700
22800
                 GAMMA=RHO+G
22900
                 DO 1 NTIME = 1, NTIMES
23000
                 NUNIV-NUNIV+1
23100
          C*THE MATRICES ABAND AND BMATRX MUST BE "ZEROED OUT"
23200
                 K = 0
23300
                 DO 26 I=2, IMAX-1
                 DO 26 U=1, JMAx
23400
23500
23600
                 BMATRX(K)=0 0
23700
                 DO 26 L=1.JMAX+1+JMAX
                ABAND(K,L)=0 0
23800
23900
                 XNTIME = 1 O*(NTIME)
24000
                 CALL PREDIF
24100
          C*SMOOTHING OF THE WAVE ANGLE, THETA, IS RE'D TO ACCT FOR DIFF EFFECTS.
24200
                 CALL SMOOTH(THETA, IMAX, JMAX, IJET, SUFTTY, MMAX, Y)
                 CALL QTRAN
24300
24400
          C*FIRST THE LONGSHORE SEDIMENT TRANSPORT WILL BE DISTRIBUTED
          C****ACROSS THE SURF ZONE . . .
24500
                 CC=1 25
24600
          C***QX(1,J) WILL BE DETERM! GED BY SUBTRACTING FROM THE INTEGRAL
24700
          C . OF QX FROM DEEP(I, J-1) TO INFINITY, THE INTEGRAL OF QX FROM DEEP(I, J)
24800
          C. TO INFINITY. IN THIS WAY THE SEDIMENT TRANS FROM JMAX OUT GETS C. TO INCLUDED IN QX(I,JMAX). TO INCLUDE THE SWASH TRANS, WHEN J=1 C. WE WILL SUBTRACT FROM 2 TO INFINITY FROM 1.0
24900
25000
25100
25200
          C-LOOP FOR VALUES WHICH ARE HELD CONST AND STORED
                 THETAB(1,1)=0.5*(THETA(1,1)+0.0)
25300
                 R(1,1)=0.5/(DX+(DEEP(1,1)+BERM/2 ))
25400
25500
                 DO 290 I=2. IMAX
25600
                 R(I,1)=0.5/(DX*(DEEP(I,1)+BERM/2.))
25700
          C *
                 THETAB(1,1)=0.25*(THETA(1,1)+THETA(1-1,1)+0.+0)
25800
                 THETAB(1,1)=0.5*(THETA(1,1)+THETA(1-1,1))
          C+NO NEED TO COMPUTE PROP ANGLE AT STRUCTS BECAUSE QX =0.0 AT IJET(M)+1
25900
26000
                 ANGLOC(I, 1) = ATAN((Y(I, 1) - Y(I - 1, 1))/DX)
          C+HBQ(IJET(M)+1) IS PROPERLY SET IN THE SUBROUTINE QTRAN.
26100
26200
                DISTR(1,1)=1.0-EXP(-((DEEP(1,1)**1.5+HBQ(1)*ADEAN**1.5)/
26300
                    (CC*DEEPB(I)**1 5))**3)
26400
                 DISTR(I,1)=DISTR(I,1)+TKSI+HBQ(I)++2.5
26500
                 DO 290 J=2,JMAX
                 R(I,J)=0 5/(DX+(DEEP(I,J)-DEEP(I,J-1)))
26600
26700
                 THETAB(I.J)=0 5*(THETA(I.J)+THETA(I 1.J))
26800
                 ANGLOC(I,J) \approx ATAN((Y(I,J)-Y(I-1,J))/DX)
26900
                 DISTR(I, J) = EXP(-((DEEP(I, J-1)**1.5+HBQ(I)*ADEAN**1.5)/(CC*DEEPR(I)
27000
                    **1 5))**3)-EXP(-((DEEP(I,J)**1.5+HBQ(I)*ADEAN**1.5)/(CC*
27100
                    DEEPB(I)**1 5))**3)
27200
                DISTR(I,J)=DISTR(I,J)+TKS1+HBQ(I)++2.5
27300
            290 CONTINUE
                 DO 301 J=1.JMAX
27400
                 DD 301 I=2, IMAX
27500
27600
                 AWARE(I,J)*DELT*R(I,J)*(QX(I,J)-QX(I+1,J)+QY(I,J)-QY(I,J+1))+Y(I,J)
27700
                S!=2.*SIN(THETAB(I,J))*COS(THETAB(I,J))*(-1.+2.*(COS(
* ANGLOC(I,J)))**2)
27800
27900
28000
                 S2=COS(2.*THETAB(1,J))*COS(ANGLOC(1,J))/(SQRT(DX**2+
28100
                Y(I,J)-Y(I-1,J))**2))
$3(I,J)=$2*DI$TR(I,J)
28200
28300
                 IF(SUETTY EQ.O.O)
                                       GO TO 302
28400
                 DO 325 M=1,MMAX
28500
                 IF(I NE.IJET(M)+1)
                                        GO TO 325
28600
                 IF (THETAD(M) GE O.O) ISIDE = IJET (M)
28700
                 IF (THETAD(M) LT 0.0)
                                           ISIDE = IJET(M)+1
28800
                 YSEA=0.5*(Y(151DE, J)+Y(151DE, J+1))
28900
                 YSHORE=0.5*(Y(ISIDE, J)+Y(ISIDE, J-1))
```

```
IF(YSEA GT SUETTY AND.YSHORE.GT SUETTY)
                                                                                                         GO TO 302
29000
                            IF(YSEA GT SUETTY AND YSHORE LE SUETTY)
                                                                                                         GO TO 298
29100
                C.BECAUSE & NO FLOW B C IS USED ALUNG THE STRUCT, NO ATTN WAS PAID
29200
                C ** TO GETTING PROPER VALUES OF ANGLOC, THETAB, DISTR. ETC
29300
29400
                            S3(1,J)=0 0
                            DISTR(I,J)=0 0
29500
29600
                            GO TO 302
29700
                    325 CONTINUE
29800
                            GO TO 302
                C***ABOVE, ALL PARAMETERS(I E .S1,S2.S3,THETAB,DISTR,ANGLOC)
C***ARE COMPUTED AS IF THE STRUCT IS NOT THERE THE B C AT THE
C***STRUCT TIP ASSUMES QX COMPUTED AS IF NO STRUCT PRESENT AND THEN
29900
30000
30100
                C***BYPASSES ACCORDING TO "RATIO"
30200
30300
                    298 RATIO=(YSEA-SJETTY)/(YSEA-YSHORE)
30400
                            O1749.([,1]E2=([,1]E3
30500
                            DISTR(I, J) = DISTR(I, J) * PATIO
                    302 RHS1(I,J)*DISTR(I,J)*S1-S3(I,J)*(Y(I,J)-Y(I-1,J))
30600
30700
                           CONTINUE
30800
                            CALL BREAK (IMAx, JMAx)
30900
                C*TO DETERMINE DECAY OF CONSTG(I,J) NEED WAVE NO. AT BREAKING.
31000
                            DO 754 I=1, IMAX+1
31100
                    754 CALL WVNUM(DEEPBI(I), T, RKB(I))
31200
                C*USING SHIELD'S DIAG,Y AXIS=0 05 & (TAU0=RHD*C*U**2),GET UCRIT(FT/SEC)
                           UCRIT=16 3*SQRT(DIAM* .00328)
31300
31400
                            DO 750 I=1, IMAX+1
31500
                            CONSTG(I, 1)=COFF+DX
31600
                           DO 750 J=2.JMAX+2
                c *CONST6(I, J) GDES W/ QY(I, J) WHICH IS ASSOC W/ DEEP(I, J-1)
31700
                IF(DEEP(I,U-1) LE DEEPBI(I)) GO TO 751
C+HERE MUST CAUSE COFF TO DECAY (WE'RE BEYOND SURF ZONE)
31800
31900
32000
                            UMAXB=HBI(I)*G*T*RKB(I)/(2.*TWOPI*COSH(RKB(I)*DEEPBI(I)))
32100
                            UMAX=H([, U-1)*G+T+RK([, U-1)/(2 *TWDPI+COSH(RK([, U-1)*DEEP([, U-1)))
32200
                            IF(UCRIT LT UMAY AND UCRIT LT UMAXB) GO TO 749
32300
                            CONST6(I, J)=0.0
32400
                            GO TO 750
32500
                    749 TOP=0 01*H(I,J-1)**3*SIGMA**3/(SINH(RK(I,J-1)*DEEP(I,J-1))**3)
                           BOT = DEEP(I, J-1)*(0 625+TWOPI*G**1 5*0.78**2*ADEAN**1.5+
32600
                          *(O O1*HBI(I)**3*SIGMA**3/(DEEPBI(I)*(SINH(RKB(I)*DEEPBI(I)))**3)+)
32700
32800
                           CONST6(I,J)=DX+COFF+TOP/BOT
32900
                            GO TO 750
33000
                    751 CONSTG(I, J)=COFF+DX
33100
                    750 CONTINUE
33200
                            K = 0
33300
                C**PUT INTO BANDED FORM USING THE ALGORITHM A(M,N)->B(M,NN) WHERE
33400
                C *** NN = KB + 1 M + N(KB IS THE NUMBER OF LOWER CODIAGONALS (= JMAX, HERE))
33500
                           DO 304 I=2, IMAX-1
33600
                            DO 304 J=1, JMAX
33700
                           K = K + 1
                            \texttt{AWARE(I,J)*RHS1(I,J)*R(I,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,J)*RHS1(I+1,
33800
33900
                                 )+DELT*R(I.J)*CONSTG(I.J)*WEQ(I.J)-DELT*R(I.J)*CONSTG(I.J+1)*
34000
                                 WEQ(1, J+1)
34100
                            YDUM=YZERO(I)
34200
                            IF(U NE.1)
                                                   YDUM=Y(1,J-1)
                            AWARE(I, J) = AWARE(I, J) + DELT + R(I, J) + CONST6(I, J) + O.5 + (YDUM - Y(I, J))
34300
                                 -DELT+R(I,J)+CONST6(I,J+1)+0.5*(Y(I,J)-Y(I,J+1))
34400
                           U=DELT*R(I,J)*S3(I,J)
34500
                            V=DELT*R(I,J)*S3(I+1,J)
34600
34700
                            71=DELT*R(I,J)*CONST6(I,J)*0.5
34800
                            Z2=DELT*R(I,J)*CONST6(I,J+1)*0.5
34900
                C*NOW WILL SET UP THE MATRICES ABAND AND BMATRX.
35000
                            ABAND (K, JMAX+1)=1.0+U+V+Z1+Z2
35100
                            IF(I.NE.2)
                                                 GD TO 305
35200
                            AWARE(I,J) = AWARE(I,J) + U + Y(I-1,J)
35300
                            GO TO 310
35400
                    305 ABAND(K, 1) = -U
                    310 IF(I.NE.IMAX-1)
35500
                                                            GO TO 306
                            AWARE(I,J) = AWARE(I,J) + V + Y(IMAX,J)
35600
35700
                            GO TO 311
                    306 ABAND(K, JMAX+1+JMAX)=-V
35800
35900
                    311 IF(U NE 1)
                                                 GO TO 307
                            ABAND(K, JMAX+1) = ABAND(K, JMAX+1)-Z1
36000
36100
                            AWARE(I,1) = AWARE(I,1)+Z1*(YZERO(I)-Y(I,1))
36200
                            GO TO 312
```

```
307 ABAND(K, JMAX) -- Z1
312 IF(J NE JMAX) GO TO 308
36300
36400
                AWARE(I,J)=AWARE(I,J)+Z2*Y(I,JMAX+1)
36500
36600
                GO TO 309
36700
            308 ABAND(K.JMAX+2) = - Z2
36800
            309 BMATRX(K)=AWARE(I,J)
36900
            304 CONTINUE
37000
                KMAX=K
         C**CALL IMSL ROUTINE LEQTIB TO SOLVE THE BANDED MATRIX.
37100
                CALL LEGTIB (ABAND, KMAX, JMAX, JMAX, 432, BMATRX, 1, 432, O, XL, IER)
37200
37300
         C*NOW, GIVE Y'S THEIR NEW VALUES STORING OLD VALUES IN YOLD.
                K=0
37400
37500
                DO 315 I=2, IMAX-1
                YOLD(I, JMAX+1)=Y(I, JMAX+1)
37600
37700
                DO 315 J= 1. JMAX
37800
                K=K+1
37900
                (U, I)Y=(U, I)DJOY
                Y(I,J)=BMATRX(K)
38000
            315 CONTINUE
38100
38200
                DO 320 J=1, JMAX+3
38300
                YOLD(1,J)=Y(1,J)
            320 YOLD(IMAX,J)=Y(IMAX,J)
38400
38500
         C+WILL USE ABBOTT'S DISSIPATIVE INTERFACE TO RID HIGH FREQ OSCILLATIONS
                DO 650 J=1,JMAX

DO 650 I=2,IMAX-1

YDISS(I,J)=TAU*Y(I-1,J)+(1.-2.*TAU)*Y(I,J)+TAU*Y(I+1,J)
38600
38700
38800
                IF(SUETTY.EQ.O.O)
                                     GO TO 650
38900
39000
                DO 649 M=1,MMAX
39100
                IF(I NE.IJET(M).AND.I.NE.IJET(M)+1)
                                                         GO TO 649
39200
                IF(Y(IJET(M), J).GT.SJETTY.OR.Y(IJET(M)+1, J).GT.SJETTY)GO TO 649
39300
                IF(I.EQ.IJET(M))YDISS(I,J)=TAU*Y(I-1,J)+(1,-TAU)*Y(I,J)
39400
                IF(I.EQ.(IJET(M)+1))YDISS(I,J)=TAU+Y(I+1,J)+(1.-TAU)+Y(I,J)
39500
            649 CONTINUE
39600
            650 CONTINUE
39700
                DO 651 J=1, JMAX
DO 651 I=2, IMAX-1
39800
39900
            651 Y(I,J)=YDISS(I,J)
40000
          C*THIS LOOP WILL STORE THE IMPLICIT Y VALUES REQ'D TO COMP QY&QX
                DO 40 I=1, IMAX+1
40100
40200
                DO 40 J=1, JMAX+3
               (L,I)Y=(L,I)
40300
         C*THIS LOOP WILL EXPLICITLY MOVE CONTOURS SEAWARD IF REPOSE EXCEEDED.
40400
                KOUNT = O
40500
                SLOPEM=TAN(O 9*REPOSE)
40600
40700
                DO 48 I=1, IMAX
40800
            43 KOUNT = KOUNT + 1
40900
                                       GO TO 41
                IF(KOUNT GT.50000)
         C*LET US COMPUTE ALL THE SLOPES(PSLOP) FOR EACH CHANGE IN DEPTH.
41000
                DO 47 J=1, JMAX+1
41100
                DUM=-BERM/2.0
41200
                              DUM=DEEP(I,J-1)
                IF(J.NE 1)
41300
                DELH=0.5*(DEEP(I,J+1)+DEEP(I,J))-0.5*(DEEP(I,J)+DUM)
41400
41500
                PSLOP=DELH/(Y(I,J+1)-Y(I,J))
                SANGLE(J)=ATAN(PSLOP)
41600
41700
         C*FIND THE MIN NEG SLOPE ANGLE OR THEN THE POS SLOPE>REPOSE OR FORGET IT
41800
                ASLOPM=-1 OE50
                ASLOPP=0.0
41900
                DO 46 J=1, JMAX+1
IF(SANGLE(J) GT 0.0)
42000
                                         GO TO 45
42100
                IF(SANGLE(J) GT ASLOPM)ASLOPM=SANGLE(J)
42200
42300
                IF(ASLOPM.EQ.SANGLE(J))
                                            ل≃Mل
42400
                GO TO 46
42500
                IF(SANGLE(J).GT.REPOSE.AND.SANGLE(J).GT ASLOPP)ASLOPP=SANGLE(J)
42600
                IF(ASLOPP.EQ.SANGLE(J))
42700
            46 CONTINUE
                IF(ASLOPM.EQ. -1.0E50.AND.ASLOPP.EQ.O.0)
42800
                                                              GO TO 42
                IF (ASLOPM.EQ. -1.0E50)
                                          GO TO 44
42900
                DUM=-BERM/2.
43000
43100
                IF(UM.NE.1)
                               DUM=DEEP(I,JM-1)
                ALTER=((O.5/SLOPEM*(DEEP(I,JM+1)-DUM))-(Y(I,JM+1)-Y(I,JM)))/
(1.0+((DEEP(I,JM+1)-DEEP(I,JM))/(DEEP(I,JM)-DUM)))
43200
43300
43400
                Y(I,JM+1)=Y(I,JM+1)+ALTER
```

1

ţ 1

```
43500
                Y(I,JM)=Y(I,JM)-(ALTER*(DEEP(I,JM+1)-DEEP(I,JM))/(DEEP(I,JM)-DUM))
43600
                QYEXP(I,JM+1)=QYEXP(I,JM+1)+DX/DELT+ALTER+(DEEP(I,JM+1)-DEEP(I,JM)
43700
                GO TO 43
43800
43900
              CONTINUE
44000
                DUM=-BERM/2.
44100
                IF(JP.NE.1)
                              DUM=DEEP(I,JP-1)
                ALTER=((O.5/SLOPEM*(DEEP(I,JP+1)-DUM))-(Y(I,JP+1)-Y(I,JP)))/
44200
                  (1.0+((DEEP(I,JP+1)-DEEP(I,JP))/(DEEP(I,JP)-DUM)))
44300
44400
                Y(I,JP+1)=Y(I,JP+1)+ALTER
44500
                Y(I, JP)=Y(I, JP)-(ALTER*(DEEP(I, JP+1)-DEEP(I, JP))/(DEEP(I, JP)-DUM))
44600
                QYEXP(I, JP+1)=QYEXP(I, JP+1)+DX/DELT*ALTER*(DEEP(I, JP+1)-DEEP(I, JP)
44700
                GO TO 43
44800
44900
               WEQ(I, JMAX+1)=Y(I, JMAX+1)-Y(I, JMAX)
45000
              CONTINUE
           48
         C*IF WE GET SENT HERE, LOOP 444 WILL CATCH THE CROSSED CONTOURS.
45100
45200
               CONTINUE
         C*NOW WE CAN COMPUTE QX'S AND QY'S!
45300
45400
                DO 318 I=2, IMAX
45500
         C*ALL IMPLIC AND EXPLIC MOVEMENT OF YZERO WILL BE TAKEN CARE OF HERE
45600
                QY(I,1)=-BERM*DX*(Y(I,1)-YOLD(I,1))/DELT
45700
                YZERO(I)=YZERO(I)+(Y(I,1)-YOLD(I,1))
45800
           319 DO 318 J=1, JMAX
45900
                QX(I,J)=RHS1(I,J)-S3(I,J)+YIMP(I,J)+S3(I,J)+YIMP(I-1,J)
           318 QY(I,U+1)=CONSTG(I,U+1)*(0.5*(YIMP(I,U)+YOLD(I,U)-YIMP(I,U+1)
46000
46100
                   -YOLD(I,J+1))+WEQ(I,J+1))
                DO 323 J=1, JMAX
46200
46300
                QX(1,J)=QX(2,J)
46400
           323 QX(IMAX+1,J)=QX(IMAX,J)
46500
         C*TOTAL QYS WILL BE COMP FROM IMPLIC AND EXPLIC VALUES.THEN ZERO QYEXP
                DO 39 I=1, IMAX+1
46600
46700
                DO 39 J=1, JMAX+3
46800
                 QY(I,J)=QY(I,J)+QYEXP(I,J)
46900
               QYEXP(I,J)=0.0
         C*THIS CHECK WILL BOMB THINGS OUT IF CONTOURS HAVE CROSSED.
47000
                DO 444 II=1, IMAX
47100
                DO 444 JJ≈1,JMAX
47200
47300
         C*IF CONTOURS CROSS AT ANY TIME WANT PROGRAM TO STOP!
47400
                IF(Y(II,JJ).LT.Y(II,JJ+1))
                                             GO TO 444
47500
                WRITE(6, 103)
                WRITE(6,*/)
                              NUNIV
47600
               DO 150 J=1, JMAX
47700
           150
                  WRITE(6, 100)
                                  (QX(I,J), I=1, IMAX)
47800
47900
               DO 151 J=1, JMAX
                  WRITE(6, 101)
48000
                                  (QY(I,J),I=1,IMAX)
48100
               DO 152 J=1, JMAX
                  WRITE(6, 100)
48200
            152
                                  (XAMI, l=1, IMAX)
            103 FORMAT(2X, 'THE CONTOURS HAVE CROSSED AND SOMETHING IS WRONG', /)
48300
48400
                DO 19 J=1, JMAX
48500
             19 WRITE(6, 100) (YOLD(I, J), I=1, IMAX)
48600
                GO TO 445
48700
           444 CONTINUE
48800
                WRITE(6,*/)
                              NUNTV
         C+THE FOLLOWING STATEMENT DETERMINES AT WHAT FREQ EVERYTHING IS WRITTEN'
48900
49000
                IF(MOD(NUNIV, 10).NE.O)
                                          GO TO 1
         C*LET'S WRITE ALL OF IT OUT.
WRITE(6,926) NUNIV
49100
49200
          926 FORMAT(2X, THE TOTAL ELAPSED NUMBER OF TIME-STEPS. NUNIV= ', 15, /) 800 FORMAT(2X, 14(F8.4))
49300
49400
                 DO 900 I=1, IMAX
49500
         C*
                                (XAMU, 1=U, (U, I)AT3HT)
49600
         C*900
                 WRITE(6,800)
                 DO 903 J=1, JMAX+1
49700
         C*
49800
         C*903
                 WRITE(6,801)
                                DEEP(1,J)
                 DO 906 I=1, IMAX
49900
         C*906
                 WRITE(6,800)
                                (XAMU, F≠U, (U, I)H)
50000
50100
                DO 755 J=1, JMAX
         C*755 WRITE(6,800) (CONST6(1,J), I=1, IMAX)
50200
          801 FORMAT(2X, 14(F8.2))
50300
                WRITE(6, 107)
50400
            107 FORMAT(/,2X, 'THE LONGSHORE TRANSPORTS.QX, FOLLOW')
50500
                DO 15 J=1, JMAX
50600
50700
            15
                 WRITE(6,100)
                                 (XAMI, l=I, (U, I)XQ)
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ij

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8116143
                             wellten, tont
                     TOR FORMATTING THE ON OFFSHORE TRANSPORTS OF FOLLOW T
BURNIE
                            FAMIL FELL TE DIT
Blinks
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                              W#11116 1011
                                                            tgs(1 a).1-1 1MA+1
B 12(%)
                             14411 A) 1114W
8 1 HR1
                      tow formatt ge top New Contour Values a follow b
B 14(N)
                            DO 18 0-1 0MA1
B 18(4)
                             WHITE GITTEN
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                     113(1
                              FORMAT( # 11(F# 11)
91700
                     101 FORMATION 11(FB 41)
9.18(%)
                            CONTINUE
                             WE TUWN
6 I Micks
BAINE
                             00 10 44a
821(Y)
                     446 $100
#33(K)
                     446 CONTINUE
43 HA1
                            t NO
                                                            4141
41041
                            RUBBOUT INE GIBAN
                 CONTROL SUMMOUSTINE CALCE THE RHEAVER HELDHS FOR FACH.
CONTROL SUMS LINES METHOD FINIS VIDIALIONS RECORD AND AFTER
COMBANING HAS DICTURED BY BEFRAC. THEN USES SHOALING TO GET THE
6 Jaimi
Ballins
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628(N)
BREE
631(X)
                            COMMONIA CLASSIAN RELACES DE VIGO 201 DEFPLAS 201 ALPHANIAS, 201
                             COMMONSANTEROLGOS
6.33(%)
93300
                            COMMONIA THETA(60,20), QATOTIGOT DIDANGIGO 201, DATGO 201
                            COMMON-C-HEGO 201 CREGO 201 NOLDEG 201 HBEGO 201 VBEGO)
COMMON, N. UNED-JUNE T. CO., CGEN., CGGEN. ANDGEN DN. BERM. THETADE FOLLOMAN
6 14(3)
6 1000
                             ETTICE COLITICE MAIN SOLL SOLL LACE THE FAMIL OLI D. AMPLE O MOMOO
S Shint
                             8 17(W)
                             COMMON/F WHO , NING PORDS, CONST. THE!
5 16(V)
6 1000
                             COMMONITY INDUSTRIAL STREET
BACKET
                             CAPPA-O 78
84 1(¥)
                             00 1 1-3, IMA
942(4)
                             J.JMAS JUST
64 NX
644(4)
                            # OFFICE, F. FIRECO., FILE, FILE,
949(30)
                            a coefficie e franceiti, franceimonocomorphie
BAGINT
                 CHEAN ONLY DEE COND ON ONE STOP OF STRUCT CAN T AVO HERE!
647(%)
                             triburity by o of on to 4
248(%)
                             DO 4 M=1 MMA+
14 4 (N)
                             trit NE taet(Missi
                                                                     00 10 4
                             IFITHE LADIM OF O OL ISIDE - LIETUM
CHHIDD
56 1(K)
                             IF ( THE TABIMI IT IT IT
                                                                         16101-14-16101-1
                                 AT STRUCT THE ASSIMES UN COMP AS IF NO STRUCT IS PRESENT
thish
                 . . . . .
                             TITLE SOLDITARIE SOLDITATION O-ASPA
88 100
884IVI
                             IFENSEN GT SUPTENT
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                            HD(M=H(1510E, J)
CKIERR
BBBIN
NR PINT
                             60 to 1
hhairs.
                            CONTINUE
BBBOX
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BRISSI
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56 1(N)
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BEZINI
                            IMO(1)-CAPPA BEFPR(1)
86 100
                 CTMQ(1) AND DEFMEEL WILL BE COMMUTED ACCOMMUNATO THE WAVE DIN
864(x)
                 C. AT THE STRUCTURE TIP THETAG
MARINI
                             If Chaffly to o of
                                                                 60 10 1
RESINI
                            DO 6 M. I. MMAY
56 2(N)
                                                                     00 10 6
                             If ( I NE | JET(M)+1)
-
                 CTITIE TRANSPORTING WAVES WILL BE COMPUTED USING THE WAVE IN PROPERTIES
....
                             If the table of o of the el
                             DEFPREEN-CHEELIE CONTENTE CONTE CONTENTE CONTENTE CONTENTE CONTENTE CONTENTE CONTENTE CONTENT
BILWES
Aften
                             6 f Jimi
                             60 10 12
BIHN
                            9 74(H)
                             180 C 4 M 1 1 - 1 M 4 F AM ( 1, IF 1 ( M ) )
BIBINI
                            IMQLII-DEEPRLIISCAPPA
& facus
                             00 10 1
REFIN
                            COMIT I MALE
5 /8(x)
                             00 10 1
6.78(W)
                            CONTINUE
BB(XX)
                             ( ONT I NUE
```

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58100
         C*IF THE OFFSHORE WAVE HT IS ZERO, NEVER GET TO HERE
58200
         C+HOWEVER IF THE H IS SUCH THAT IT WOULD BREAK INSHORE OF Y(1,2)
58300
         C*DEEPB(I) WOULD STILL BE ZERO AND DISTR(I,J) WOULD BLOW-UP
58400
                DO 20 I=1. IMAX
58500
                IF(DEEPB(I).GT.O.O)
                                      GO TO 20
                DEEPB(I)=(H(I,1)*DEEP(I,1)**0.25/CAPPA)**0.8
58600
                HBQ(I)=CAPPA*DEEPB(I)
58700
58800
               CONTINUE
58900
                HBQ(1)=HBQ(2)
59000
                HBQ(IMAX+1)=HBQ(IMAX)
59100
                DEEPB(1)=DEEPB(2)
                DEEPB(IMAX+1)=DEEPB(IMAX)
59200
59300
                RETURN
59400
                FND
59500
59600
                SUBROUTINE BREAK (IMAX, JMAX)
59700
         C*ROUTINE WILL DETERMINE HB AND DEEPB ON THE GRID LINES RATHER
59800
             THAN BETWEEN THEM. REQ'D FOR COFF BEYOND SURF ZONE
59900
                COMMON/A/ C(60,20), RK(60,20), Y(60,20), DEEP(60,20), ALPHAS(60,20)
60000
                COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
                COMMON/MP/ RKB(60), HBI(60), DEEPBI(60)
60100
60200
                CAPPA=0.78
60300
                DO 1 I=2, IMAX
60400
                DO 2 JJ=1, JMAX
60500
                J=JMAX-JJ+1
60600
                IF(H(I,J).LT.HB(I,J)) GO TO 2
                DEEPBI(I)=((H(I,J+1)*DEEP(I,J+1)**0.25)/CAPPA)**0.8
60700
60800
                HBI(I)=CAPPA*DEEPBI(I)
60900
         C***ONCE THE HEIGHT & DEPTH AT BREAKING ARE FOUND, GO TO NEXT GRID-LINE.
61000
                GO TO 1
                CONTINUE
61100
61200
                CONTINUE
61300
               DO 20 I=1, IMAX
61400
                IF(DEEPBI(I).GT.O.O)
                                        GO TO 20
61500
                DEEPBI(I)=(H(I,1)*DEEP(I,1)**0.25/CAPPA)**0.8
61600
               HBI(I)=CAPPA*DEEPBI(I)
61700
               CONTINUE
61800
                DEEPBI(1)=DEEPBI(2)
                DEEPBI(IMAX+1)=DEEPBI(IMAX)
61900
62000
                HBI(1)=HBI(2)
62100
                HBI(IMAX+1)=HBI(IMAX)
62200
                RETURN
62300
                END
62400
                SUBROUTINE REFRAC(JBEGIN, JEND, NPTS, IBEGIN, IEND, 1START, M)
62500
62600
                CDMMON/A/ C(60.20), RK(60.20), Y(60.20), DEEP(60.20), ALPHAS(60.20)
                COMMON/AA/YZERO(60)
62700
                CDMMON/B/ THETA(60,20),QXTOT(60), OLDANG(60,20), DY(60,20)
COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
62800
62900
63000
                COMMON/N USED/JUSE, T, CO, CGEN, CGGEN, ATIGGEN, DX, BERM, THETAO (10), MMAX
63100
                COMMON/D/SIGMA, G, ELO, JMAX, IMAX, PI, TW JPI, PIO2, HGEN, IJET(10), SJETTY
63200
                COMMON/G/IBREAK(60), HNONBR(20)
63300
                COMMON/ZZZ/NTIME
63400
                DIMENSION JBEGIN(60), JEND(60)
                                                THIS SUBROUTINE WILL DETERMINE H AND
63500
                                                THETA AT THE MID PT OF Y VALUES.
63600
         C***TAU IS THE FACTOR WHICH RECOUPLES THE REFRACTION EQS. SEE ABBOTT
63700
63800
                TAU=0.25
63900
         C+MUST PRESCRIBE THE WAVE ANGLE AT THE OUTERMOSTCONTOUR BOX
64000
         C*SNELL'S LAW WILL BE USED TO START THINGS OFF
         C+THETA(I,J) WILL BE AT AREA'S CENTER AND WILL USE Y(I,J) IN NEG Y-DIR
64100
         C*WILL INITIALIZE ALL THETA'S USING SNELL'S LAW.
64200
                DO 206 I=IBEGIN, IEND
64300
         C*INITIALIZE TWO J-VALUES BEYOND JMAX, IF IN REGION 1.
64400
64500
                IF(JEND(I).EQ.JMAX)
                                       JINIT=2
                IF(JEND(I).NE.JMAX)
                                       JINIT=0
64600
                DO 206 J=JBEGIN(I), JEND(I)+JINIT
64700
64800
         C+MUST CORRECT FOR THE CONTOUR ORIENTATION, ALPHAS.
64900
                IF(I.NE.IBEGIN)
                                   GO TO 960
                ALPHAS(I,J)=ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1))-0 5*(Y(I,J)
65000
65100
               + +Y(I,U+1)))/DX)
                GO TO 962
65200
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65300
            960 IF(I.NE.IEND) GO TO 961
65400
                ALPHAS(I, J) = ATAN((0.5*(Y(I, J)+Y(I, J+1))-0.5*(Y(I-1, J))
                 +Y(I-1,U+1)))/DX)
65500
65600
                GD TD 962
            961 ALPHAS(I,J)*ATAN((0.5*(Y(I+1,J)+Y(I+1,J+1))-0.5*
65700
65800
                 (Y(I-1,J)+Y(I-1,J+1)))/(2.*DX))
            962 DALPHA=ANGGEN-ALPHAS(I,J)
65900
66000
                THETA(I,J )=ARSIN((C(I,J )/CGEN)*SIN(DALPHA))
          C+MUST GET THETA WRT THE X-AXIS
66 100
66200
                THETA(I,J)=THETA(I,J)+ALPHAS(I,J)
66300
            206 CONTINUE
66400
          C*NOW, WE MUST COMP THE BOUN WAVE HTS SO THE HTS CAN BE COMPUTED
66500
          C*WILL USE THE EQ. ******
                                      DEL DOT (E*CG)=O.O
66600
          C+NOW WE WILL CORRECT THE HT FOR SHOALING AND REFRACTION TO THE B C
66700
          C+WILL ALSO INITIALIZE H'S WITH THESE EQUATIONS FOR ENTIRE ARRAY.
66800
                DO 500 I=IBEGIN, IEND
66900
          C*INITIALIZE TWO J-VALUES BEYOND JMAX IF IN REGION 1.
67000
                IF(JEND(I).EQ.JMAX)
                                       JINIT=2
                IF(JEND(I).NE.JMAX)
67100
                                       JINIT = O
                DO 500 J=JBEGIN(I), JEND(I)+JINIT
67200
67300
                H(I,J)=HGEN*SQRT(CGGEN/CG(I,J))*SQRT(COS(ANGGEN)/COS(THETA(I.
67400
                  J)))
67500
                IF(HB(I,J),LT,H(I,J)) = H(I,J)*HB(I,J)
67600
           500 CONTINUE
67700
          67800
67900
          C*LET'S FILL THE DY ARRAY.
68000
         C*DY WILL BE INDEXED AS THE THETA TO WHICH WE ARE GOING.
68100
               DO 209 I=IBEGIN, IEND
                DO 209 J=JBEGIN(1)+1,JEND(1)
68200
68300
                DY(I,J-1)=0.5*(Y(I,J-1)+Y(I,J))-0.5*(Y(I,J)+Y(I,J+1))
68400
              CONTINUE
68500
                NITERS=100
68600
                DO 100 NITER=1, NITERS
68700
                SUMANG=0.0
         C*DO "60 LOOP" GOES FROM 2 TO IMAX IF ISTART = IBEGIN C*DO "60 LOOP" GOES FROM IMAX-1 TO 1 IF ISTART=IEND
68800
68900
69000
               DO 60 II=IBEGIN, IEND
69100
         C*MUST HAVE IT SET UP SO THAT THE KNOWN BOUNDARIES ANGLES AREN'T RECOMP
69200
                IF (ISTART . EQ . IBEGIN)
                                       I = I I
69300
                IF(ISTART.EQ.IBEGIN .AND.
                                            I.EQ.IBEGIN)
                                                            GO TO 60
               IF(ISTART.EQ.IEND) I=IEND-II+IBEGIN
IF(ISTART.EQ.IEND AND I.EQ.IEND)
69400
69500
                                                        GO TO 60
69600
         C*ADX EQUALS ACTUAL DELTA X ACROSS SPACE STEP
69700
         C*ONLY ON BOUNDARIES WHERE FORWARD OR BACKWARD DIFFERENCING.
69800
               IF(I.NE.IBEGIN)
                                 GO TO 6
69900
                ADX=DX
70000
                IP=I+1
70100
               IM=I
70200
               GD TO 12
70300
               IF(I.NE.IEND)
                                GO TO 10
70400
               ADX = DX
70500
               IP=I
70600
               IM≈ I - 1
70700
               GO TO 12
70800
          10
               ADX = 2.0*DX
70900
               IP=I+1
71000
               IM=1-1
71100
                CONTINUE
71200
               DO 40 J=JBEGIN(I).JEND(I)-1
71300
         C*WILL GO FROM (JMAX-1) TO 1 BECAUSE THAT'S THE DIR WAVE COMES IN FROM
71400
                JJ=JEND(I)-1-J+JBEGIN(I)
71500
               OLDANG(I,JJ)=THETA(I,JJ)
71600
         C*LOCATE MIDPOINT BETWEEN TWO ADJACENT BLOCK CENTERS
         C*BECAUSE THETA'S JJ-VALUE IS THE SAME AS THE FIRST SHOREWARD Y VALUE
71700
71800
         C*MUST USE JJ, JJ+1, AND JJ+2 TO COMPUTE YBAR
71900
               YBAR=0.25*(Y(I,JJ)+2.0*Y(I,JJ+1)+Y(I,JJ+2))
         C+LOCATE APPROPRIATE INDICES ON IP AND IM GRID LINES
72000
72100
               IMINUS = - 1
72200
               IPLUS*+1
72300
               CALL LOC(IM, JJ, JOIM, JSIM, YBAR, IMINUS)
72400
               CALL LOC(IP, JJ, JOIP, JSIP, YBAR, IPLUS)
         C*NOW USE THE CONSERVATION OF WAVES EQUATION ....
72500
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72600
                PART 1C=RK(I, JJ+1)*SIN(THETA(I, JJ+1))
72700
                PART2=-DY(I,JJ)/ADX
         C*WILL LINEARLY INTERPOLATE TO DETERMINE RK*COS(THETA) AT I+1 AND I-1.
72800
         C*IF NO ADJ SHOREWARD PT EXISTS, PUT IN ZERO FOR TERMS IN GOV. EQ.
72900
                IF(JSIM.NE.O)
73000
                                GO TO 301
73100
                PART3B=0.0
73200
                GO TO 302
73300
            301 TOPIM=RK(IM, JOIM-1)+COS(THETA(IM, JOIM-1))
73400
                BOTIM=RK(IM, JSIM) +COS(THETA(IM, JSIM))
                TOTALB=0.5*(Y(IM, JOIM)+Y(IM, JOIM-1))-0.5*(Y(IM, JSIM+1)+Y(IM, JSIM))
73500
73600
                DUMB=O.5*(Y(IM, JOIM)+Y(IM, JOIM-1))-YBAR
                PART3B=((TOTALB-DUMB)+(TOPIM-BOTIM)/TOTALB)+BOTIM
73700
73800
            302 IF(JSIP.NE.O)
                                GD TO 303
73900
                PART3A=0.0
74000
                GO TO 304
74100
            303 TOPIP=RK(IP, JOIP-1)*COS(THETA(IP, JOIP-1))
74200
                BOTIP=RK(IP, JSIP) + COS(THETA(IP, JSIP))
                TOTALA=0.5*(Y(IP, JOIP)+Y(IP, JOIP-1))-0.5*(Y(IP, JSIP+1)+Y(IP, JSIP))
74300
74400
                DUMA=0.5*(Y(IP,JOIP)+Y(IP,JOIP-1))-YBAR
                PART3A=((TOTALA-DUMA)*(TOPIP-BOTIP)/TOTALA)+BOTIP
74500
           304 PART3=PART3A-PART3B
74600
74700
         C*NOW MUST FIND RK*SIN(THETA) FOR I+1 AND I-1 AT J+1
74800
                YBARP=0.25*(Y(I,JJ+1)+2.*Y(I,JJ+2)+Y(I,JJ+3))
74900
                CALL LOC(IM, JJ+1, JPOIM, JPSIM, YBARP, IMINUS)
75000
                CALL LOC(IP, JU+1, JPOIP, JPSIP, YBARP, IPLUS)
IF(JPSIM.NE.O) GO TO 305
75100
75200
                PART 1B=0.0
75300
                GO TO 306
75400
            305 TOPM=RK(IM.JPOIM-1)*SIN(THETA(IM,JPOIM-1))
                BOTM=RK(IM, JPSIM) +SIN(THETA(IM, JPSIM))
75500
75600
                TOTB=0.5*(Y(IM, JPOIM)+Y(IM, JPOIM-1))-0.5*(Y(IM, JPSIM+1)+
75700
                   Y(IM, JPSIM))
                DUMPB=O.5*(Y(IM, JPOIM)+Y(IM, JPOIM-1))-YBARP
75800
75900
                PART 1B=((TOTB-DUMPB)*(TOPM-BOTM)/TOTB)+BOTM
76000
            306 IF(JPSIP.NE.O)
                                 GO TO 307
76100
                PART 1A=0.0
76200
                GO TO 308
            307 TOPP=RK(IP, JPOIP-1)+SIN(THETA(IP, JPOIP-1))
76300
76400
                BOTP=RK(IP, JPSIP) *SIN(THETA(IP, JPSIP))
76500
                TOTA=0.5*(Y(IP, JPOIP)+Y(IP, JPOIP-1))-0.5*(Y(IP, JPSIP+1)+Y(IP, JPSIP
76600
76700
                DUMPA=O.5*(Y(IP, JPOIP)+Y(IP, JPOIP-1))-YBARP
                PART 1A=((TOTA-DUMPA)*(TOPP-BOTP)/TOTA)+BOTP
76800
            308 PART1=TAU*PART1B+(1.-2.*TAU)*PART1C+TAU*PART1A
IF(JPSIM.EQ.O)PART1=(1.-TAU)*PART1C+TAU*PART1A
76900
77000
                IF(JPSIP.EQ.O)PART1=TAU+PART1B+(1.-TAU)+PART1C
77100
                ARG=((PART1+PART2*PART3)/RK(I,UJ))
77200
         C*IF THE ROUTINE IS TO BLOWUP, USE SNELLS LAW
77300
77400
                IF(ABS(ARG).LE.1.0)
                                       GO TO 41
77500
                ARG=(C(I,JJ)/C(I,JJ+1))*SIN(THETA(I,JJ+1))
77600
                IF(ARG.GT.1.0) ARG=1.0
77700
                THETA(I, JJ) = ARSIN(ARG)
77800
                GO TO 42
                THETA(I, JJ) = ARSIN(ARG)
77900
                THETA(I,JJ)=0.5*(THETA(I,JJ)+OLDANG(I,JJ))
78000
                SUMANG=SUMANG+(ABS(THETA(I,JJ)-OLDANG(I,JJ)))
78100
78200
                CONTINUE
78300
          60
                CONTINUE
         C*MUST EJECT IF WE HAVE REACHED AN ACCEPTABLE ITERATION ERROR
78400
78500
         C*IF THE SUM OF THE ABSOLUTE VALUE OF ANGLE CHANGES DURING AN ITERATION
78600
                  AVERAGES LESS THAN 0.02 DEGREES PER GRID ITS CLOSE ENOUGH.
                IF(SUMANG.LT.(NPTS*0.0035))
78700
                                                GO TO 215
78800
                IF(NITER.GE.50)
                                   GO TO 215
78900
               CONTINUE
79000
                WRITE(6,803)
79100
          215 CONTINUE
         C*ITERATION LOOP FOR THE WAVE HEIGHT.
79200
79300
                DO 501 NITER=1, NITERS
79400
                SUMH=0.0
79500
                DO 510 II-IBEGIN, IEND
         C*MUST HAVE IT SET UP SO THAT THE KNOWN BOUNDARIES HTS. AREN'T RECOMP
79600
79700
                IF(ISTART.EQ.IBEGIN) I=II
79800
                IF(ISTART.EQ.IBEGIN .AND. I.EQ.IBEGIN) GO TO 510
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79900
                 IF(ISTART.EQ.IEND)
                                         I=IEND-II+IBEGIN
80000
                 IF(ISTART.EQ.IEND
                                       .AND. I.EQ.IEND)
                                                             GO TO 510
80100
          C*ADX EQUALS ACTUAL DELTA X ACROSS SPACE STEP.
80200
          C*ONLY ON BOUNDARIES WHERE FORWARD OR BACKWARD DIFFERENCING.
80300
                 IF(I.NE.IBEGIN)
                                     GO TO 503
80400
                 ADX=DX
80500
                 IP=I+1
                 IM=I
80600
                 GO TO 505
80700
80800
           503
                   IF(I.NE.IEND)
                                     GO TO 504
80900
                 ADX=DX
81000
                 IP=I
                 IM=I-1
81100
81200
                 GO TO 505
           504
                  ADX = 2.0 + DX
81300
81400
                 IP=I+1
81500
                 IM=I-1
81600
           505
                   CONTINUE
81700
                 DO 502 J=JBEGIN(I), JEND(I)-1
81800
                 JJ=JEND(I)-1-J+JBEGIN(I)
                 HOLD(I,JJ)=H(I,JJ)
81900
82000
                 YBAR=0.25*(Y(I,JJ)+2.0*Y(I,JJ+1)+Y(I,JJ+2))
                 CALL LOC(IM, JU, JOIM, JSIM, YBAR, IMINUS)
CALL LOC(IP, JU, JOIP, JSIP, YBAR, IPLUS)
PART13=(H(I, JU+1)**2.)*CG(I, JU+1)*CDS(THETA(I, JU+1))
82100
82200
82300
82400
                 PART2=DY(I,JJ)/ADX
                                  GO TO 311
82500
                 IF(JSIM.NE.O)
82600
                 PART4B=0.0
82700
                 GO TO 312
82800
            311 TOPIMH=(H(IM, JOIM-1)**2.)*CG(IM, JOIM-1)*(SIN(THETA(IM, JOIM-1)))
                 BOTIMH=(H(IM, JSIM) ** 2.) *CG(IM, JSIM) *SIN(THETA(IM, JSIM))
82900
                 TOTALB=0.5*(Y(IM, JOIM)+Y(IM, JOIM-1))-0.5*(Y(IM, JSIM+1)+Y(IM, JSIM))
83000
                 DUMB=0.5*(Y(IM, JOIM)+Y(IM, JOIM-1))~YBAR
83100
                 PART48=((TOTALB-DUMB)+(TOPIMH-BOTIMH)/TOTALB)+BOTIMH
83200
            312 IF(JSIP.NE.O)
                                   GO TO 313
83300
83400
                 PART4A=0 0
83500
                 GO TO 314
83600
            313 TOPIPH=(H(IP, JOIP-1)**2.)*CG(IP, JOIP-1)*SIN(THETA(IP, JOIP-1))
                 BOTIPH=(H(IP, USIP)**2 )*CG(IP, USIP)*SIN(THETA(IP, USIP))
83700
                 TOTALA=0.5*(Y(IP, JOIP)+Y(IP, JOIP-1))-0.5*(Y(IP, JSIP+1)+Y(IP, JSIP))
83800
                 DUMA=0.5*(Y(IP, JOIP)+Y(IP, JOIP-1))~YBAR
83900
84000
                 PART4A=((TOTALA-DUMA)*(TOPIPH-BOTIPH)/TOTALA)+BOTIPH
84100
            314 PART4=PART4A-PART4B
                 YBARP=0.25*(Y(I,JJ+1)+2.+Y(I,JJ+2)+Y(I,JJ+3))
CALL LOC(IM,JJ+1,JPOIM,JPSIM,YBARP,IMINUS)
84200
84300
                 CALL LOC(IP.JU+1, JPOIP, JPSIP, YBARP, IPLUS)
84400
84500
                 IF(JPSIM.NE.O) GO TO 315
84600
                 PART 12=0 0
84700
                 GO TO 316
84800
            315 TOPMH=(H(IM, JPOIM-1)++2)+CG(IM, JPOIM-1)+COS(THETA(IM, JPOIM-1))
                 BOTMH=(H(IM, JPSIM) ++2) +CG(IM, JPSIM) +COS(THETA(IM, JPSIM))
84900
                 TOTB = 5*(Y(IM, JPOIM) + Y(IM, JPOIM - 1)) - .5*(Y(IM, JPSIM + 1) + Y(IM, JPSIM))
85000
85100
                 DUMPB=0.5*(Y(IM.JPOIM)+Y(IM.JPOIM-1))-YBARP
85200
                 PART 12=((TOTB-DUMPB)+(TOPMH-BOTMH)/TOTB)+BOTMH
            316 IF(UPSIP.NE.O)
                                    GD TD 317
85300
85400
                 PART11=0 0
85500
                 GO TO 318
            317 TOPPH=(H(IP, JPOIP-1)**2)*CG(IP, JPOIP-1)*COS(THETA(IP, JPOIP-1))
85600
                 BOTPH=(H(IP, JPSIP)**2)*CG(IP, JPSIP)*COS(THETA(IP, JPSIP))
85700
85800
                 TOTA = .5*(Y(IP, JPOIP) + Y(IP, JPOIP - 1)) - .5*(Y(IP, JPSIP + 1) + Y(IP, JPSIP))
85900
                 DUMPA=0.5*(Y(IP, JPOIP)+Y(IP, JPOIP-1))-YBARP
                 PART 11=((TOTA-DUMPA)*(TOPPH-BOTPH)/TOTA)+BOTPH
86000
            318 PART 1H=TAU*PART 12+(1.-2.*TAU)*PART 13+TAU*PART 11
IF(JPSIM_EQ_0)PART 1H=(1.-TAU)*PART 13+TAU*PART 11
86100
86200
                 IF(JPSIP.EQ.O)PART1H=TAU*PART12+(1.-TAU)*PART13
86300
                 ARG=((PART1H+PART2*PART4)/(CG(I,JJ)*COS(THETA(I,JJ))))
86400
86500
          C*IF THERE IS TO BE AN INVALID SQRT, USE LINEAR SHOALING.
86600
                 IF(ARG.GE.O.)
                                   GO TO 44
86700
                 ARG=(CG(I, JJ+1)*CDS(THETA(I, JJ+1)))/(CG(I, JJ)*CDS(THETA(I, JJ)))
86800
                 IF(ARG.LT.O.O)
                                    ARG=0.0
86900
                 H(I,JJ)=H(I,JJ+1)+SQRT(ARG)
                 GO TO 45
87000
```

```
87100
                H(I, JJ) = SQRT(ARG)
87200
                H(I,JJ)=0.5*(H(I,JJ)+HOLD(I,JJ))
                HNONBR(JJ)=H(I,JJ)
87300
87400
          C*IBREAK(I)=JJ, THEREFORE JJ WILL BE LEEWARD SIDE OF GRID AT INIT BREAK
                IF(HB(I,JJ),LT,H(I,JJ),AND,HB(I,JJ+1),GE,HNONBR(JJ+1))
87500
87600
                       IBREAK(I)=JJ
87700
                IF(HB(I,JJ).LT.H(I,JJ))
                                           H(I,JJ)=HB(I,JJ)
87800
                SUMH=SUMH+ABS(H(I,JJ)-HOLD(I,JJ))
87900
                CONTINUE
88000
            510 CONTINUE
88100
                 IBREAK(IEND)=IBREAK(IEND-1)
                IBREAK(IBEGIN) = IBREAK(IBEGIN+1)
88200
                IF(SUMH.LT.(NPTS+0.01))
88300
                                            GO TO 507
                IF(NITER.GE.50) GD TD 507
88400
88500
           501
                CONTINUE
88600
                WRITE(6,803)
88700
           507
                CONTINUE
88800
                FORMAT(2X,4(F15.5),///)
           802
88900
           803
                FORMAT(2X, "AFTER NITERS ITERATIONS, CONVERGENCE WAS NOT REACHED")
                FORMAT(2X, "THE WAVE HT. ROUTINE CONVERGED IN, NITER= ",15,//)
FORMAT(2X, "THIS IS MY CHECKING WRITE STATEMENT")
89000
           804
89100
           805
                 FORMAT(2X, "THE WAVE ANGLE ROUTINE CONVERGED IN, NITER= ",15,//)
89200
           806
89300
                RETURN
89400
                END
89500
89600
                SUBROUTINE DIFF(RHOND, THETAO, ANGLE, AMP)
89700
          C****DIFFRACTION ABOUT SEMI INFINITE BREAKWATER (PENNEY-PRICE)
89800
                PI=3 14159265
89900
                ABSS=SIN(O.5*(ANGLE-THETAD))
                ABSP=SIN(O.5*(ANGLE+THETAO))
90000
                ABC=COS(ANGLE-THETAO)
90100
                ABC1=COS(ANGLE+THETAO)
90200
90300
                XX=RHOND * ABC
90400
                XXC=COS(XX)
90500
                 XXS=SIN(XX)
90600
                 XX1=RHOND*ABC1
90700
                 XXC1=COS(XX1)
90800
                XXS1=SIN(XX1)
90900
                AL=SQRT(RHOND/PI)
                SIG=2.0*AL*ABSS
91000
                SIGP=-2.0*AL*ABSP
91100
                CALL FRES(SIG, C, S, FR, FI)
91200
                CALL FRES(SIGP,CP,SP,FRP,FIP)
SUM1=XXC*FR+XXS*FI+XXC1*FRP+XXS1*FIP
91300
91400
91500
                 SUM2=XXC*FI-XXS*FR+XXC1*FIP-XXS1*FRP
                 AMP=SQRT(SUM1**2+SUM2**2)
91600
91700
                RETURN
91800
                END
91900
         SUBROUTINE FRES(A,C,S,FR,FI)

C*FRESNEL INTEGRAL SUBROUTINE****AFTER ABROMOWITZ AND STEGUN.
Z=ABS(A)
92000
92100
92200
92300
                P02=1.5707963
                FZ=(1.0+0.926+Z)/(2.0+1.792+Z+3.104+Z+Z)
92400
92500
                GZ=1.0/(2.0+4.142*Z+3.492*Z*Z+6.670*Z*Z*Z)
92600
                 XX=P02*Z*Z
                cz=cos(xx)
92700
                 SZ=SIN(XX)
92800
92900
                 C=O.5-GZ*CZ+FZ*SZ
93000
                 S=O 5-FZ*CZ-GZ*SZ
93100
                 IF(A.GT.O.O) GO TO 50
93200
                C = -C
93300
                 S = - S
93400
            50 FR=0.5*(1.0+C+S)
93500
                 FI=-0.5*(S-C)
93600
                 RETURN
93700
                END
93800
93900
                 SUBROUTINE PREDIF
94000
                 COMMON/A/ C(60,20), RK(60,20), Y(60,20), DEEP(60,20), ALPHAS(60,20)
                 COMMON/AA/YZERO(60)
94100
94200
                 COMMON/B/ THETA(60,20),QXTOT(60), OLDANG(60,20), DY(60,20)
94300
                 COMMON/C/ H(60,20),CG(60,20),HOLD(60,20),HB(60,20),YB(60)
```

```
COMMON/N USED/JUSE.T.CO.CGEN.CGGEN.ANGGEN.DX.BERM.THETAD(10).MMAX
94400
                 COMMON/D/SIGMA, G. ELO, UMAX, IMAX, PI, TWOPI, PIO2, HGEN, IJET(10), SJETTY
94500
94600
                 COMMON/G/IBREAK(60), HNDNBR(20)
                 DIMENSION J1(60), J2(60), J1REF(60), J3REF(60)
94700
          C+THIS SUB CALCS WHERE DIFFRACTION GOVERNS AND WHERE REFRACT GOVERNS
94800
          C*IT WILL CALL REFRAC FOR OFFSHORE AREA(OFF TIP OF STRUCTURE)
94900
          C*THEN IT WILL DO THE SHADOW ZONE USING DIFF(IF THETAD .NE.O.O)
95000
          C* IT WILL THEN FINISH THE OTHERS USING REFRAC AGAIN.
95100
          C*LET'S ZERO-OUT THE DIMENSIONED ARRAYS
95200
                DO 1000 I=1, IMAX+2
95300
95400
                 J1(I)=0 0
                 J2(I)=0.0
95500
                 J1REF(I)=0.0
95600
95700
           1000 J3REF(I)=0.0
95800
          C+NOW, LETS FIND C,CG,RK,HB, AND WVNUM
95900
                 DO 202 I=1, IMAX
                 DO 202 J=1, JMAX+2
96000
                 DEPTH=DEEP(I.J)
96 100
96200
                 CALL WVNUM(DEPTH, T, DUMK)
96300
                 RK(I J)=DUMK
96400
                 C(I.J)=CO*TANH(RK(I,J)*DEEP(I,J))
                 EN=0.5*(1.0+((2.*RK(I,J)*DEEP(I,J))/SINH(2.*RK(I,J)*DEEP(I,J))))
96500
                 CG(I,J)=EN*C(I,J)
96600
                 HB(I,J)=0.78*DEEP(I,J)
96700
                CONTINUE
96800
           202
          C.WILL ATTRIB AN EQUAL REACH TO EACH SIDE OF EACH M-GROIN
96900
                 DO 200 M=1, MMAX
97000
                 IDUML = 1
97100
                 IF(M.NE.1) IDUML=(IJET(M)+IJET(M~1))/2
97200
97300
                 IDUMR = IMAX
                 IF(M.NE.MMAX) IDUMR=(IJET(M)+IJET(M+1))/2
97400
97500
                 NPTS=0
                 DO 1 I = IDUML , IDUMR
97600
                 DO 2 J=1,JMAX
97700
                 IF(Y(I,J).LT.SJETTY)
                                          GD TD 14
97800
                 J1(1)=J
97900
                 J2(1)=JMAX
98000
                 GO TO 15
98100
                CONTINUE
98200
                CONTINUE
98300
98400
                CONTINUE
          C+IF NO STRUCT IS PRESENT(SUETTY=0.0), DO REFRAC THRUOUT GRID SYSTEM IF(SUETTY EQ.0.0) J1(I)=1
98500
98600
98700
                CONTINUE
               DO 16 I=IDUML, IDUMR
'REFRAC' STARTS ON THE NEXT TO LAST J-CONTOUR, NOT THE LAST!
98800
 98900
                 DO 16 J=J1(I),J2(I)-1
 99000
 99100
             16 NPTS=NPTS+1
          C.WILL NOW DO THE REFRACT FOR THE REGION 1 AREA
99200
          C*ISTART REPRESENTS THE DIRECTION THE SWEEPS WILL BEGIN FROM C*WILL USE DUMMY IMAX.IJET.IJET+1 IN CALL STTS SO IBEGIN.IEND. AND
 99300
 99400
          C***ISTART
                       WON'T CHANGE THEM MUST RESET AFTER EACH CALL REFRAC
 99500
 99600
                 IMAXT=IDUMR
 99700
                 IJETT=IJET(M)
99800
                 IJETP1=IJET(M)+1
 99900
                 IDUM: L = IDUM:
                 IF (ANGGEN.GE O.O) CALL REFRAC (U1, U2, NPTS, IDUMLL, IMAXT, IDUMLL, M)
100000
100100
                 IF(ANGGEN.LT O.O) CALL REFRAC(U1,U2,NPTS,IDUMLL,IMAXT,IMAXT,M)
100200
                 IMAXT = IDUMR
100300
                 IJETT=IJET(M)
                 IJETP1=IJET(M)+1
100400
100500
                 IDUMLL = IDUML
100600
                 JDUMN=J1(IJET(M))
100700
                 JDUMS=J1(IJET(M)+1)
                 XDISTN=(IJET(M)-1 0)*DX+DX/2
100800
                 ELTIP=T*O.5*(C(IJET(M), JDUMN)+C(IJET(M)+1, JDUMS))
100900
          CONDW MUST CHECK THE ANGLE AT THE STRUCTURE'S TIP TO SEE WHERE SHAD ZONE
101000
          C*IF NO STRUCT PRESENT (SUETTY=0.0), FUTHER REFRAC/DIFF UNNECESSARY
101100
                 IF(SUETTY.EQ.O.O) GO TO 13
101200
                 THETAO(M)=0 5*(THETA(IJET(M), JDUMN)+THETA(IJET(M)+1, JDUMS))
101300
                 HINC=0.5*(H(IJET(M),JDUMN)+H(IJET(M)+1,JDUMS))
101400
101500
                 IF(THETAD(M))10,11,12
          C+THIS SECTION HANDLES REFRAC/DIFF IF THETAD<O O
101600
```

```
101700
             10 CONTINUE
101800
          C*FIRST ALL OF REGION 2 WILL GET REFRACTED.
                 NPTS=0
101900
                 DO 100 I=IJET(M)+1, IDUMR
102000
102100
                 J2(I)=J1(I)
102200
             100 J1(I)=1
102300
                 DO 101 I=IJET(M)+1, IDUMR
102400
                 DO 101 J=J1(I),J2(I)-1
102500
             101 NPTS=NPTS+1
                 IMAXT = IDUMR
102600
                 IDUMLL = IDUML
102700
102800
                 IJETT=IJET(M)
102900
                 IJETP1=IJET(M)+1
                 CALL REFRAC(J1, J2, NPTS, IJETP1, IMAXT, IMAXT, M)
103000
103100
                 TMAXT=TDUMR
103200
                 IJETT=IJET(M)
                 IJETP1=IJET(M)+1
103300
103400
                 IDUMLL = IDUML
103500
          C.NOW MUST DO REGION 3 OF NEG THETAO CASE-SHADOW ZONE
103600
                 DO 102 I=IDUML, IJET(M)
103700
                 J2(I)=Jt(I)
103800
             102 J1(I)=1
                 DO 103 I = IDUML . IJET(M)
103900
104000
                 J1REF(I)=1
                 DO 104 J=J1(I),J2(I)+1
104100
                 XCOOR=(I-1.0)*DX
104200
                 YCOOR=0.5*(Y(I,J)+Y(I,J+1))
104300
                 ANGLE = ATAN((XDISTN-XCOOR)/(SJETTY-YCOOR))
104400
104500
                 IF (YCOOR . GT . SJETTY)
                                         ANGLE=PI+ANGLE
          C*IF MOST SHOREWARD PT OUT OF SHAD ZONE, SO ARE THE OTHERS FOR THAT I IF(ABS(ANGLE) GT ABS(THETAO(M))) GO TO 105
104600
104700
                 RAD=SQRT((XDISTN-XCOOR)**2+(SUETTY-YCOOR)**2)
104800
                 RHOND = RAD + TWOPI / ELTIP
104900
           C*DIFFRACTION TREATS THE POS THETAD CASE.
105000
105100
                 THE = ABS(THETAO(M))
105200
                 CALL DIFF(RHOND, THE, ANGLE, AMP)
105300
                 H(I,J)=AMP*HINC
105400
                 ANGRAD = - ANGLE
          C*WILL NOW REFRACT DIFF WAVES IN THE SHAD ZONE USING SNELL'S.
105500
105600
                 CTIP=ELTIP/T
105700
                  ALPHAS(I, J) = ATAN((0.5*(Y(I+1, J)+Y(I+1, J+1))-0.5*
105800
                   (Y(I-1,J)+Y(I-1,J+1)))/(2.*DX))
105900
                 IF(I.EQ.IJET(M))ALPHAS(I,J)=ATAN((0.5*(Y(I,J)+Y(I,J+1))-0.5*(Y(I-1
106000
                     (U)+Y(I-1,U+1))/DX)
                 DALPHA = ANGRAD - ALPHAS (1, J)
106 100
106200
                 THETA(I, J) = ARSIN((C(I, J)/CTIP) * SIN(DALPHA))
                 THETA(I,J)=THETA(I,J)+ALPHAS(I,J)
106300
106400
          C.MUST CHECK TO SEE IF WAVE WOULD HAVE BROKEN.
106500
                 IF(HB(I,J) LE H(I,J).AND.HB(I,J+1).GT.H(I,J+1))IBREAK(I)=J
106600
                 IF(HB(I,J).LT.H(I,J))
                                           H(I,J)=HB(I,J)
106700
             104 CONTINUE
                 GO TO 103
106800
             iO5 J1REF(I)≃J
106900
10 1000
             103 CONTINUE
107100
          C*NOW MUST DO REFRACTION FOR REGION 4
107200
                 NPTS=0
107300
                 DO 106 I = IDUML, IJET(M)
107400
                 DO 106 J=J1REF(I).J2(I)-1
107500
             106 NPTS=NPTS+1
107600
                 IDUML1 = IDUML
107700
                 IMAXT = IDUMR
107800
                 IJETT = IJET(M)
107900
                 IJETP1=[JET(M)++
108000
                 CALL REFRAC(J1REF, J2, NPTS, IDUMLL, IJETT, IDUMLL, M)
108 100
                 IDUMLI. = IDUML
108200
                 IMAXT = IDUMR
108300
                 IJETT=IJET(M)
108400
                 IJETP1=IJET(M)+1
108500
                 GO TO 13
          C. THIS HANDLES REFRAC/DIFF IF THETAC IS O.O.
108600
108700
          C*FOR THIS CASE, ONLY THREE REGIONS EXIST
108800
                CONTINUE
108900
                 NPTS=0
```

```
109000
                 DO 120 I=IDUML, IJET(M)
109 100
                 J2(I)=J1(I)
109200
             120 J1(I)=1
109300
                 DO 121 I = IDUML, IJET(M)
109400
                 DO 121 J=J1(I),J2(I) 1
109500
             121 NPTS=NPTS+1
                 IMAXT = IDUMR
109600
109700
                  IDUMLL = IDUML
109800
                  IJETT=IJET(M)
109900
                  IJETP1=IJET(M)+1
110000
                 CALL REFRAC(J1, J2, NPTS, IDUMLL, IJETT, IDUMLL, M)
110100
                  IMAXT = IDUMR
110200
                  IJETT=IJET(M)
110300
                  IJETP1=IJET(M)+1
110400
                  IDUMLL = IDUML
110500
                 DO 122 I=IJET(M)+1, IDUMR
110600
                  J2(I)=J1(I)
110700
             122 J1(I)=1
110800
                 NPTS=0
110900
                 DO 123 I=IJET(M)+1, IDUMR
                 DO 123 J=J1(I),J2(I)-1
111000
111100
             123 NPTS=NPTS+1
111200
                  TMAXT = TOUMR
                 IDUMLL=IDUML
IJETT=IJET(M)
111300
111500
                  IJETP1=IJET(M)+1
                  CALL REFRAC(J1, J2, NPTS, IJETP1, IMAXT, IMAXT, M)
111600
111700
                  IMAXT = IDUMR
                  IJETT=IJET(M)
111800
111900
                  IJETP1=IJET(M)+1
112000
                  IDUMLL = IDUML
112100
                  GO TO 13
112200
           C*THIS SECTION HANDLES REFRACT/DIFF IF THETAD>O.O
112300
             12 CONTINUE
112400
           C*FIRST, REGION 2- ALL REFRACTION.
112500
                 NPTS=0
112600
                 DO 110 I=IDUML, IJET(M)
112700
                 J2(I)=J1(I)
112800
             110 J1(I)=1
112900
                 DO 111 I=IDUML, IJET(M)
113000
                 DO 111 J=J1(I).J2(I)-1
113100
             111 NPTS=NPTS+1
                  IMAXT = IDUMP
113200
113300
                  IDUMLL = IDUML
113400
                  IJETT = IJET(M)
113500
                  IJETP1=IJET(M)+1
113600
                  CALL REFRAC(J1, J2, NPTS, IDUMLL, IJETT, IDUMLL, M)
113700
                  IMAXT = IDUMR
113800
                  IJETT=IJET(M)
113900
                  IJETP1=IJET(M)+1
114000
                  IDUMLL = IDUML
114100
           C*NOW WILL DO REGION 3 OF THE POS THETAD CASE.
114200
                 DO 112 I=IJET(M)+1, IDUMR
114300
                  J2(I)=J1(I)
114400
             112 J1(I)=1
114500
                 DO 113 I=IJET(M)+1, IDUMR
114600
                  J1REF(I)=1
114700
           C+WILL GO ONE PT. BEYOND J2(I) TO MAKE SURE OUTOF DIFF ZONE
114800
                 DO 114 J=J1(I),J2(I)+1
                  XCOOR = ( I - 1.0) *DX
114900
115000
                  YCOOR=0 5*(Y(I,J)+Y(I,J+1))
115100
                  ANGLE = ATAN((XCOOR - XDISTN)/(SJETTY YCOOR))
115200
                  IF(YCOOR.GT.SJETTY) ANGLE=PI+ANGLE
           C*IF LEAST J-VALUE IS OUT OF SHAD ZONE, SO ARE OTHER J'S (FOR EACH I)
IF(ANGLE.GT.ABS(THETAO(M))) GO TO 115
115300
115400
                  RAD=SQRT((XCOOR-XDISTN)**2+(SJETTY-YCOOR)**2)
115500
115600
                  RHOND=RAD+TWOPI/ELTIP
115700
                  THE = THE TAO(M)
115800
                 CALL DIFF(RHOND, THE, ANGLE, AMP)
115900
                  ANGRAD = ANGLE
116000
           C*WILL NOW REFRACT DIFFRACTED WAVES IN SHAD ZONE USING SNELL"S
116100
                 CTIP=ELTIP/T
116200
                  ALPHAS(I, J) = ATAN((0 5*(Y(I+1, J)+Y(I+1, J+1))-0.5*
```

```
116300
                   (Y(I-1,J)+Y([ 1,J+1)))/(2 *Dx))
116400
                 IF(I EQ IUET(M)+1)ALPHAS(I, \theta)=ATAN((0.5*(\tau(I+1, \theta)+\tau(I+1, \theta++)) \sigma =+
116500
                     (Y(I,J)+Y(I,J+1)))/DX)
                  DALPHA = ANGRAD - ALPHAS (I . J)
116600
116700
                  THETA(I, U) = ARSIN((C(I, U)/CTIP) + SIN(DALPHA) +
116800
                  THETA(I,J)=THETA(1,J)+ALPHAS(I,J)
116900
                  H(I,J)=HINC+AMP
117000
           C+MUST CHECK TO SEE IF WAVE WOULD HAVE BROKEN
117100
                  IF(HB(I,U) LE H(I,U) AND HB(I,U+1) GT HTI HTTBREAKTITET
117200
                  IF(HB(I,U).LT.H(I,U)) =
                                           H(I,J)≋HB(I,J)
117300
             114 CONTINUE
117400
                  GO TO 113
117500
                 JIREF(I)=J
             113 CONTINUE
117600
117700
           C*NOW MUST DO REFRAC FOR REGION 4
117800
                 NPTS=0
117900
                 DO 116 I=IJET(M)+1, IDUMR
118000
                 DO 116 J=J1REF(I), (2(I) 1
             116 NPTS=NPTS+1
118100
118200
                 IMAXT = IDUMR
118300
                 IDUMLL = IDUML
118400
                  IJETT=IJET(M)
118500
                 IJETP1=IJET(M)+1
118600
                 CALL REFRACEDIREF, J2, NETS I TEACH IMAKE MAKE MA
118700
                  IMAXT = IDUMR
118800
                  IJETT = IJET(M)
118900
                 IJETP1=IJET(M)+1
119000
                 IDUMLL = IDUML
119100
                 CONTINUE
119200
             200 CONTINUE
119300
                 RETURN
119400
                 END
119500
119600
                 SUBROUTINE LOCIIM, JU, JOIM, JSIM, YBAR, IDUM)
119700
                 COMMON/A/ C(60.20), RK(60.20), Y(60.20), DEEP(60.20), ALPHAS(60.20)
119800
                 COMMON/AA/YZERO(60)
119900
                 COMMON/B/ THETA(60.20), QXTOT(60), OLDANG(60,20), DY(60.20)
120000
                 COMMON/C/ H(60,20), CG(60,20), HOLD(60,20), HB(60,20), FB(60)
120100
                 COMMON/N USED/JUSE, T.CO. CGEN, CGGEN, ANGGEN, DX. BERM, THE TAO ( 10) MMA.
120200
                 COMMON/D/SIGMA, G. ELO, JMAX, IMAX, PI, TWOPI, PIO2, HGEN, IJET(10), S. ETT.
           C*SUBROUTINE LOC FINDS U-VALUES WHICH ARE GREATER AND LESS THAN .BAR
120300
120400
                 JOIM = 2
120500
                 AA=0.5*(Y(IM, JOIM)+Y(IM, JOIM-1))
120600
                 IF(AA.GT YBAR)
                                   GO TO 4
120700
                 JOIM=JOIM+1
120800
           C*THE FOLLOWING IS REQ'D SO THAT DY/DX50.5
           C*WILL DTERMINE K SIN THETA ON IM-LINE AT A DIST YBAR
120900
121000
           C*WILL CALL THIS POINT
                                      JUSE+1
121100
                 IF(UDIM LE.JUSE)
                                      GO TO 2
121200
                 JOIM=JUSE+1
121300
                 Y(IM, JOIM)=YBAR
121400
          C* DEPTH AT THIS POINT WILL BE COMP ASSUMING CONST BEACH SLOPE ON 1-1M
121500
                 DEL=.5*(Y(IM, JOIM-1)+Y(IM, JOIM-2))- 5*(Y(IM, JOIM-2)+F(IM, JOIM-2))
121600
                 BSLOPE=(DEEP(IM, JOIM-2)-DEEP(IM, JOIM-3))/DEL
121700
                 DEEP(IM, JOIM-1) = DEEP(IM, JOIM-2) + BSLOPE + (Y(IM, JOIM) Y(IM, JOIM +))
121800
                 DEPTH=DEEP(IM, JOIM-1)
121900
                 CALL WVNUM(DEPTH, T, DUMK)
122000
                 RK(IM, JOIM-1) = DUMK
122100
                 C(IM, JOIM-1) *CO*TANH(RK(IM, JOIM-1)*DEEP(IM, JOIM-1))
                 EN=0.5*(1 0+((2 0*RK(IM, JOIM-1)*DEEP(IM, JOIM-1))/SINH(
2.*RK(IM, JOIM-1)*DEEP(IM, JOIM-1))))
122200
122300
122400
                 CG(IM, JOIM-1)=C(IM, JOIM-1)*EN
122500
           C'WILL USE SNELL'S LAW TO DETERMINE THE WAVE ANGLE HERE
122600
           C*ANGLE OF CONTOUR WILL BE ASSUME TO BE THE SAME AS THE UMAX+1 CONTOUR
122700
                 IF (IDUM.EQ 1) ALPH=ATAN((Y(IM, JOIM-1) Y(IM 1, JOIM 1)) / Dx)
122800
                 IF (IDUM.EQ. -1) ALPH=ATA" ((Y(IM+1, JOIM 1)-Y(IM, JOIM 1)) The)
122900
                 DALPHA = ANGGEN-ALPH
                 THETA(IM, JOIM-1) = ARSIN((C(IM, JOIM 1)/CGEN) + SIN(DAIPHA))
123000
123100
                 THETA(IM, JOIM-1) = THETA(IM, JOIM-1)+ALPH
123200
                  JSIM=JMAX-1
                 AA=0.5*(Y(IM, USIM)+(Y(IM, USIM+1)))
123300
123400
                 IF(AA.LT.YBAR)
                                   GO TO 8
123500
                 JSIM=JSIM-1
```

```
C*IF USIM=O, THERE IS NO ADJ PT. SUB REFRAC CAN HANDLE IT
123600
                 IF(USIM.EQ.O) GO TO 8
GO TO 6
123700
123900
                 RETURN
124000
                 END
124100
124200
                 SUBROUTINE WVNUM(DEPTH, T, RK)
                 G=32 17
124300
                 EPS=0.001
124400
                 TWOPI = 6 283185307
124500
                 SIGMA=TWOPI/T
124600
                 RK=TWOPI/(T+SQRT(G+DEPTH))
124700
                 DO 100 IT=1,20
ARG=RK*DEPTH
124800
124900
                 EK=(G*RK*TANH(ARG))-(SIGMA**2)
125000
                 EKPR=G*(ARG*((SECH(ARG))**2)+TANH(ARG))
125100
                 RKNEW=RK-EK/EKPR
125200
                 IF(ABS(RKNEW-RK).LE.ABS(EPS+RKNEW))
                                                         GO TO 120
125300
125400
                 RK = RKNEW
                 CONTINUE
            100
125500
                 WRITE(6, 1000)
                                 IT, DEPTH, RK
125600
            1000 FORMAT(///, 10x, "ITERATION FOR K FAILED TO CONVERGE AFTER"

. 3x,13, "ITERATION", /, "OUTPUT" DEPTH, RK", 3x, 2F13 5)
125700
125800
125900
                 CALL FXIT
126000
            120 RK=RKNEW
                 IF(RK.GT.O.O)
                                   GC TD 140
126100
                                  DEPTH.RK
126200
                 WRITE(6, 1020)
            1020 FORMAT(///, 10x, " RK IS NEG",/." DUTPUT DEPTH, RK", 3x, 2F13 5)
126300
126400
                 CALL EXIT
            140
                RETURN
126500
                 END
126600
126700
                 SUBROUTINE SMOOTH(THETA, IMAX, JMAX, IJET, SUETTY, MMAX, Y)
126800
           C. THIS WILL SMOOTH THE WAVE ANGLE FIELD TO ACCT FOR DIFF(ARTIFICIALLY)
126900
                 DIMENSION TEMP(60,20), Y(60,20), THETA(60,20), IJET(10)
127000
           C*(MMAX+1) IS REQ D BECAUSE M-GROINS HAVE M+1 REACHES OF SHORELINE
127100
127200
                 DO 10 M=1, MMAX+1
                  IF(M.NE 1)
                               GO TO 3
127300
                 ILEFT=2
127400
                  IRIGHT = IJET(1)
127500
                 GO TO 5
127600
                 IF (M. NE MMAX+1)
                                     GD TD 4
127700
                  ILEFT=IJET(MMAX)+1
127800
127900
                  IRIGHT = IMAX - 1
128000
                  GO TO 5
128100
                 ILEFT=IJET(M-1)+1
                  IRIGHT = IJET (M)
128200
                 CONTINUE
128300
128400
                  DD 1 J=1, JMAX-1
128500
                  DO 1 I=ILEFT, IRIGHT
                  IF(I NE.ILEFT. AND I NE. IRIGHT)
                                                     GO TO 15
128600
           C*TO GET HERE. MUST BE ON BOUN OR ADJ TO A STRUCTURE
128700
                  IF(I.EQ.2.OR.I.EQ.IMAX-1)
                                               GO TO 15
128800
           C*TO GET HERE, ADJ TO A STRUCT AND CAN BE ILEFT OR IRIGHT
128900
                                          GO TO 15
                  IF(Y(I,J) GE.SJETTY)
129000
           C*IF HERE, WITHIN JETTY AND ADJ TO EITHER SIDE
129100
                  IF(I.EQ.ILEFT)TEMP(I,U)=0.5*(THETA(I,U)+THETA(I+1,U))
129200
                  IF(I.EQ.IRIGHT)TEMP(I,J)=0.5*(THETA(I,J)+THETA(I-1,J))
129300
129400
                  GO TO 1
                  TEMP(I.J)=0.25*THETA(I-1,J)+0.50*THETA(I.J)+0.25*THETA(I+1,J)
129500
                  CONTINUE
129600
 129700
              10
                  CONTINUE
                  DO 2 U=1, UMAX-1
 129800
                  DO 2 I=2. IMAX-1
 129900
                  THETA(I,J)=TEMP(I,J)
 130000
 130100
                  RETURN
 130200
                  FND
 130300
 130400
                  FUNCTION SECH(A)
 130500
                  SECH=1 O/COSH(A)
 130600
                  RETURN
 130700
                  END
 130800
           C****HERE IS WHERE THE IMSL ROUTINES MUST GO!
```

## APPENDIX C

## CONTOURS AND SCHEMATIC ILLUSTRATIONS

This appendix presents tables of the original contours at Oregon Inlet and the final contours for the eight numerical simulations (Tables C-1 to C-9). Also included are schematic illustrations of sediment volumes transported from the nourished region (Figs. C-1 to C-8).

Table C-1. Initial bathymetry for all simulations (prior to any sediment addition).

	190.000	000			221.623	2 2	123		279.443	143	143		412.028	)28 4	128		654.758	758 5	758		95c.726	726 6	726		7.414	114 7	114		2.228	22 <b>8</b> 8	228	
		000 230.000			201.623 221	26			259.443 279	e			392.028 412	4	28 442.028		634.758 654	99			930.726 950	ő	26 980,726		.414 1240	14 1280.4	14 1270.4		.228 1672	28 1712.3	28 1702.	
	200.000 170.000	00 220.000			23	2			<b>4</b>	ຕ			28	4	28 442.028		58	.8 684.75B		83	26	26 980.726	26 980.726	9:	1250.414 1220.414 1240.4	14 1270.4	4 1270.4	4	228 1652	28 1702.2	28 1702.2	Œ
		2			623 231,623	~			5	N		3 289.443	028 422.028	4	8 432.028		758 664.758	8 674.758	8 674.759	B 664.758	2	٠,	6 970.726	6 960,726	414 1250.	4 1250.41	4 1250.41	4 1250.41	228 1682.	8 1692.22	8 1692.22	R 1682, 228
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	000 220 000	3	170.000		23 251.623	7			43	N	259.443	289.443	28 442.028	402.028	392.028	422.028	58 684.758	644.758	634.758	664.758	26 980.726	940.726	930.726	960.726	14 1270.414 1270.414 1260.414 1250.414 1270.414	4 1210.414 1240.414 1240.414 1240.414 1230.414 1240.414 1260.414 1270.414 1280.414	4 1210.414 1210.414 1220.414 1220.414 1220.414 1230.414 1250.414 1270.414 1270.414	4 1250.414 1250.414 1250.414 1250.414 1250.414 1260.414 1250.414	228 1702.228 1702.228 1692.228 1682.228 1702.228 1682.228 1682.228 1632.228 1652.228	1662.228	1652.228	1682,278 1682,278 1682,278 1682 228 1682 228 1682 228
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	00 210.000	190.000	170.000	200.000	23 241.623	221,623	201.623	231.623	13 299.443	279.443	259.443	289.443	28 432.02B	412.028	392,028	422.02B	58 674.758	654.758	634.758	664.758	980.726 970.726	950.726	930.726	960,726	4 1260.4	1240.414	1220.414	1250.414	38 1692.23	1672.228	1652.228	1507 720
	0 220.000	190.000	160.000	200.000	3 251,623	221.623	191,623	23 .623	3 309,443	279.443	249.443	289,443	8 442.028	412.02B	382.028	422.02B	8 684.758	654.758	624.758	664.758	6 980.72	950,726	920.726	960,726	4 1270.41	1240.414	1210.414	1250.414	18 1702.22	1672.228	1642.228	1587 JOB
	0 220.000	160.000	160.000	200.000	3 251.623	191.623	191,623	231,623	3 309,443	249.443	249,443	289.443	8 442.028	382.028	382.028	422.028	8 684.758	624.758	624,758	ī	S 980.726	920.726	920,726	960,726	4 1270.41	1210.414	1210.414	1250.414	B 1702.22	1642.228	1642.228	1587 228
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	0 200,000	160.000	160.000	220.000	3 201,623	191.623	191.623	251.623	3 269,443	249.443	249.443	m	8 422.028 422	382.028	382.028	*	8 664,758	624,758	624.758	<u>~</u>		920.726	920.726	980,726	4 12:0.41	1210.414	1210.414	1270.414	8 1682.22	1642.228	1642.228	1707 228
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Table C-2. Final contours, case 2.a.

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Table C-3. Final contours, case 2.b.

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Final contours, case 2.cl.

Table C-5. Final contours, case 2.c2.

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Table C-6. Final contours, case 2.c3.

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Table C-7. Final contours, case 2.c4.

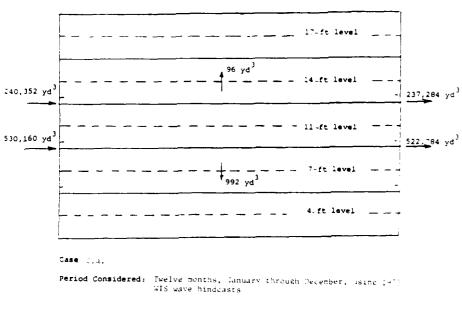
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Table C-8. Final contours, case 3 (17 weeks plus sediment addition).

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Table C-9. Final contours, case 4.

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## Sediment Budget Summary:

Amount of se	ediment add	ied:				None	
Amount of se	ediment tra	insported	shoreward fro	m nourished	region:	992 y	d 3
Amount of se	ediment tra	ansported	seaward from	nourished re	gian:	96 y	d <sup>3</sup>
Net amount	of sediment	transpor	ted alongshor	e trom nouri	shed region <b>a</b> c	,444 ye	d ³
letal amoun	t of sedime	ent transp	orted from no	ourished regi	on:	,356 y	a³

Figure C-1. Schematic illustration of sediment volumes transported from region, case 2.a.

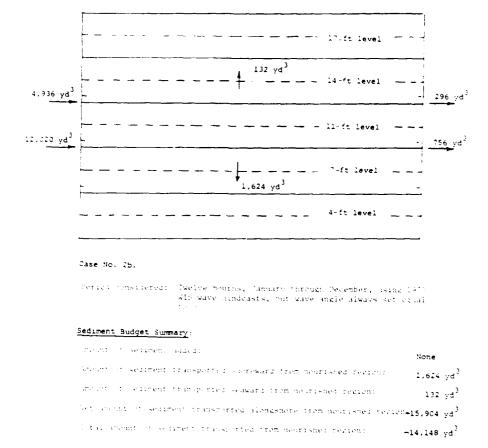


Figure C-2. Schematic illustration of sediment volumes transported from region, case 2.b.

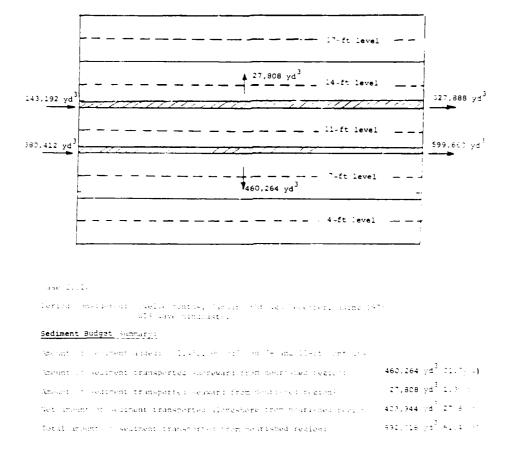
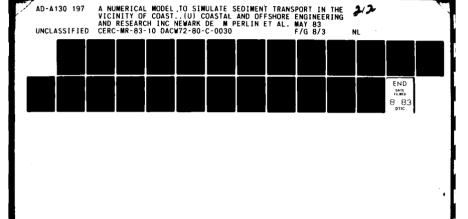
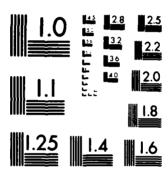
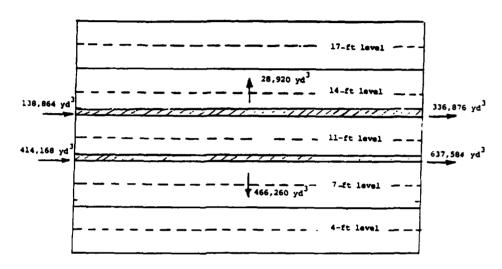


Figure C-3. Schematic illustration of sediment volumes transported from nourished region, case 2.c1.





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Case 1.c2.

Period considered: Twelve months, April through March, using 1975 WIS wave hindcasts.

### Sediment Budget Summary:

Amount of sediment added: 1,452,000 yd (on 7- and 11-ft contours)

Amount of sediment transported shoreward from nourished region: 466,260 yd (32.1pct)

Amount of sediment transported seaward from nourished region: 28,920 yd (2.0 pct)

Net amount of sediment transported alongshore from nourished region: 421,428 yd (29.0pct)

Total amount of sediment transported from nourished region: 916,608 yd (63.1pct)

Figure C-4. Schematic illustration of sediment volumes transported from nourished region, case 2.c2.

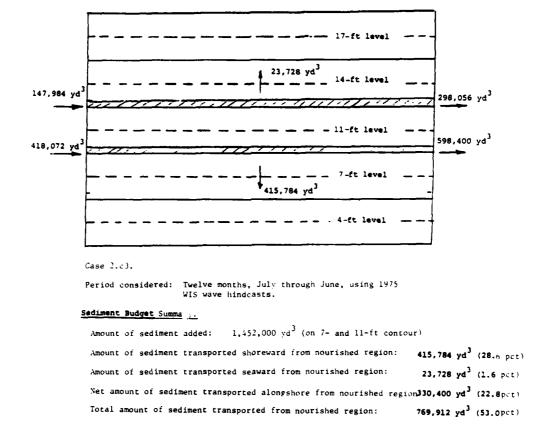
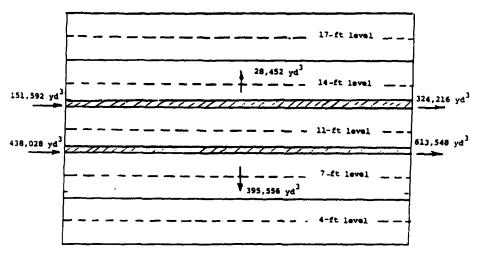


Figure C-5. Schematic illustration of sediment volumes transported from nourished region, case 2.c3.



Case 2.c4.

Period considered: Twelve months, October through September, using 1975 WIS wave hindcasts.

# Sediment Budget Summary:

Amount of sediment added: 1,452,000 yd3 (on 7- and 11-ft contours).

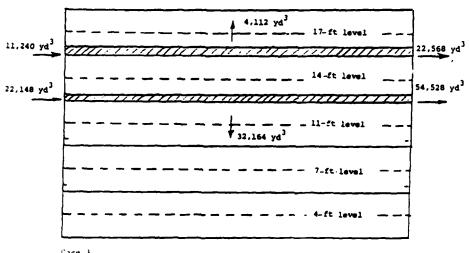
Amount of sediment transported shoreward form nourished region: 395,556 yd<sup>3</sup> (27.2 pct)

Amount of sediment transported seaward from nourished region: 28,452 yd<sup>3</sup> (2.0 pct)

Net amount of sediment transported alongshore from nourished region: 348,144 yd (24.0 pct)

Total amount of sediment transported from nourished region: 772,152 yd (53.2 pct)

Figure C-6. Schematic illustration of sediment volumes transported from nourished region, case 2.c4.

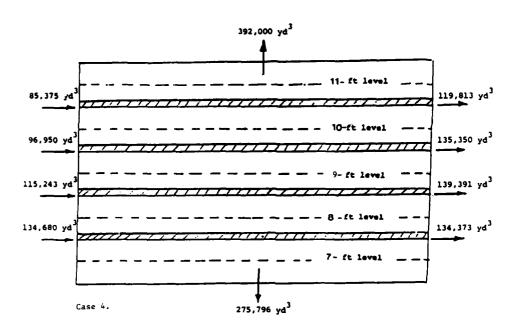


Period considered: Four months, January through April, using 1975 WIS wave hindcasts.

## Sediment Budget Summary:

Amount of sediment added 363,000  $yd^3$  (on 11- and 14-ft contours). Amount of sediment transported shoreward from nourished region: 32.164 yd (8.9pct) Amount of sediment transported seaward from nourished region: 4,112 yd<sup>3</sup> (1.1 pct) Net amount of sediment transported alongshore from nourished region: 43,708 yd (12.0 pct) Total amount of sediment transported from nourished region: 79,984 yd 3 (22.0 pct)

Figure C-7. Schematic illustration of sediment volumes transported from nourished region, case 3.



Period considered: Twelve months, January through December, using 1975 WIS wave hindcasts.

## Sediment Budget Summary:

Amount of sediment added: 1,452,000 yd (on 7-, 8-, 9-, and 10-ft contours).

Amount of sediment transported shoreward from nourished region: 275,796 yd (19.0pct)

Amount of sediment transported seaward from nourished region: 392,000 yd (27.0pct)

Net amount of sediment transported alongshore from nourished region: 96,679 yd (6.7pct)

Total amount of sediment transported from nourished region: 764,475 yd (52.6pct)

Figure C-8. Schematic illustration of sediment volumes transported from nourished region, case 4.

### APPENDIX D

# METHODOLOGY AND PROGRAM LISTING OF COMPUTER PROGRAM WHICH CONVERTS BATHYMETRIC DATA INTO MONOTONICALLY DECREASING DEPTH CONTOURS

In order to simulate prototype shorelines (and in this case to help verify the numerical model via Channel Islands Harbor data), the (x, y, z) data points must be transformed into a form suitable for use in the model (i.e., bars can not be present). First, the bathymetric data have to be put into a form with fixed longshore and offshore spacings (i.e.,  $\Delta x$  and  $\Delta y$  equal constants). This can be accomplished using one of the many available canned programs which do the interpolation. The problem is then one of finding the most suitable value of the constant, A, in the equation  $h = Ay^2/3$ . However, as is usually the case, the exact location of the shoreline (h = 0) is unknown. In addition, one requires the added constraint is required that the volumes of sediment (or conversely, the water above the profiles) balance. The problem is solved using LaGrange Multipliers and the Newton Raphson technique for non linear equations.

The equation to be minimized is

F(A,ydel<sub>1</sub>, ydel<sub>2</sub>, ... ydel<sub>IMAX</sub>) = 
$$\sum_{i=1}^{IMAX} \sum_{j=1}^{IMAX} (h_{meas_{i,j}} - h_{pred_{i,j}})^2$$
 (D-1)

where A is the scale parameter in the equilibrium beach profile, ydel, are the locations of the shoreline for the IMAX profiles,  $h_{\rm meas}$  is the interpolated depth from the survey, and  $h_{\rm pred}$  is the depth predicted by the equation

$$h_{\text{pred}_{i,j}} = A(y_{i,j} - ydel_i)^{2/3}$$
 (D-2)

The constraint equation is as follows

$$g(A,ydel_1, \dots ydel_{IMAX}) = V_{pred} = \sum_{i=1}^{IMAX} \Delta x \left\{ \int_{ydel_i}^{y} fA(y - ydel_i)^{2/3} dy \right\}$$

$$= \sum_{i=1}^{\text{IMAX}} \frac{3}{5} \Delta x A(y_f - ydel_i)^{5/3} = V_{\text{meas}}$$
 (D-3)

where  $V_{pred}$  is the predicted volume of water above the profile to the reference datum,  $V_{meas}$  is the measured volume computed from the survey,  $\Delta x$  is the longshore distance between onshore-offshore profiles, and  $y_f$  is the distance offshore to the last point on each of the measured profiles (it was a constant after the interpolation routine was used).

LaGrange Multipliers procedure says to form the quantify F\* as

• 
$$F^* = F - \lambda g$$
 (D-4)

take the total differential of equation (D-4)

$$dF^* = dF - \lambda dg = \left(\frac{dF}{dA} dA + \frac{dF}{d(ydel_1)} d(ydel_1) + \dots \frac{dF}{d(ydel_{IMAX})}\right) d(ydel_{IMAX})$$

$$- \lambda \left(\frac{dg}{dA} dA + \frac{dg}{d(ydel_1)} d(ydel_1) + \dots \frac{dg}{d(ydel_{IMAX})} d(ydel_{IMAX})\right)$$
(D-5)

Rearranging

$$0 = dF^* = \left(\frac{dF}{dA} - \lambda \frac{dg}{dA}\right) dA + \left(\frac{dF}{d(ydel_1)} - \lambda \frac{dg}{d(ydel_1)}\right) \qquad d(ydel_1) + \dots$$
(D-6)

It is clear that the terms in brackets in equation (D-6) must individually equal zero, however this leaves (IMAX + 2) unknown (udel i = to IMAX, A, and  $\lambda$ ) and only (IMAX = 1) Equations. The (IMAX + 2)th equation is taken as equation (D-3). The following system of equation then results:

$$0 = \frac{dF}{dA} - \lambda \frac{dg}{dA} = \sum_{i=1}^{IMAX} \sum_{j=1}^{JMAX} [-2(h_{meas_{i,j}} - A(y_{i,j} - ydel_{i})^{2/3})(y_{i,j} - ydel_{i})^{2/3}]$$

$$- \lambda \sum_{i=1}^{IMAX} \frac{3}{5} \Delta x (y_{f} - ydel_{i})^{5/3} \qquad (D-7-1)$$

$$0 = \frac{dF}{d(ydel_1)^{-1}} \lambda \frac{dg}{d(ydel_1)^{-1}} = \sum_{j=1}^{MAX} \left[ 2(h_{meas_{1,j}} - A(y_{1,j} - ydel_1)^{2/3}) + \lambda \Delta x A (y_f - ydel_1)^{2/3} \right]$$

$$(D-7-2)$$

$$\vdots$$

$$0 = \frac{dF}{d(ydel_{1MAX})^{-1}} \lambda \frac{dg}{d(ydel_{1MAX})^{-1}} = \sum_{j=1}^{MAX} \left[ 2(h_{meas_{1MAX},j} - A(y_{1MAX,j} - ydel_{1MAX})^{2/3} \right]$$

$$(D-7-(1MAX+1))$$

$$V_{meas} = \sum_{j=1}^{MAX} (3/5 \Delta x A(y_f - ydel_1)^{5/3})$$

$$(D-7-(1MAX+2))$$

Because Equations (D-7) is a system of nonlinear equations, it can not be written in matrix form as a [D] [x] = [E] system of equations (the brackets denote matrices). To solve the equations, a Newton-Raphson Iteration technique for nonlinear equations was used. This is done by differentiating each of the (IMAX + 2) equations with respect to each of the unknowns, the resulting equations are then linear in terms of  $\Delta a$ ,  $\Delta y del_1$ , . . .  $\Delta y del_1 MAX$ ,  $\Delta \lambda$ . The resulting matrix is inverted to obtain the  $\Delta (unknown)$  and the quantities are added to the original estimates to produce a better estimate. This iterative procedure is continued until the changes become acceptably small. The solution converged rapidly. Generally, the first row of the matrix to be inverted is  $(a_{11}$  represents the kth row and the lth column of the matrix).

$$a_{11} = \sum_{i=1}^{IMAX} \sum_{j=1}^{JMAX} 2(y_{i,j} - ydel_{i})^{4/3}$$

$$a_{1,2} = \sum_{j=1}^{JMAX} \frac{4}{3} (y_{1,j} - ydel_{1})^{-1/3} (h_{meas_{i,j}} - 2A(y_{1,j} - ydel_{1})^{2/3})$$

$$a_{1,IMAX+1} = \sum_{j=1}^{I} \frac{4}{3} (y_{IMAX,j} - ydel_{IMAX})^{-1/3} (h_{meas_{IMAX,j}} - 2A(y_{IMAX,j} - ydel_{IMAX})^{2/2})$$

$$a_{1,IMAX+2} = \sum_{i=1}^{IMAX} \sum_{j=1}^{3} \Delta x (y_{f} - ydel_{j})^{5/3}$$
 (D-8)

The second row of the matrix is as follows:

$$a_{2,1} = \sum_{j=1}^{JMAX} {4 \choose 3} h_{meas_{1,j}} (y_{1,j} - ydel_1)^{-1/3} - \frac{\alpha}{3} A(y_{1,j} - ydel_1)^{1/3}$$

$$+ \lambda \Delta x (y_f - ydel_1)^{2/3}$$

$$a_{2,2} = \sum_{j=1}^{JMAX} \left[ \frac{4}{9} A h_{meas_{i,j}} (y_{1,j} - ydel_{1})^{-4/3} + \frac{4}{9} A^{2} (y_{1,j} - ydel_{1})^{-2/3} \right]$$

$$- \lambda (2/3) \Delta x A (y_{f} - ydel_{1})^{-1/3}$$

$$a_{2,3} = 0$$

$$a_{2,1MAX+1} = 0$$

$$a_{2,1MAX+2} = \Delta x A (y_f - ydel_1)^{2/3}$$
(D-9)

The third row is simply these elements repeated except that the ones on the right-hand side of the first and last elements are changed to twos, and the a3 3 element is similar to the  $a_{2,2}$  except the ones on the right hand side become twos. The remaining column elements (i.e., those when the k=1) are zeroes. This process is continued to fill the array, except for the last row.

The (IMAX+2)th row is as follows:

$$a_{\text{IMAX}+2,1} = \frac{\text{IMAX}}{i=1} \frac{3}{5} \Delta x (y_f - y_{\text{del}_i})^{5/3}$$

$$a_{\text{IMAX}+2,2} = -\Delta x A (y_f - y_{\text{del}_1})^{2/3}$$

$$\vdots$$

$$a_{\text{IMAX}+2, \text{IMAX}+1} = -\Delta x A (Y_f - y_{\text{del}_{\text{IMAX}}})^{2/3}$$

$$a_{\text{IMAX}+2, \text{IMAX}+2} = 0$$

The E matrix in the [D] [x] = [E] system of equations is

$$E_{1} = -\frac{\sum_{i=1}^{IMAX} \int_{j=1}^{JMAX}}{\sum_{j=1}^{IMAX} \int_{j=1}^{J} \left(\frac{3}{5}\right) \Delta x \left(y_{f} - y d e l_{i}\right)^{2/3} \left(y_{i,j} - y d e l_{i}\right)^{2/3}}$$

$$-\lambda \sum_{i=1}^{IMAX} \left(\frac{3}{5}\right) \Delta x \left(y_{f} - y d e l_{i}\right)^{5/3}$$

$$E_{2} = -\left[\sum_{j=1}^{JMAX} 2(h_{meas}_{i,j} - A(y_{i,j} - y d e l_{i})^{2/3})((\frac{2}{3}) A (y_{i,j} - y d e l_{i})^{-1/3}) + \lambda \left(\Delta x A (y_{f} - y d e l_{i})^{2/3}\right)$$

$$E_{\text{IMAX}+1} = -\left[\sum_{j=1}^{JMAX} 2(h_{\text{meas}_{\text{IMAX},j}} - A(y_{\text{IMAX},j} - y\text{del}_{\text{IMAX}})^{2/3})\right]$$

$$+(\binom{2}{3}) A(y_{1,j} - y\text{del}_{1})^{-1/3}) + \lambda (\Delta x A(y_{f} - y\text{del}_{1})^{2/3})$$

$$E_{IMAX+2} = -\left[\sum_{j=1}^{IMAX} (\binom{3}{5}) \Delta x A(y_f - ydel_I)^{5/3}\right) - v_{meas}$$
 (D-11)

The [D] [x] = [E] system of equations was then solved, as explained previously, by solving the x column vector (which represents the changes in the unknowns,  $\Delta A$ ,  $\Delta y$ del<sub>1</sub> ...  $\Delta y$ del<sub>1</sub>MAX,  $\Delta \lambda$ ), adding these changes to the respective variables and iterating until a final solution is obtained.

The computer program which did these calculations for the Channel Island Harbor simulation follows. A user-supplied matrix inversion routine is required (Line 37,200).

```
100
         SRESET FREE
        C**********PROGRAM
200
                                   CIH/BVALUE 1
        FILE 5(KIND-PACK, TITLE-"CIH42076A", FILETYPE-7)
 300
 400
              6(KIND=REMOTE)
        FILE
        C+THIS PROGRAM USES THE INTERPOLATED PROFILES OF CIH.
500
        C*IT FINDS THE LOCATION OF THE SHORELINE, YDEL AND THE BEST C*FIT LEAST SQUARES "B" VALUE FOR H-BY**2/3
600
700
800
        COUSES LAGRANGE MULTIPLIERS TO CONSTRAIN THE VOLUMES(SO THEY ARE EQUAL)
        C+THEN IT USES NEWTON-RAPHSON ITER FOR NON-LIN EQS
900
1000
               DIMENSION X(40)
1100
               DIMENSION WKAREA(600), AMATRX(23, 23), BMATRX(23, 1)
1200
               DIMENSION Y(40,20),Z(40,20),YDEL(40),JBEGIN(40),YDELI(40)
               DIMENSION DYTWO(40,20), DYDNE(40,20), DYMTWO(40,20), DYMONE(40,20)
1300
               DIMENSION DYMFOR (40, 20), DYFOR (40, 20), YDONE (40, 20), YDMTWO (40, 20)
1400
               DIMENSION YDMONE(40,20), YETWO(40), YEONE(40), YEMONE(40)
1500
1600
               DIMENSION YEMTWO(40), YEMFOR(40), YEFIVE(40)
1700
               EXPON=2./3.
1800
               THIRD=0.33333333333333333
        C*FIRST READ IN THE PROFILES FROM DISKPACK.
1900
2000
               DO 1 I=1,34
2100
               DO 1 J=1,15
               READ(5, 100)
                              X(1),Y(1,J),Z(1,J)
2200
2300
          100 FORMAT(14X,F6.0,F5.0,F5.0)
2400
        C*NOW WE MUST GET A FIRST APPROX FOR YDEL
2500
        COWE WILL USE LINEAR INTERPOLATION TO DETERMINE IT.
2600
               IBEGIN= 1
2700
               IMAX=21
2800
               JMAX = 15
2900
        C+CHANGE PROFILE TO SPAN 1 TO IMAX(IF ALREADY DONE, WON'T HARM THINGS)
3000
               ITEMP1=1
3100
               ITEMP2=IMAX-IBEGIN+1
3200
               DO 777 1=1, ITEMP2
3300
3400
               K=K+1
3500
               DO 777 J=1, JMAX
               Y(I,J)=Y(IBEGIN+K.J)
3600
           777 Z(I,J)=Z(IBEGIN+K,J)
3700
3800
               IMAX=ITEMP2
3900
               DX = 100.00
4000
               DO 2 I=1, IMAX
               DO 3 J=1, JMAX
4100
4200
               IF(Z(I,J).GE.O.O)
                                     GO TO 3
         C*FIRST NEG POINT ON THE PROFILE IS SEAWARD OF Z=O.O
4300
4400
         C* WE MUST ALSO REMEMBER THIS LOCATION.
4500
         C+1F Z(1,1)<0., CHOOSE ARBITRARY PT, ROUTINE ITERATES TO SOLN.
               ZDUM= 1.0
4600
4700
                IF(J.NE.1)
                              ZDUM=Z(I,J-1)
4800
                YDUM=Y(I,J)-50.0
4900
                IF(J.NE.1)
                             YDUM=Y(I,J-1)
5000
               DELY=ZOUM/((ZOUM-Z(I,J))/(Y(I,J)-YOUM))
5100
                YDEL(I)=YDUM+DELY
5200
                JBEGIN(I)=J
5300
               GO TO 2
5400
            3 CONTINUE
5500
            2 CONTINUE
         C*THE VALUES FOR Z ARE NEG ON FILE, MUST NOW MAKE POS.
5600
         C*THE Z VALUES ARE ALSO *10.
5700
5800
               DO 35 I=1, IMAX
5900
               DO 35 J-JBEGIN(1). JMAX
         35 Z(I,J)=-Z(I,J)/10.0
C*MUST INITIALIZE "B" SO WILL MAKE A FIRST GUESS.
C*MUST ALSO GUESS LAMBDA (XLAMB)
6000
6100
6200
6300
               B=0.30
6400
                XLAMB = -2.0
6500
               DO 10 ITER=1,100
6600
         C*LET'S CALCULATE THE VOL OF WATER ABOVE THE PROFILE VMEAS.
         COLTS OUR CONSTRAINT, BUT SINCE YDEL IS NOT KNOWN, A PRIORI, IT WILL CHANGE
6700
6800
                VMEAS=0.0
6900
               DO 200 1-1, IMAX
7000
               DO 200 J=JBEGIN(1), JMAX
7100
                IF(J.NE.JBEGIN(I)) GO TO 201
```

```
7200
               VMEAS-VMEAS+DX+2(1,J)+(0.5+(Y(1,J)+Y(1,J+1))-YDEL(1))
7300
               GO TO 200
7400
           201 IF(J.EQ.JMAX)
                                GO TO 202
7500
                VMEAS=VMEAS+DX+0.5+(Y(I,J+1)-Y(I,J-1))+Z(I,J)
7600
               GO TO 200
7700
           202 VMEAS=VMEAS+DX*Z(I,J)*(Y(I,J)-0.5*(Y(I,J)+Y(I,J-1)))
7800
           200 CONTINUE
7900
         C*PRIOR TO EQS.COMPUTE AND STORE SEVERAL VALUES WE NEED OVER AND OVER
         C.BECAUSE COMPUTER CAN'T RAISE A NEG VALUE TO AN EXPONENT
8000
8100
         C.NUST PRESERVE THE SIGN.
8200
               DO 400 II=1, IMAX
8300
               DO 401 JJ=JBEGIN(II), JMAX
               ARG1=Y(II,JJ)-YDEL(II)
8400
8500
               DYSIGN-SIGN(1., ARG1)
8600
               DY=ABS(Y(II,JJ)-YDEL(II))
8700
               DYTWO(II, JJ)=DY ** EXPON
8800
                DYONE (II, JJ) = DYSIGN = DY . * THIRD
8900
               DYMTWO(II.JJ)=DY++(~EXPON)
9000
               DYMONE(II, JJ) = DYSIGN * DY * * ( - THIRD)
9100
               DYMFOR(II, JJ) = DY ++ (-2. *EXPON)
9200
               DYFOR(II, JJ) =DY**(2.*EXPON)
9300
           401 CONTINUE
9400
                ARG2=1400.-YDEL(II)
9500
               DSIGN=SIGN(1., ARG2)
9600
               DYE - ABS (ARG2)
9700
                YETWO(II) = DYE * * EXPON
9800
                YEONE(II) = DSIGN + DYE + + THIRD
9900
                YEMONE(II) = DSIGN * DYE * * ( - THIRD)
10000
                YEMTWO(II)=DYE++(-EXPON)
10100
                YEMFOR(II)=DYE++(-2.+EXPON)
                YEFIVE(II) =DSIGN *DYE ** (5. *THIRD)
10200
10300
           400 CONTINUE
10400
         C*LET'S INPUT THE FIRST ROW OF THE MATRIX, A
10500
                SUM 18 = 0.0
10600
                DO 300 II=1, IMAX
10700
                DO 300 JJ=JBEGIN(II), JMAX
10800
           300 SUM18=SUM18+2.*DYFOR(II,JJ)
                AMATRX(1,1)=SUM1B
10900
11000
                SUMLAM=0.0
11100
                DO 305 K=1, IMAX
11200
                SUM IK=0.0
                DO 306 JJ=JBEGIN(K),JMAX
11300
11400
           306 SUMIK=SUMIK+2. *EXPON*DYMONE(K, JJ)*(Z(K, JJ)-2. *B*
11500
                   DYTWO(K,JJ))
11600
                SUMLAM=SUMLAM-O.6+DX+YEFIVE(K)
           305 AMATRX(1,K+1)=SUM1K
11700
                AMATRX(1, IMAX+2) = SUMLAM
11800
11900
         C*NOW THE MIDDLE ROWS OF THE AMATRX.
                DO 410 LROW-2, IMAX+1
12000
12100
                SUM28-0.0
12200
                II=LROW-1
12300
                DO 415 JJ=JBEGIN(II), JMAX
            415 SUM2B=SUM2B+2. *EXPON*Z(II,JJ)*DYMONE(II,JJ)-4. *EXPON*
12400
12500
                   B.DYONE(II,JJ)
                AMATRX(LROW, 1) = SUM28+XLAM8 *DX *YETWO(II)
12600
12700
                DO 430 II=1, IMAX
                SUM2Y=0.0
12800
12900
                DO 425 JJ=JBEGIN(II), JMAX
            425 SUM2Y=SUM2Y+2.*EXPON*THIRD*B*Z(II,JJ)*DYMFOR(II,JJ)+THIRD*EXPON
13000
                   *2. *8*8*DYMTWO(11.JJ)
13100
                IF((11+1).EQ.LROW)
13200
                                       GO TO 431
13300
                AMATRX(LROW, II+1)=0.0
13400
                GO TO 430
13500
            431 AMATRX(LROW. II+1) "SUM2Y-XLAMB" EXPON"DX "B"YEMONE(II)
13600
            430 CONTINUE
            410 AMATRX(LROW, IMAX+2)=DX+8+YETWO(LROW-1)
13700
13800
         C-NOW THE LAST ROW OF THE MATRIX A
                SUMF8=0.0
13900
14000
                DO 450
                          11=1, IMAX
            450 SUMFB-SUMFB+O.6+DX+YEFIVE(II)
14100
14200
                AMATRX(IMAX+2,1)=SUMFB
```

```
DO 453 II=1,IMAX
453 MATAX(III,2+XAMI)+TAMA (II)
14300
14400
14500
                AMATRX(IMAX+2, IMAX+2)=0.0
         C.NOW MUST INPUT THE BMATRX.
14600
                SUMF 1A=0.0
14700
                SUMF 18=0.0
14800
14900
                DO 455
                         11=1, IMAX
                SUMF 1B=SUMF 1B+XLAMB+O.6+DX+YEFIVE(II)
15000
                          JJ=JBEGIN(II),JMAX
                DO 455
15100
           455 SUMF 1A=SUMF 1A-2. *(Z(II,JJ)-B*DYTWO(II,JJ))*DYTWO(II,JJ)
15200
                BMATRX(1,1)=-(SUMF1A-SUMF1B)
15300
                DO 460 II-1, IMAX
15400
15500
                SUMFII=0.0
                           JJ=JBEGIN(II), JMAX
                DO 462
15600
            462 SUMFII=SUMFII+2. *(Z(II,JJ)-B*DYTWO(II,JJ))*EXPON*B*DYMONE(II,JJ)
15700
                SUMFII=SUMFII+XLAMB*DX*B*YETWO(II)
15800
15900
            460 BMATRX(II+1,1)=-SUMFII
                SUMV=0.0
16000
                DO 465
                         II=1,IMAX
16100
            465 SUMV=SUMV+O.6*DX*B*YEFIVE(II)
BMATRX(IMAX+2,1)=-(SUMV-VMEAS)
16200
16300
          CONEXT LET'S CALL THE MATRIX INVERSION ROUTINE VIA IMSL
16400
                CALL LEQT2F(AMATRX, 1, 1MAX+2, 23, BMATRX, 3, WKAREA, IER)
16500
          C. THE SOLN IS RETURNED IN THE VECTOR BMATRX
16600
          C.FINALLY, WE MUST UPDATE THE X VECTOR IN AX=B.
16700
                B=B+BMATRX(1,1)
16800
                XLAMB=XLAMB+BMATRX(IMAX+2,1)
16900
17000
                00 470
                        II=1.IMAX
            470 YDEL(11)=YDEL(11)+BMATRX(11+1,1)
17100
          C*CHECK THE CRITERION FOR COMPLETION
17200
                SUMVEC=Q.O
17300
17400
                DO 475
                           II=1, IMAX
            475 SUMVEC=SUMVEC+ABS(BMATRX(II,1))
17500
                IF(SUMVEC.LT.(0.1*(IMAX+2))) GO TO 11
17600
                WRITE(6, */) B. ITER. (I, YDEL(I), I=1, IMAX), XLAMB
17700
            10 CONTINUE
17800
17900
          C*LET'S WRITE IT ALL OUT.
18000
                WRITE(6,*/) ITER.B.(I.YDEL(I), I=1, IMAX)
18100
                STOP
18200
                FNO
18300
```

## APPENDIX E

## USER DOCUMENTATION AND INPUT AND OUTPUT FOR PROGRAM VERIFICATION

The computer program presented in Appendix B was run on a Burroughs B-7700 computer. The B7000/B6000 series FORTRAN language was designed so several existing programs written in FORTRAN would be compatible with minimal changes. It was designed to be compatible with Fortram IV, H level and to contain ANSI X3.9-1966 Standard FORTRAN as a subset.

Line 37,200 of the coding (see App. B) requires a subroutine from the IMSL subroutine package, LEQTIB and its associated subroutines. If the user's computing center has access to this package of subroutine programs they need only bind them to the program (note: copyright laws prohibited the inclusion of the IMSL coding). If not, a substitute subroutine must be user supplied. It must facilitate the solution of a banded storage mode matrix.

The program input will be described here using a card deck set-up, however, the use of diskpack or magnetic tape input follows directly. Lines 3100, 4100, 5500, 5900, 6800, 7500, and 12,900 are read statements. The cards used for the simulation presented in this appendix are shown in Figure E-1. The first card contains the value of WDEPTH, the depth of water (in meters) to which the input wave conditions are to be transformed (a partial list of variables used in the program is presented beginning on page A-8 of Appendix A). The format statements are obviously in the program coding.

The second data input card is read by line 4100 where the variables SJETTY, BERM, SFACE, and DIAM are required (length of the structure, berm height, shore face slope, and sediment diameter, respectively).

Lines 5500 reads MMAX, the number of structures to be simulated (as set-up here, a maximum of 10 structures can be modeled, however, appropriate changes in array dimensions would allow additions (structures). Line 5900, which is in a "DO" loop reads the lesser I grid value adjacent to where the structure is desired. The number of structures, MMAX, determines the number of data cards required here; 3 structures require 3 cards with the 3 I grid locations (note, the present configuration of the refraction and diffraction subroutines requires evenly spaced structures, however this can be altered if necessary).

The parameter ADEAN, which represents the value of A in the equilibrium profile used is the next value input (line 6800). As mentioned previously, whenever possible a site-specific value should be used. The space-step and time-step (DX and DELT in the coding) are input next (line 7500).

The last input values are the wave data, HS, T, ALPWIS read by line 12,900. This statement is in a loop made by the unconditional GO TO statement (line 16,400) and the read statement. There is an action specifier included in the read statement to transfer the program to statement 1000, thereby stopping execution of the program once all the wave climate data have been used. The number of data cards required for this read statement is dictated by the length of the simulation and the time-step used.

The input file and output for program verification follow.

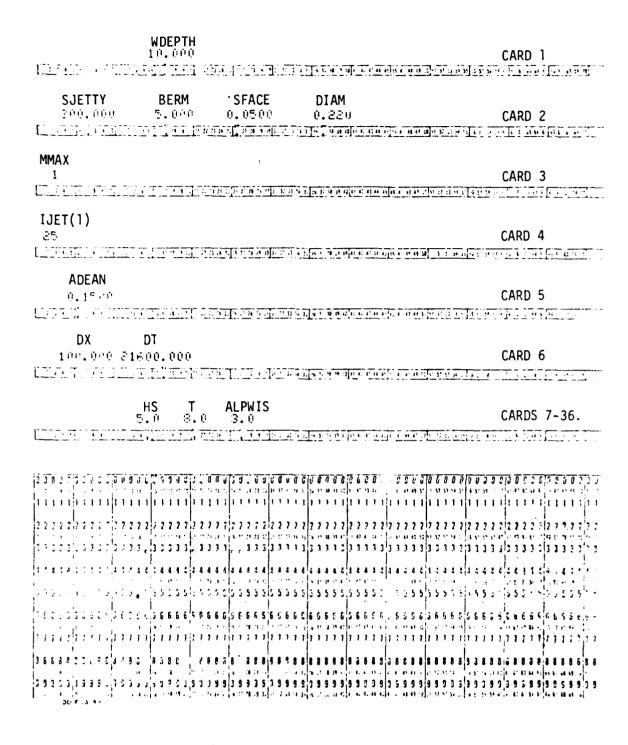


Figure E-1. Card deck input for program verification.

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0.220																															
0.0500		•	•	3.0	3.0		3.0	3.0	3.0	3.0	3.0		•	3.0	3.0	•	•	•	3.0		•			•					•	•	3.0
000	00	8	•	<b>8.</b> 0		8.0	8.0	9°°	<b>B</b> .0	8.0	8.0	8.0	8.0	8.0		•		•	8.0	9.0	•	•		•	8.0			•		•	8.0
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100 200 300	500 500 600	200	800	900	1000	1100	1200	1300	1400	1200	1600	1700	1800	1900	2000	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	<b>4</b>	20	3600

0 00 31 62 68 01 137 71 252 78 464 76 750 73 1050 41 1656 50 2674 85 0 00 31 62 68 01 137 71 252 78 464 76 760 73 1050 41 1656 50 2674 85 32 81 2**2** 28 TO WIND DEPTH AND THE WAVE, TO HE TRANSFORMED THE DEPTH OF WIND THE TOWN STREET TO WIND THE TOWN STREET AND DIAM 100 200 300 500 700 1100 1400 THE LENGTH OF THE STRUCTURE SUCTIVE 300 0x0
THE SEQUE OF THE BEACH ACC. SEACH
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THE NUMBER THE VALUE OF ABEAN
THE SPACE STEP. THE SECON THE SEACH STEP THE VALUE OF THE LUBISHINE SPACE STEP, DAY 100 000 THE TIME SIEP IN SECINGS, DELTY 216/3/ 000 INF BOURDARY Y VALUES, I'LL IMAX ARE AS FOLLOWS 9 MINITY TO. THE TOTAL ELAPSED RIMBER OF TIME-STEPS, MUNIVE THE DEPTHS BETWEEN CONTOURS ARE AS FOLLOWS MMIV:4. FAINTY-7. PASSAL V. 1. PAJNIV-3. PAINIV-5 MINITY - 6. HIMIN'B. PAININ-9. MINIV-2.

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Perlin, Marc  A numerical model to simulate sediment transport in the vicinity of coastal structures / by Marc Perlin and Robert G. Dean.—Fort Belvoir, Va.: U.S. Army, Corps of Engineers, Coastal Engineering Research Center, Springfield, Va.: available from NTIS, 1983.  [119] p.: iil.; 28 cm.—(Miscellaneous report / Coastal Engineering Research Center; no. 83-10).  Cover title.  "May 1983."  Report provides an implicit finite—difference, n-line numerical model which predicts sediment transport and the resulting bathymetry in the vicinity of coastal structures. The wave field transformation includes refraction, shoaling, and diffraction.  I. Numerical model. 2. Shorellane evolution. 3. Sediment transport. 4. Maye transformation. 5. Littoral barrier. 1. Title.  [U.S.). IV. Series: Miscellaneous report (Coastal Engineering Research Center (U.S.).  TC203  COASTAL WASHIER COASTAL COASTAL ENGINEERING MESSEARCH Center (U.S.).	A numerical model to simulate sediment transport in the vicinity of coastal structures / by Marc Perlin and Robert G. DeanFort Belvoir, Va.: U.S. Arry, Corps of Engineers, Coastal Engineering Research Center, Springfield, Va.: available from NTIS, 1983. [119] p.: 111.: 28 cm(Miscellaneous report / Coastal Engineering Research Center; no. 83-10).  Cover title. "May 1983."  Report provides an implicit finite-difference, n-line numerical model which predicts sediment transport and the resulting bathymetry in the vicinity of coastal structures. The wave field transformation includes refraction, shoaling, and diffraction.  I. Numerical model. 2. Shoreline evolution. 3. Sediment transport.  W. Maye transformation. 5. Littoral barrier. 1. Title.  II. Dean, Robert G. III. Coastal Engineering Research Center (U.S.): IV. Series: Miscellaneous report (Coastal Engineering Research Center (U.S.): TC203  TC203

